MATH-GA1002 Multivariable Analysis Change of Variables Formula for Integral Tangent Bundle Pushforward of Tangent Vector Cotangent Bundle Differential 1-Forms Pullback of Differential 1-Form

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# Change of Variables Formula for Single and Double Integrals

The change of variable formula for a single integral is also known as substitution,

$$\int_{u=u(a)}^{u=u(b)} f(u) \, du = \int_{x=a}^{x=b} f(u(x))u'(x) \, dx.$$

The change of variable formula for a double integral is more complicated:

$$\int_{x=...}^{x=...} \int_{y=...}^{y=...} f(x, y) \, dy \, dx$$
  
=  $\int_{u=...}^{u=...} \int_{v=...}^{v=...} f(x(u, v), y(u, v)) |\det J(u, v)| \, dv \, du,$ 

where

$$J(u,v) = \begin{bmatrix} \partial_{u}x & \partial_{v}x \\ \partial_{u}y & \partial_{v}y \end{bmatrix}$$

# Change of Variables Formula for Multiple Integral

The change of variable formula for an *m*-dimensional integral is:

$$\int_{x^{1}=...}^{x^{1}=...} \cdots \int_{x^{m}=...}^{x^{m}=...} f(x^{1},...,x^{m}) dx^{m} \cdots dx^{1}$$
  
=  $\int_{u^{1}=...}^{u^{1}=...} \cdots \int_{u^{m}=...}^{u^{m}=...} f(x^{1}(u),...,x^{m}(u)) |\det J(u)| du^{m} \cdots du^{1},$ 

where

$$J(u) = \begin{bmatrix} \partial_1 x^1 & \cdots & \partial_m x^1 \\ \vdots & & \vdots \\ \partial_1 x^m & \cdots & \partial_m x^m \end{bmatrix}$$

## Inconsistency Between Single and Double Integrals

If f(x, y) is always positive on a rectangle R = [a, b] × [c, d], then

$$\int_{R} f = \int_{x=a}^{x=b} \int_{y=c}^{y=d} f(x, y) \, dy \, dx > 0$$

• If f(x) is always positive on an interval [a, b], then

$$\int_{x=a}^{x=b} f(x) \, dx = - \int_{x=b}^{x=a} f(x) \, dx$$

For a single integral, the direction of integration matters
We do this, so that the Fundamental Theorem of Calculus,

$$\int_{x=a}^{x=b} f'(x) \, dx = f(b) - f(a)$$

holds, even if a > b

#### **Tangent Vectors**

- Let  $O \subset \mathbb{R}^m$  be open
- ► Recall that a tangent vector at x ∈ O is the velocity vector of a parameterized curve
- Let  $T_x O$  be the space of all tangent vectors at x
- Given a tangent vector v ∈ T<sub>x</sub>O, there is a smooth curve c : I → O such that

$$c(0) = x$$
 and  $c'(0) = v$ 

- Recall also that a tangent vector defines a directional derivative of functions
- Given a tangent vector v ∈ ℝ<sup>m</sup> at x ∈ O and a smooth function f : O → ℝ,

$$D_{v}f(x) = \left.\frac{d}{dt}\right|_{t=0} f(c(t))$$

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#### **Coordinate Tangent Vectors**

• Given  $x = (x^1, ..., x^m) \in O$  and  $1 \le k \le m$ , let  $c_k : I \to O$  be the curve such that

$$c_k(t) = (c_k^1(t), \ldots, c_k^m(t)),$$

where for each  $1 \leq j \leq m$ ,

$$c_k^j(t) = egin{cases} x^j & ext{if } j 
eq k \ t & ext{if } j = k \end{cases}$$

For each 1 ≤ k ≤ m, let ∂<sub>k</sub> ∈ T<sub>x</sub>O be the velocity vector
Then c<sub>k</sub>(0) = x and ∂<sub>k</sub> = c'<sub>k</sub>(0)

# Tangent Space is a Vector Space

Let v ∈ T<sub>x</sub>O and c : I → O be a curve such that c(0) = x and c'(0) = v
If c(t) = (c<sup>1</sup>(t),..., c<sup>m</sup>(t)), then v = c'(0) = ((c<sup>1</sup>)'(0),..., (c<sup>m</sup>)'(0)) ∈ ℝ<sup>m</sup>
For any a ∈ ℝ, the curve ã : L > O given by

For any  $a \in \mathbb{R}$ , the curve  $\tilde{c} : I \to O$  given by

$$\tilde{c}(t) = x + t(av)$$

has velocity  $\tilde{c}'(0) = av$ 

► Given x ∈ O and v<sub>1</sub>, v<sub>2</sub> ∈ T<sub>x</sub>O, if c<sub>1</sub> and c<sub>2</sub> are the curves given by

$$c_1(t) = x + tv_1$$
 and  $c_2(t) = x + tv_2$ ,

then the curve c: I 
ightarrow O given by

$$c(t) = x + t(v_1 + v_2)$$

satisfies c(0) = x and  $c'(0) = v_1 + v_2$ 

•  $T_pO$  satisfies all of the properties of a vector space

# Tangent Bundle

• We will let 
$$T_*O = \coprod_{x \in O} T_xO,$$

#### which is called the **tangent bundle** of O

Coordinate Tangent Vectors are a Basis of Tangent Space

Any v ∈ T<sub>x</sub>O can be written with respect the coordinate tangent vectors (∂<sub>1</sub>,...,∂<sub>m</sub>) as

$$v = \partial_k a^k = a^1 \partial_1 + \dots + a^m \partial_m$$

I.e., there is a linear isomorphism

$$\mathbb{R}^m o T_X O$$
  
 $(a^1, \dots, a^m) \mapsto a^1 \partial_1 + \dots + a^m \partial_m$ 

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## Pushforward of a Tangent Vector

- Let  $U \subset \mathbb{R}^k$  and  $F : U \to O$  be a smooth map
- Let  $t = (t^1, \ldots, t^k)$  denote the coordinates on U
- ▶ Recall that the **differential** of F at  $t \in U$  is the linear map

$$\partial F(t) : T_t U o T_{F(t)} O$$
  
 $au \mapsto D_{ au} F(x) = \left. \frac{d}{dt} \right|_{t=0} F(c(t)),$ 

where c(0) = t and  $c'(0) = \tau$ 

- The tangent vector ∂F(x)(τ) is called the **pushforward** of τ by F
- The pushforward map at x is also denoted

$$F_*: T_t U \to T_{F(t)} O$$

# Cotangent Space and Bundle

For each 
$$x \in O$$
, denote  $T_x^* O = (T_x O)^*$ 

And denote

$$T^*O = \coprod_{x \in O} T^*_x O$$

# **Differentials of Functions**

• Let  $O \subset \mathbb{R}^m$  be open and  $f : O \to \mathbb{R}$  be a smooth function

Recall that the differential of f at each  $x \in O$  is a linear map

$$df(x): T_x O \to \mathbb{R},$$

where, for each  $v \in T_X O$ ,

$$\langle df(x),v\rangle = D_v f(x) = \left. \frac{d}{dt} \right|_{t=0} f(c(t)),$$

where  $c: I \to O$  is a smooth curve such that c(0) = x and c'(0) = v

# Differentials of Coordinate Functions

- Let  $(\partial_1, \ldots, \partial_m)$  denote the standard basis of  $\mathbb{R}^m$
- For each  $1 \le k \le m$ , there is the coordinate function

$$x^k:\mathbb{R}^m o\mathbb{R}$$
 $(a^1,\ldots,a^m)\mapsto a^k$ 

• Let 
$$v = \partial_k v^k \in T_x O$$

- Let  $c: I \to O$  be a curve such that c'(0) = v
- ▶ Then, if  $c = (c^1, ..., c^m)$ , then for any  $1 \le j \le m$ , differential of  $x^j$  at  $x \in O$  is  $dx^j \in T_x^*O$ , where

$$\langle d\mathsf{x}^j(\mathsf{x}),\mathsf{v}
angle = \left.rac{d}{dt}
ight|_{t=0}\mathsf{x}^j(c(t)) = (c^j)'(0) = \mathsf{v}^j$$

In particular,

$$\langle dx^j, \partial_k \rangle = \delta^j_k$$

► Therefore, (dx<sup>1</sup>,..., dx<sup>m</sup>) is the basis of T<sup>\*</sup><sub>x</sub>O that is dual to the standard basis (∂<sub>1</sub>,..., ∂<sub>m</sub>) of T<sub>x</sub>O

#### Differential of Function With Respect to Coordinates

Recall that if f : O → ℝ is a smooth function, then its differential is given by

$$df = \partial_k f \, dx^k,$$

where for each  $x \in O$ ,  $df(x) \in T_xO$ 

- For any  $v = \partial_k v^k \in T_x O$ , let  $c : I \to O$  be a curve such that c(0) = x and c'(0) = v
- Then, by the chain rule,

$$df(x), v \rangle = D_v f(x)$$

$$= \frac{d}{dt} \Big|_{t=0} f(c(t))$$

$$= \partial_k f(c(0))(c^k)'(0)$$

$$= \partial_k f(x)v^k$$

$$= \partial_k f(x)\langle dx^k, v \rangle$$

#### **Differential 1-Forms**

A differential 1-form or just 1-form is a map

 $\theta: O \to T^*O,$ 

such that  $\theta(x) \in T_x^*O$ 

▶ I.e., for each x,  $\theta(x)$  is a linear function on  $\mathbb{R}^m$ ,

$$egin{aligned} & heta(x): \mathbb{R}^m o \mathbb{R} \ & v \mapsto \langle heta(x), v 
angle \end{aligned}$$

Since (dx<sup>1</sup>,..., dx<sup>m</sup>) is a basis of (ℝ<sup>m</sup>)\*, it follows that for each x ∈ O, there exist coefficients a<sub>1</sub>(x),..., a<sub>m</sub>(x) such that

$$\theta(x) = a_1(x) \, dx^1 + \cdots + a_m(x) \, dx^m$$

•  $\theta$  is a **smooth** 1-form if the functions  $a_1, \ldots, a_m$  are smooth

#### Pullback of 1-Form

▶ Recall that a linear map  $L: V \rightarrow W$  induces a natural map

$$L^*: W^* \to V^*,$$

where for each  $\beta \in W^*$ ,  $L^*\beta = \beta \circ L \in V^*$ , i.e., for each  $v \in V$ ,

$$L^*\beta(v) = \beta(L(v))$$

- L\*β is called the pullback of beta by L
- Let  $O \subset \mathbb{R}^m$  and  $P \subset \mathbb{R}^n$  be open
- Let  $F: O \rightarrow P$  be a smooth map
- ► The pushforward map at x ∈ O is a linear map

$$F_*:\mathbb{R}^m\to\mathbb{R}^n$$

The pullback by F is a linear map

$$F^*: (\mathbb{R}^n)^* \to (\mathbb{R}^m)^*$$

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Pullback of 1-Form (Part 2)

For any 1-form β on P and y ∈ P, β(y) ∈ (ℝ<sup>n</sup>)\* is a linear function

 $\beta(y): T_y P \to \mathbb{R}$ 

▶ By definition, the pullback  $F^*\beta$  at  $x \in O$  is the linear function

 $(F^*\beta)(x):\mathbb{R}^m\to\mathbb{R}$ 

given by  $(F^*\beta)(x) = \beta(F(x)) \circ F_*$ 

▶ I.e., given a tangent vector  $v \in \mathbb{R}^m$  at  $x \in \mathbb{R}^m$ ,

$$\langle (F^*\beta)(x), v \rangle = \langle \beta(F(x)) \circ F_* \rangle \\ = \langle \beta(F(x)), F_* v \rangle$$

## Pullback of Differential of Function

- Let f : P → ℝ be a smooth function and F : O → P be a smooth map
- ▶ Recall that for any  $v \in T_x O$ , and  $c : I \to O$  such that c(0) = x and c'(0) = v,

$$D_{v}(f \circ F)(x) = \langle d(f \circ F)(x), v \rangle$$
$$= \frac{d}{dt} \Big|_{t=0} f(F(c(t)))$$
$$= \frac{d}{dt} \Big|_{t=0} f((F \circ)(t)))$$
$$= \langle df(x), (F \circ c)'(0) \rangle$$
$$= \langle df(x), F_{*}v \rangle$$
$$= \langle (F^{*}df)(x), v \rangle$$

#### Coordinate Vectors and 1-Forms

- Let (x<sup>1</sup>,...,x<sup>m</sup>) denote coordinates on O
- Let  $(y^1, \ldots, y^m)$  denote coordinates on P
- Denote the coordinate basis of  $T_X O$  by

$$(\partial_1^x,\ldots,\partial_m^x) = \left(\frac{\partial}{\partial x^1},\ldots,\frac{\partial}{\partial x^m}\right)$$

• Denote the coordinate basis of  $T_y P$  by

$$\left(\partial_1^{y},\ldots,\partial_m^{y}\right) = \left(\frac{\partial}{\partial y^1},\ldots,\frac{\partial}{\partial y^m}\right)$$

Each coordinate on P can be viewed as a function

$$y^a: P \to \mathbb{R}$$

The differentials (dy<sup>1</sup>,..., dy<sup>n</sup>) are the basis of T<sup>\*</sup><sub>y</sub>P dual to the coordinate basis of T<sub>y</sub>P

#### Pullback of Coordinate 1-Form

For each  $x \in O$ , denote

$$F(x) = (y^1(x), \dots, y^n(x)) \in P$$

For each  $1 \le a \le n$ , denote

$$(y^a \circ F)(x) = y^a(x)$$

• Then, for each  $v \in T_x O$  and  $1 \le a \le n$ ,

$$\langle (F^*dy^a)(x), v \rangle = \langle d(y^a \circ F), v \rangle$$
  
=  $\langle dy^a, v \rangle$ 

▶ With respect to coordinates on *O*, if  $v = v^i \partial_i^x \in T_x O$ , then

$$\langle (F^* dy^a)(x), v \rangle = \langle dy^a, v \rangle \\ = \langle \partial_i^x y^a dx^i, v^j \partial_j^x \rangle \\ = v^j \frac{\partial y^a}{\partial x^j}$$

# Pullback of 1-Form in Coordinates

$$\blacktriangleright F^* dy^a = \partial_j y^a \, dx^j$$

The pullback by F of the 1-form

$$\beta = b_a \, dy^a$$

is

$$F^*\beta = b_a \frac{\partial y^a}{\partial x^j} \, dx^j$$

• Here,  $b_a = b_a \circ F$  and  $y^a = y^a \circ F$