

Midterm : Monday 10/25

- Covers everything up to 10/18
(up to Lagrange multipliers)
- HW solutions will be available next week

Quiz 8, #5

Tangent plane to $f(x,y) = x^2y$
at $(1,2)$ is

$$z = 2 + 2xy(x-1) + x^2(y-2)$$

True or false ?

FALSE:

Equation of a plane is linear

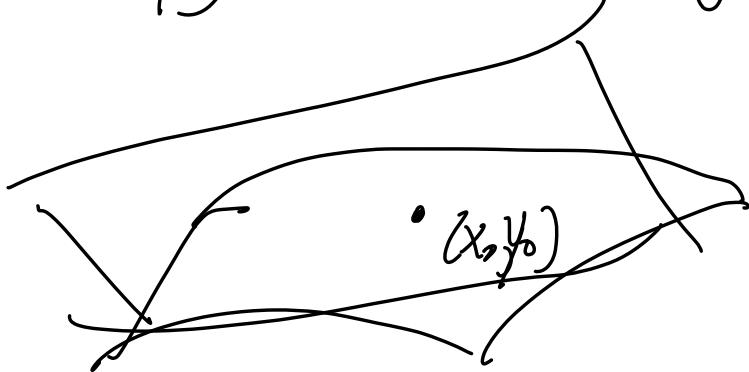
$$z = ax + by + c$$

where a, b, c are constants
(no x, y, z in them)

$$f(x,y) \approx f(x_0, y_0) + f_x(x_0, y_0)(x - x_0)$$

$$+ f_y(x_0, y_0)(y - y_0)$$

(x_0, y_0) is where the tangent plane is



In problem, $(x_0, y_0) = (1, 2)$

In formula, use $f_x(1, 2), f_y(1, 2)$
instead of $f_x(x, y), f_y(x, y)$

Tangent plane to contour

$$f(x, y, z) = \frac{x^2}{4} + \frac{y^2}{9} + \frac{z^2}{16}$$

Tangent plane to contour $f(x, y, z) = 3$
at $(2, 3, 4)$: $f(2, 3, 4) = 3$

Idea: Use implicit differentiation
Use differentials

$$f(x, y, z) = 3$$

means $\frac{x^2}{4} + \frac{y^2}{9} + \frac{z^2}{16} = 3$

$$\frac{x dx}{2} + \frac{2y dy}{9} + \frac{2z dz}{16} = 0$$

At $(2, 3, 4)$
 " " "
 x y z

$$dx + \frac{2}{3} dy + \frac{1}{8} dz = 0$$

$dx \approx x - 2$
$dy \approx y - 3$
$dz \approx z - 4$

Plug in

Get a linear equation that
approximates contour at $(2, 3)$

Linear equation defines tangent plane at
 $(2, 3)$

HW5 #5 $g=0 \Rightarrow dg=0$

$$dg = g_x dx + g_y dy + g_z dz = 0$$

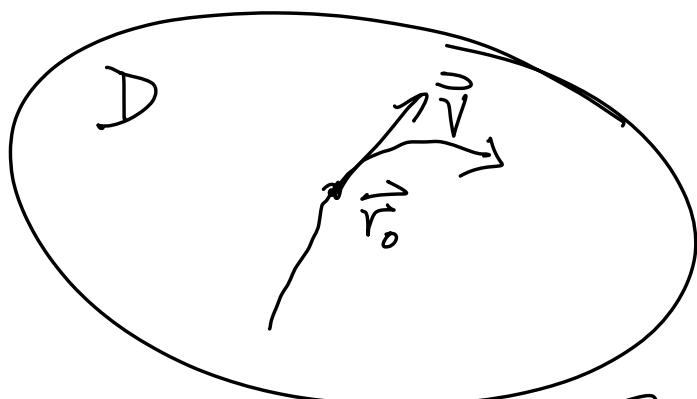
$$\begin{bmatrix} dx \\ dy \\ dz \end{bmatrix} \approx$$

Plug $(x, y, z) = (2, 1, 7)$ into

$$g_x, g_y, g_z$$

Use g_x, g_y, g_z only at $\underline{(2, 1, 7)}$

Directional derivative



$$f : D \rightarrow \mathbb{R}$$

Define $D_{\vec{v}} f(\vec{r}_0)$:

- 1) choose a parameterized curve $\vec{r}(t)$
where $\vec{r}(0) = \vec{r}_0$, $\vec{r}'(0) = \vec{v}$

$$D_{\vec{v}} f(\vec{r}_0) = \left. \frac{d}{dt} \right|_{t=0} f(\vec{r}(t))$$

function
of t only

$$2) D_{\vec{v}} f(\vec{r}_0) = \vec{v} \cdot \nabla f(\vec{r}_0)$$

where $\vec{\nabla}f(\vec{r}) = \langle f_x, f_y, f_z \rangle$
 which is a vector field
 called the gradient of f

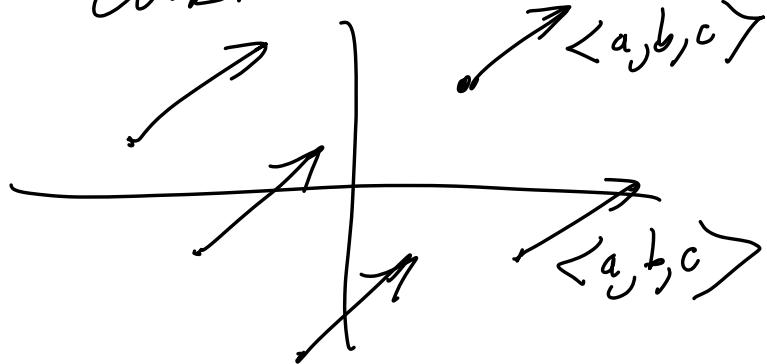
Examples

i) Linear function,
 $f(x, y, z) = ax + by + cz + d$

a, b, c constants

$$\vec{\nabla}f(x, y, z) = \langle a, b, c \rangle$$

constant vector field



$$2) f(\vec{r}) = |\vec{r}|^2$$

$$f(x, y, z) = x^2 + y^2 + z^2$$

$$\vec{\nabla} f = \langle 2x, 2y, 2z \rangle$$

$$\vec{\nabla} f = 2\vec{r}$$

Given \vec{u} ,

$$D_{\vec{u}} f = \vec{u} \cdot \vec{\nabla} f$$

$$D_{\vec{u}} f = \vec{u} \cdot (2\vec{r})$$

$$D_{\vec{u}} f = 2\vec{u} \cdot \vec{r}$$

$$3) f(\vec{r}) = x^3 + y^3 + z^3$$

$$\vec{\nabla} f = \langle 3x^2, 3y^2, 3z^2 \rangle$$

$$= 3 \langle x^2, y^2, z^2 \rangle$$

$$D_{\vec{u}} f = \vec{u} \cdot \vec{\nabla} f$$

\dots (no simple formula like)

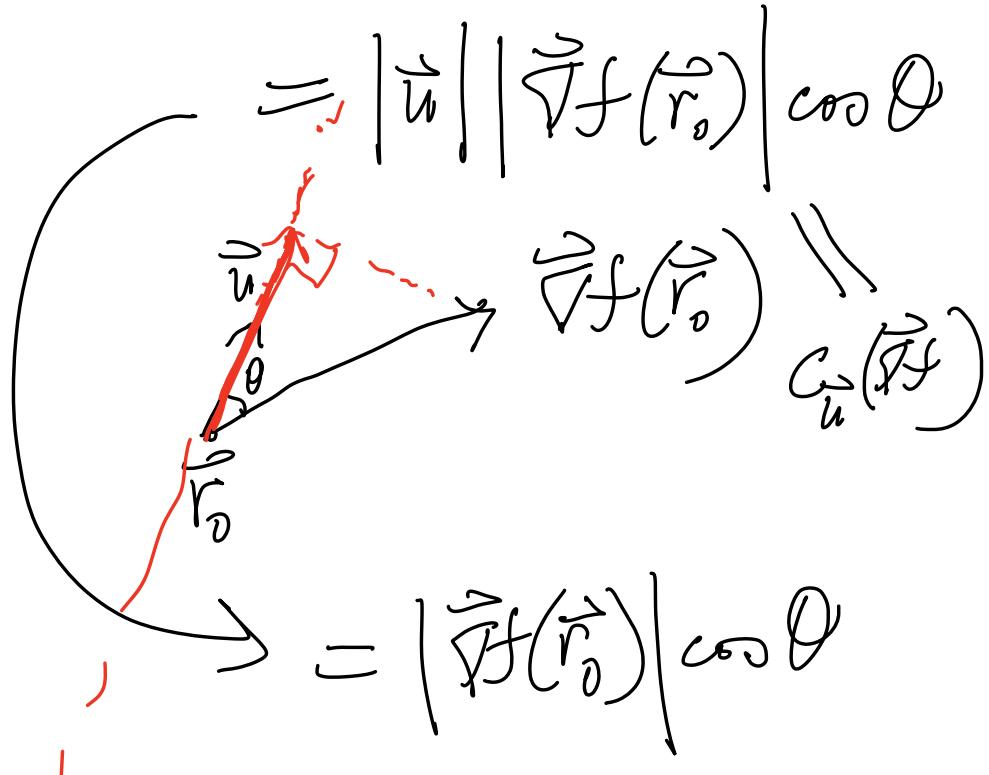
$$\begin{aligned}\vec{u} &= \left\langle \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}} \right\rangle \quad \begin{matrix} x \\ y \\ z \end{matrix} \\ D_{\vec{u}} f(1, -1, 1) &= \vec{u} \cdot \vec{\nabla} f(1, -1, 1) \\ &= \left\langle \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}} \right\rangle \cdot \begin{matrix} 3 \\ 3 \\ 3 \end{matrix} \\ &= \sqrt{3} + \sqrt{3} - \sqrt{3} = \sqrt{3}\end{aligned}$$

Output of f is scalar
 Output of $\vec{\nabla} f$ is vector
 Output of $D_{\vec{u}} f$ is scalar
 $\vec{u} \cdot \vec{\nabla} f$

Directional derivative $D_{\vec{u}} f$

where \vec{u} is unit

$$D_{\vec{u}} f(\vec{r}_0) = \vec{u} \cdot \vec{\nabla} f(\vec{r}_0)$$



$D_{\vec{u}} f(\vec{r}_0)$ is greatest when $\theta = 0$

A diagram shows a black vector ∇f originating from a point. A blue vector \vec{u} is shown originating from the same point, representing the unit vector in the direction of ∇f . The formula $\vec{u} = \frac{\nabla f(\vec{r}_0)}{|\nabla f(\vec{r}_0)|} \quad (\text{if } \nabla f(\vec{r}_0) \neq \vec{0})$ is written below, explaining that \vec{u} is the normalized gradient vector.

$$\vec{u} = \frac{\nabla f(\vec{r}_0)}{|\nabla f(\vec{r}_0)|} \quad (\text{if } \nabla f(\vec{r}_0) \neq \vec{0})$$

\vec{f} points in direction that f increases the fastest

and $D_{\vec{u}} f = |\vec{\nabla} f(\vec{r}_0)|$

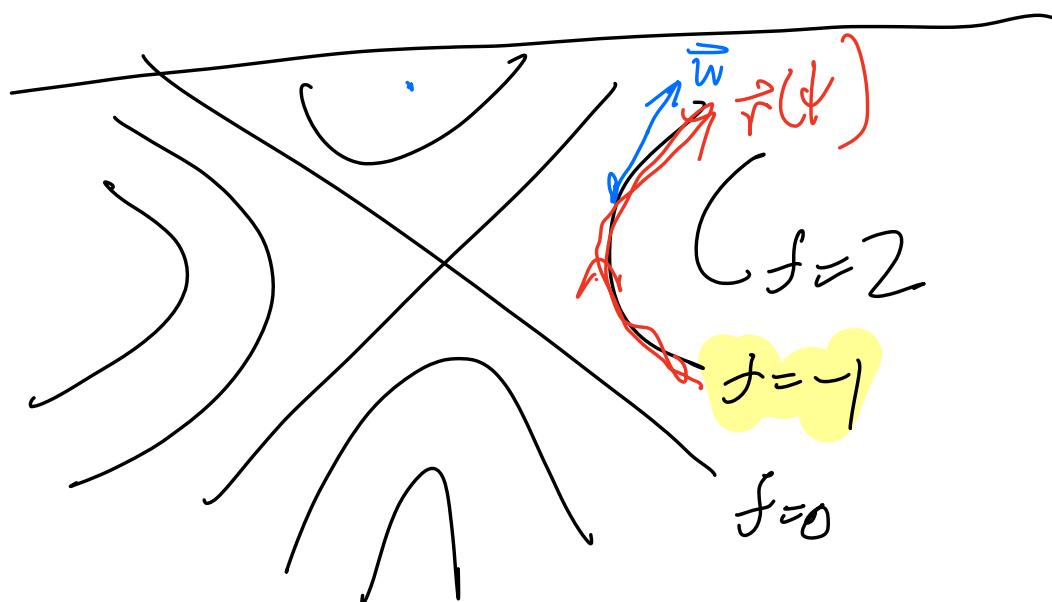
If $\vec{u} = -\frac{\vec{\nabla} f}{|\vec{\nabla} f|}$, $D_{\vec{u}} f = -|\vec{\nabla} f|$

If $\vec{u} \cdot \vec{\nabla} f = 0$, then $D_{\vec{u}} f = 0$

If $|\vec{u}| = 1$

$$-|\vec{\nabla} f(\vec{r}_0)| \leq D_{\vec{u}} f(\vec{r}_0) \leq |\vec{\nabla} f(\vec{r}_0)|$$

$$D_{\vec{u}} f(\vec{r}_0) = 0 \iff \vec{u} \perp \vec{\nabla} f(\vec{r}_0)$$



Here, each contour is a curve
on which f is constant

So if \vec{u} tangent to contour

$$D_{\vec{u}} f = \frac{d}{dt} \Big|_{t=0} f(\vec{r}(t)) = 0$$

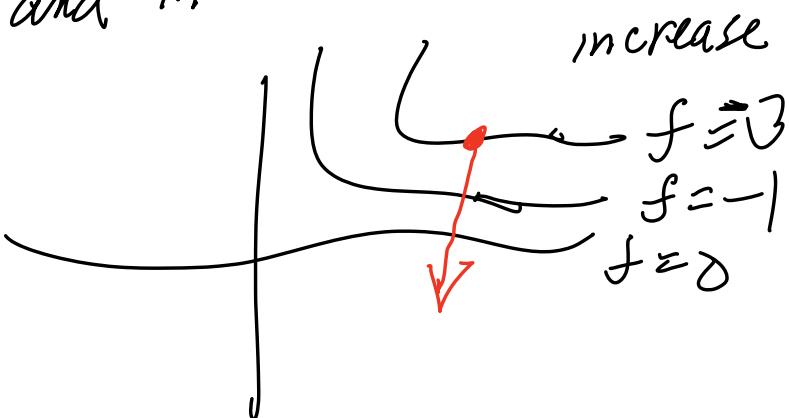
where $\vec{r}(t)$ is a parameterization
of contour

$$\Rightarrow \vec{u} \cdot \vec{\nabla} f(\vec{r}_0) = 0$$

if \vec{u} is tangent to contour

$\Rightarrow \vec{\nabla} f(\vec{r}_0)$ is normal to contour

and in direction of maximal



$$f(x, y, z) = x^2 + y^2 - z^2$$

$$f(1, 1, 1) = 1$$

Contour of f containing $(1, 1, 1)$

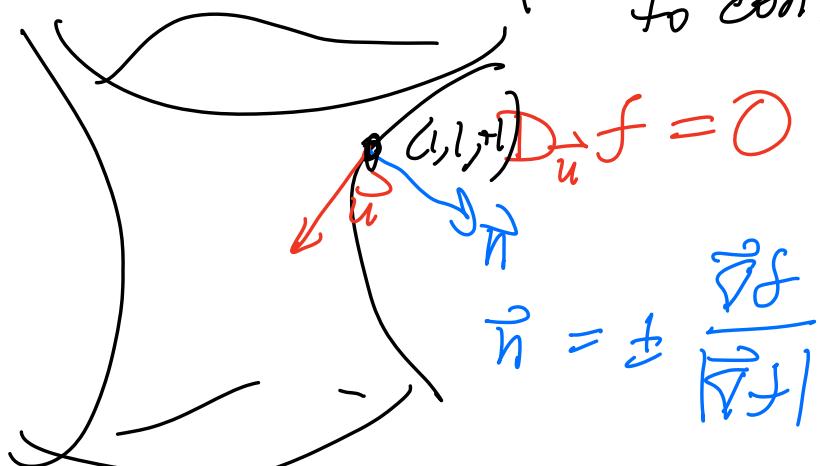
$$\text{, i.e. } x^2 + y^2 - z^2 = 1$$

which is a surface contour

If \vec{u} is tangent to surface

$$\text{then } D_{\vec{u}} f(1, 1, 1) = 0$$

If $\vec{u} = \frac{\nabla f(1, 1, 1)}{|\nabla f(1, 1, 1)|}$, it is normal to contour



$$\vec{n} = \pm \frac{\nabla f}{|\nabla f|}$$

Here: $\vec{\nabla}f = \langle 2x, 2y, -2z \rangle$

$$\vec{\nabla}f(1,1,1) = \langle 2, 2, -2 \rangle$$

$$\vec{n} = \frac{\vec{\nabla}f(1,1,1)}{|\vec{\nabla}f(1,1,1)|} = \left\langle \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{-1}{\sqrt{3}} \right\rangle$$

$\vec{\nabla}f(1,1,1)$ is normal to $f=1$
at $(1,1,1)$

Equation of tangent plane
to $f=1$ at $(1,1,1)$

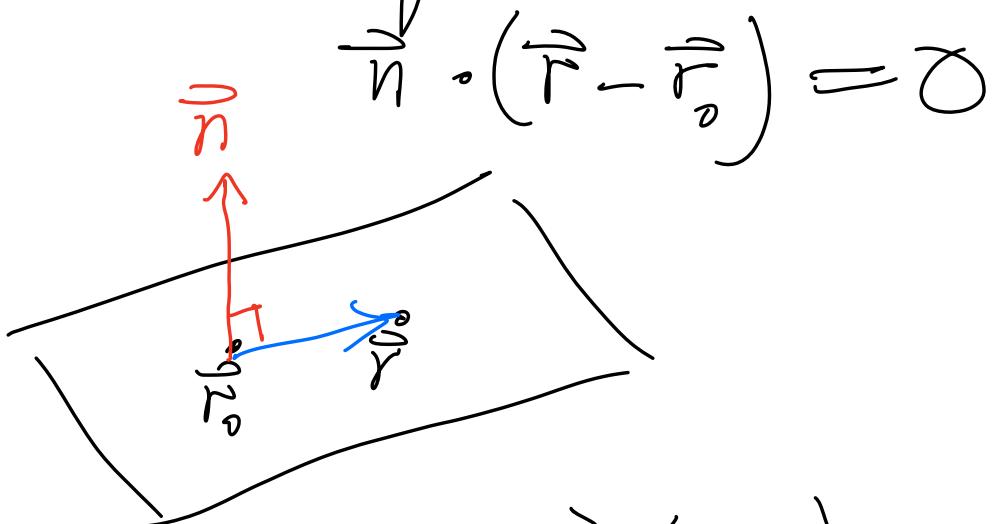
Tangent plane at $(1,1,1)$

1) Contains $(1,1,1)$

2) $\vec{\nabla}f(1,1,1) = \langle 2, 2, -2 \rangle$

is normal to tangent plane

Recall that if $(x_0, y_0, z_0) = \vec{r}_0$
 lies in a plane and \vec{n} is normal to plane,
 then equation of plane is



$$\text{Hence, } \vec{n} = \nabla f(1, 1, 1) = \langle 2, 2, -2 \rangle$$

$$\text{Use } \vec{n} = \langle 1, 1, -1 \rangle \text{ instead}$$

$$\vec{r}_0 = \langle 1, 1, 1 \rangle$$

$$\vec{r} = \langle x, y, z \rangle$$

$$0 = \vec{n} \cdot (\vec{r} - \vec{r}_0) = \langle 1, 1, -1 \rangle \cdot$$

$$\begin{aligned} & \langle x-1, y-1, z-1 \rangle \\ &= x-1 + y-1 - z+1 = x+y-z-1 \end{aligned}$$

So tangent plane to contour $f=1$
where $f = x^2 + y^2 - z^2$, at $(1, 1, 1)$

is $x + y - z - 1 = 0$

$1 + 1 - 1 - 1 = 0$ so $(1, 1, 1)$ lies
in plane

Coefficients are $\langle 1, 1, -1 \rangle$

Given $f(x, y, z)$,

a contour $f(x, y, z) = c$,

and a point (x_0, y_0, z_0) on contour,

then $\vec{n} = \nabla f(x_0, y_0, z_0)$

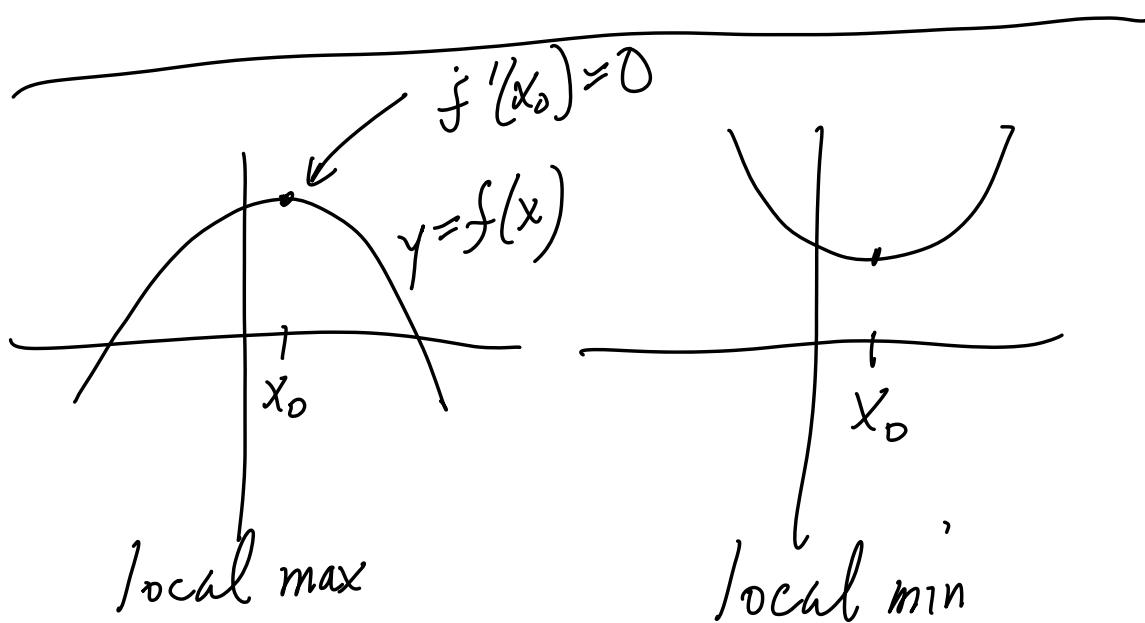
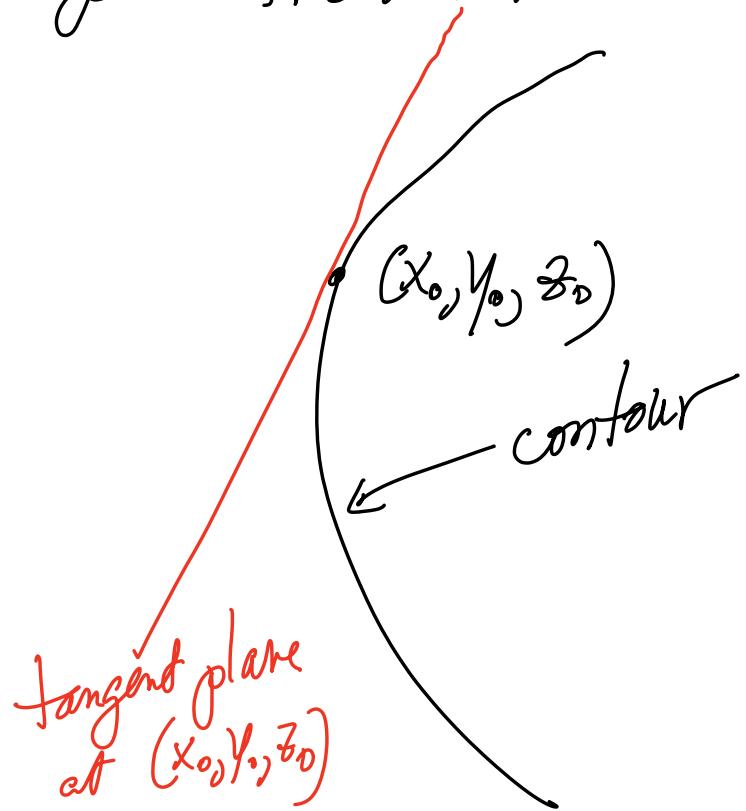
is normal to contour at (x_0, y_0, z_0)

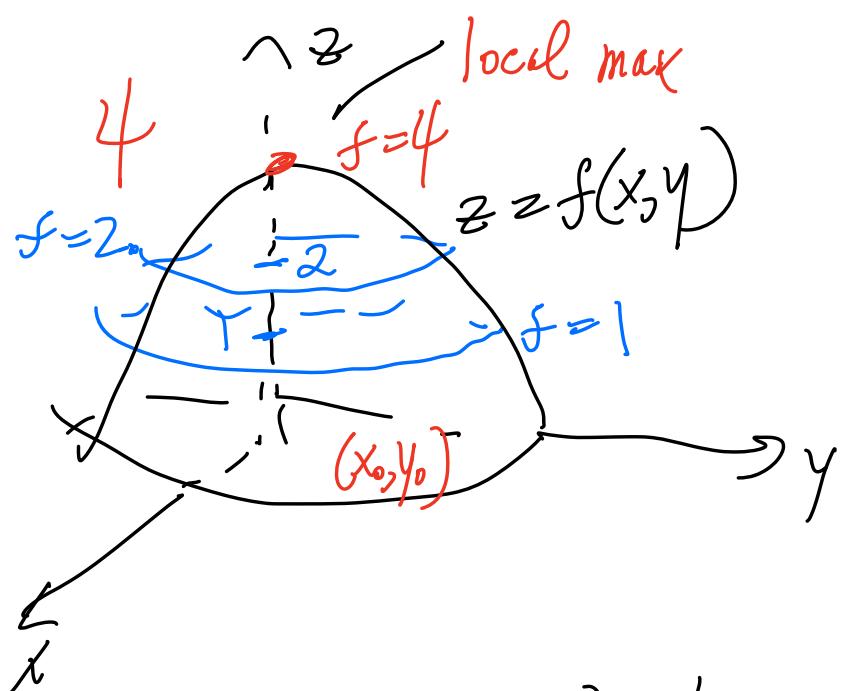
and therefore normal to tangent

plane to the contour at (x_0, y_0, z_0)

\Rightarrow tangent plane has normal vector $\nabla f(x_0, y_0, z_0)$
and contains (x_0, y_0, z_0)

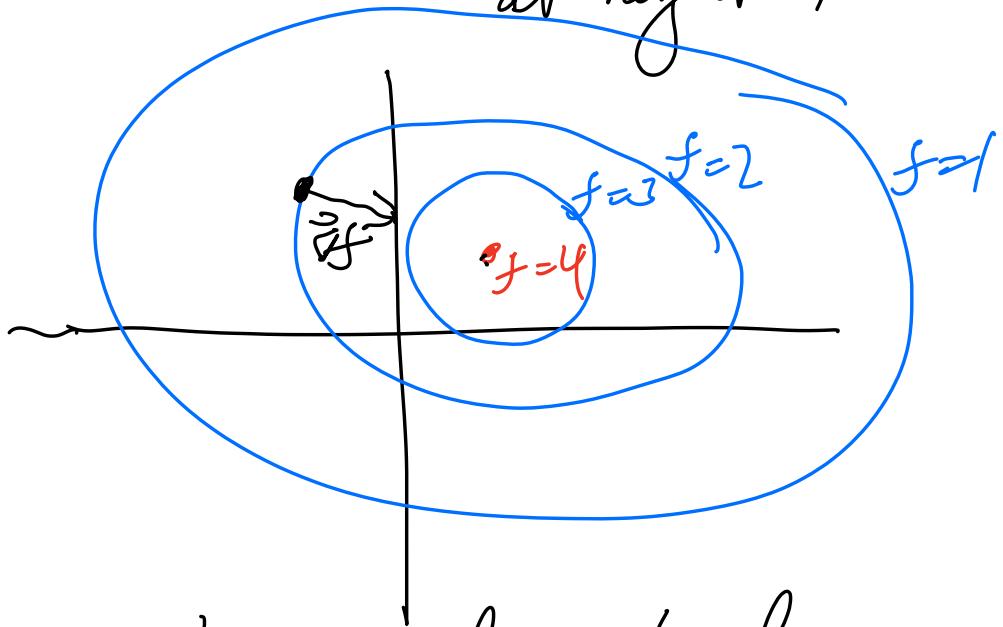
\Rightarrow can write equation for tangent plane from this



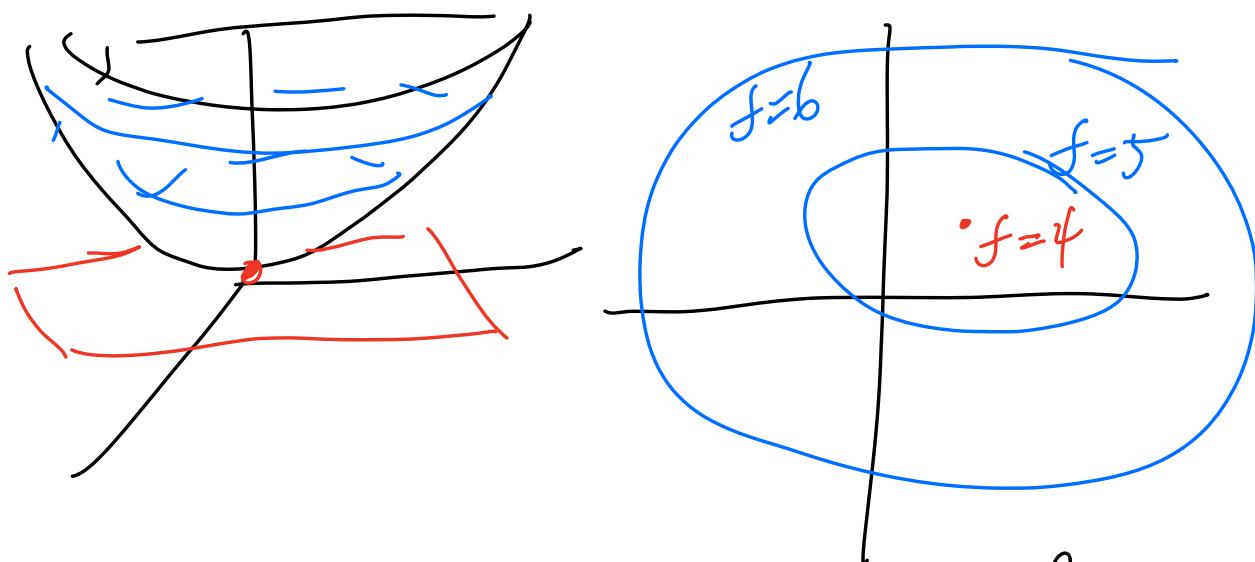


Level sets: $f(x, y) = h$

Slice graph with horizontal plane
at height h



Contour map of a local max



Contour map of local minimum

Local max or min point has zero gradient

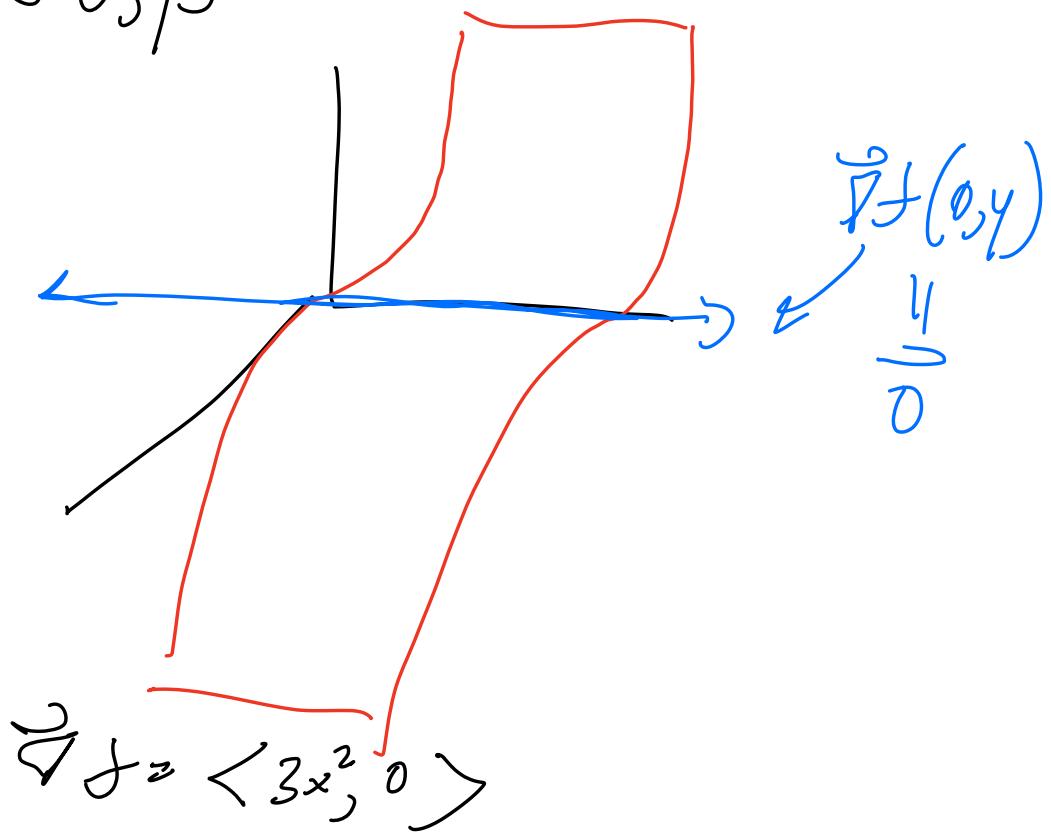
If f has a local max or min at (x_0, y_0) , then $\vec{\nabla}f(x_0, y_0) = \vec{0}$

But converse is not necessarily true

If $\vec{\nabla}f(x_0, y_0) = \vec{0}$, (x_0, y_0) .

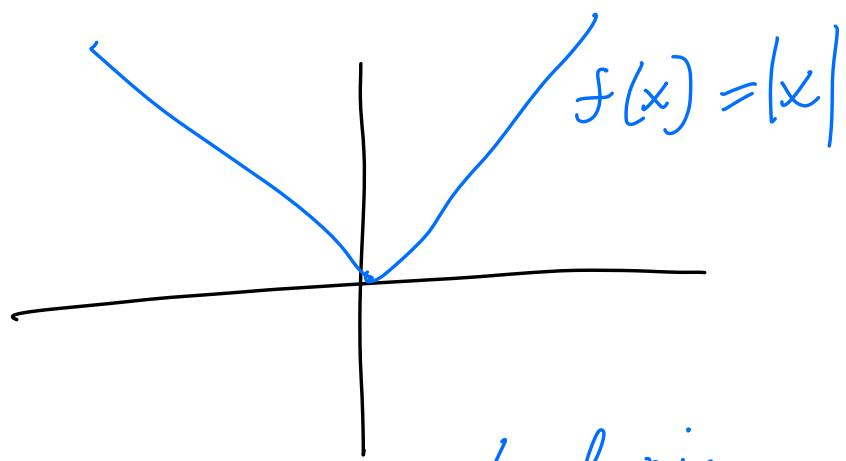
could be a local max or min
but it could be something else

$$f(x,y) = -x^3$$

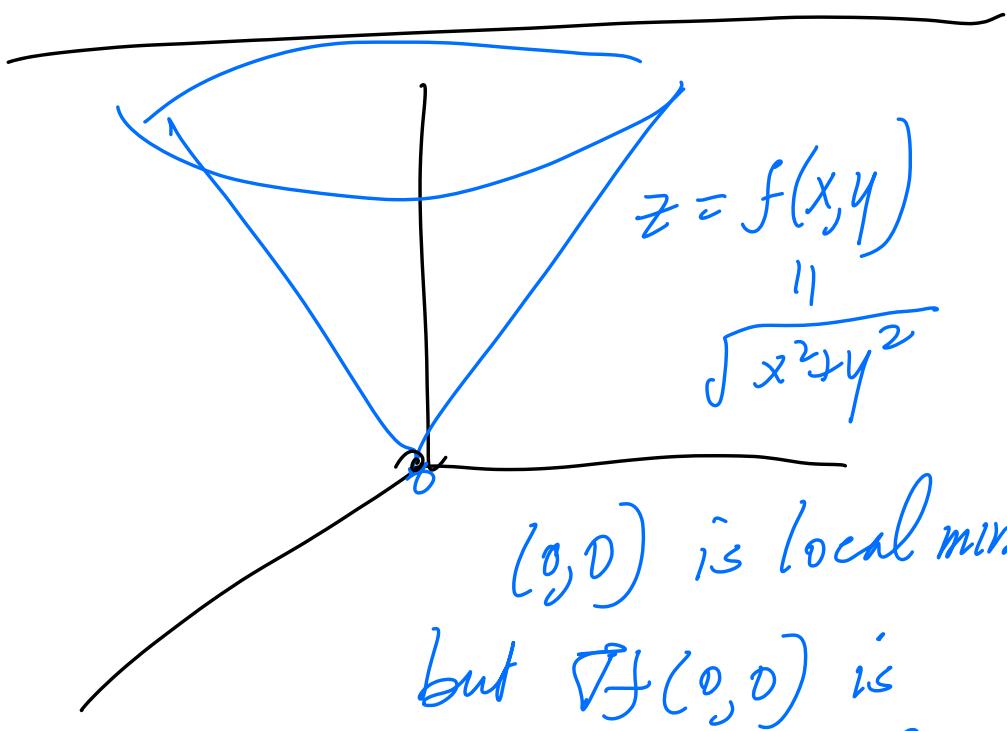


$$\vec{D}f(0,y) = \langle 0, 1 \rangle$$

but no local max or min



$x=0$ is a local min
but $f'(0)$ is undefined



$(0,0)$ is local min
but $\nabla f(0,0)$ is undefined

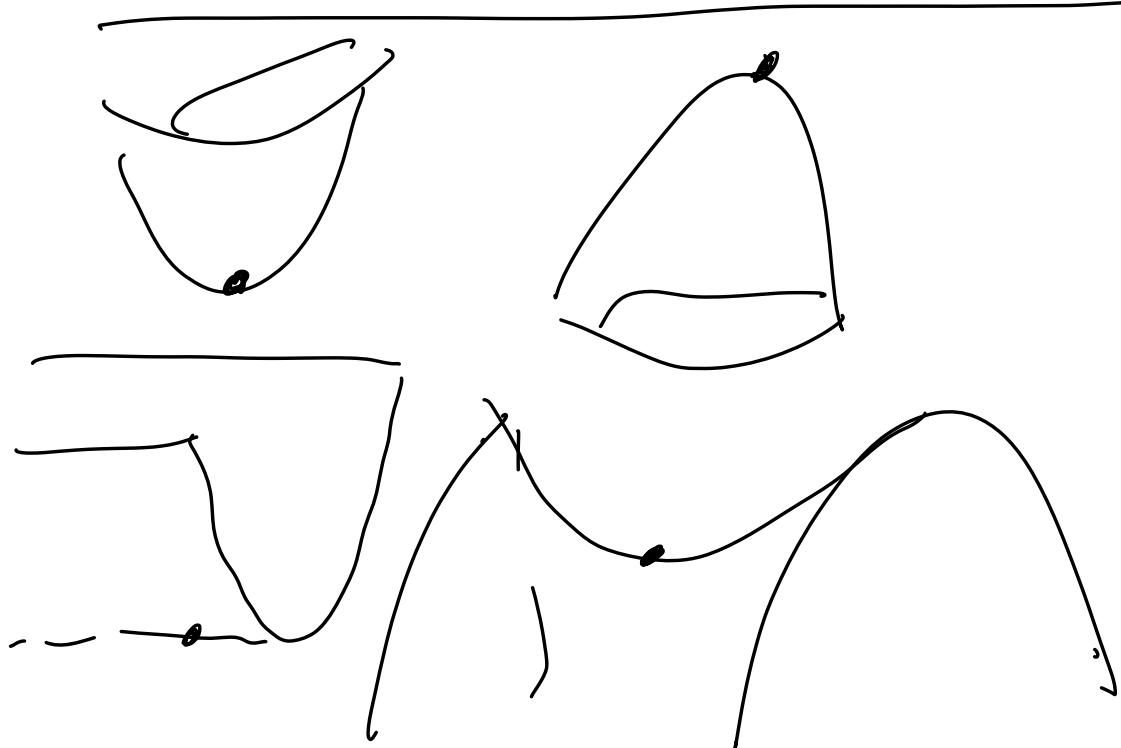
Critical point of $f(x,y)$

(x_0, y_0) is a critical point of f

; if either $\vec{\nabla}f(x_0, y_0) = \langle 0, 0 \rangle$

or: $f_x(x_0, y_0)$ or $f_y(x_0, y_0)$
is undefined

(i.e., $\vec{\nabla}f(x_0, y_0)$ is undefined)



Many different kinds of critical points

Example $f(x,y) = x^2 + xy + y^2$

$$\vec{\nabla} f(x,y) = \langle 2x+y, x+2y \rangle$$

$$\vec{\nabla} f(0,0) = \langle 0, 0 \rangle$$

Is it a local max, local min, saddle point, or something else?

2nd derivative test

Based quadratic surfaces

$$z = x^2 + y^2$$

local
min

$$z = -x^2 - y^2$$

local
max

$$z = x^2 - y^2$$

or $-x^2 + y^2$

saddle
point

2nd derivatives of $f(x,y)$

$$H = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix}$$

"symmetric 2-by-2 matrix"

$$\det H = f_{xx}f_{yy} - (f_{xy})^2$$

If $\det H > 0$, then
 (x_0, y_0) is local max or min

If $\det H < 0$, then saddle point

If $\det H = 0$, inconclusive
