

on the left.

The QI lens:

Last time: ~~QI's~~, ~~Milnor~~ = Schwarz - Milnor:

Thm: Let X be a proper geodesic metric space and let G be a group that acts geometrically on X . Then X is finitely generated, and if G also acts geometrically on Y , then $X \sim_{QI} Y$.

~~Specifically, for any finite gen. set, $X \sim_{QI} \Gamma_S$.~~

PF: Suffices to show that \exists a finite gen. set S s.t. $X \sim_{QI} \Gamma_S$. All Cayley graphs are QI so if G acts on Y , then $Y \sim_{QI} \Gamma_S \sim \Gamma_S$.

~~Let $r > 0$ be s.t. $G B_r(x) = X$.~~ ~~Note because G acts by isms, $d(gx, hx) = d(x, gx)$.~~
 Let $r = \text{diam } X$, so $G B_r(x) = X$ for any $x \in X$. Let $x \in X$.
 Let $S = \{s \in G \mid s B_{2r}(x) \cap B_{2r}(x) \neq \emptyset\}$. Then S is finite.

S generates G : Let $g \in G$. Let $\gamma: [0, L] \rightarrow X$ be a unit-speed geodesic from x to gx . We discretize γ : Let $n = \lceil \frac{L}{r} \rceil$, let x_0, \dots, x_n be evenly spaced points along γ , $x_0 = \gamma(0), x_n = \gamma(L)$. Then $d(x_i, x_{i+1}) \leq r$.

$\forall i, \exists g_i$ s.t. $x_i \in g_i B_r(x)$. (take $g_0 = e, g_n = g$)
 Then $\forall i, d(g_i x, g_{i+1} x) \leq d(g_i x, x_i) + d(x_i, x_{i+1}) + d(x_{i+1}, g_{i+1} x) \leq 3r$.

So $d(x, g_i^{-1} g_{i+1} x) \leq 3r \Rightarrow g_i^{-1} g_{i+1} \in S$.

Further, $(g_0^{-1} g_1)(g_1^{-1} g_2) \dots (g_{n-1}^{-1} g_n) = g_0^{-1} g_n = g$. So S generates G .

~~$\Gamma_S \sim_{QI} X$~~ Let $f: G \rightarrow X$. Further, if d_S is word metric, $d_S(1, g) \leq n = \lceil \frac{d(x, gx)}{r} \rceil \leq \frac{d(x, gx)}{r} + 1$.

$\Gamma_S \sim_{QI} X$: Let $f: G \rightarrow X, f(g) = gx$. We claim f is a QI.

By above, $\forall g, h \in G$, Because G acts by isms, $d(gx, hx) = d(x, g^{-1}hx)$.
 $r d_S(g, h) - r \leq d(gx, hx)$

Conversely, $\forall s \in S, d(x, sx) \leq 4r$. Suppose $g = s_1 \dots s_k$.

Then we can draw: $x \xrightarrow{4r} s_1 x \xrightarrow{4r} s_1 s_2 x \xrightarrow{4r} \dots \xrightarrow{4r} g x$, of length $\leq 4rk$.

$\Rightarrow d(x, gx) \leq d_g(1, g) \cdot 4r$. So f is a BI-embedding.
The image of G is Gx and $d(y, Gx) \leq r \ \forall y \in X \Rightarrow f$ is coarsely surjective, so f is a BI.

We thus say that G acts on X if \exists finite sets $S \subset G, T \subset H$ s.t. $\Gamma_S \cong \Gamma_T$.

Corollaries: - All finite groups act geometrically on $*$ \Rightarrow all are BI.

- Suppose $H \triangleleft G$ is a finite-index subgroup

Then H acts geometrically on $\Gamma_S \Rightarrow G \cong_{BI} H$.

- Suppose $N \triangleleft G$ is finite. Then $G/N \cong_{BI} G$.

~~What do these geometries look like?~~ - we can associate geometry to every group.

What do these geometries look like? - this ignores finite groups, phenomenon

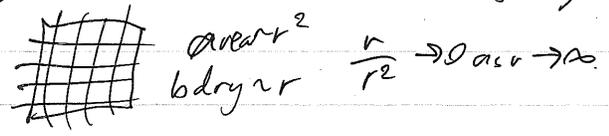
Martin Bridson drew the following map: . . . but there's still a lot left.

four: | • - all finite groups live here.

Rest is infinite groups: complexity roughly left-to-right.

Edges describe two major phenomena in GBT: amenability, hyperbolic NPC.

Amenability: a little hard to describe - we'll talk about it later, but one def: ~~for these~~ ^{all} groups where the Banach-Tarski paradox you can find subsets of the Cayley graph with small boundary:



vs. non amenable where you can't: any subset of n vertices has at least n edges leading out.

Related to ~~at least~~ ^{many diff props, like} Banach-Tarski:

(classification says that every abelian is BI to \mathbb{Z}^n)

So: abelian groups. If you extend an amenable group by an amenable group: ~~to~~ \Rightarrow you get an amenable gp: i.e., if $N \triangleleft G$ and $N, G/N$ are amenable, then so is G .

Examples: Nilpotent groups \mathbb{Z}^n (covered in my topics course in the spring)

- abelian with a twist: $\mathbb{Z} \langle x, y, z \mid [x, z] = [y, z], [x, y] = z \rangle$.

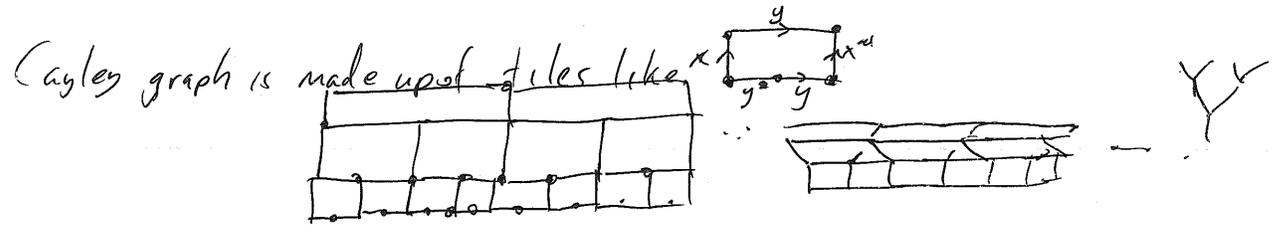
$[x^n, y^n] = z^{n^2}$ - so we can write z^{n^2} as a word of length $4n$.

Solvable groups: Geometry starts to get more complex:

$$BS(1,2) = \langle x, y \mid xyx^{-1} = y^2 \rangle$$

Then $x^n y x^{-n} = y^{2^n}$ - exponential distortion.

(This also gets into another issue: Computations in groups
~~Context~~ ~~We have~~: What does this look like geometrically?



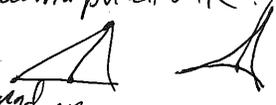
This is metabelian: $1 \rightarrow \mathbb{Z}[\frac{1}{2}] \rightarrow BS(1,2) \rightarrow \mathbb{Z} \rightarrow 1$
 More complex groups exist.

Elementary amenable: can be constructed from ~~sets~~ finite and abelian sps by taking subgroups, quotients, extensions, ~~and~~ direct unions.

Open question: Are all elementary amenable groups elementary amenable?
 (Hope for some algebraic good behavior.)

Hyperbolic/NPC:

Recall from diff geo: ~~the~~ negatively curved / NPC spaces are nice:

- Unique geodesics
- Universal cover is homeomorphic to \mathbb{R}^n
- triangle comparison: 
- compact NPC ~~spaces~~ ~~have~~ ~~no~~ ~~fund~~ ~~sp.~~
- ~~flat torus theorem~~
- splitting theorem: if fund sp is a product, then space is a product

~~Hyperb~~ This side of the map covers groups with similar properties:

Prototypically: F - free groups.



- Unique geodesics
- Universal cover is contractible
- Cayley graph is contractible
- ~~fronds~~ ~~are~~ ~~tripods~~

Note: All free groups are QI: $\bigoplus \bigoplus \bigoplus \rightarrow \bigoplus$

turns $\#$ into $\#$ in a QI way.
Same for $\bigoplus \rightarrow \bigoplus$, etc.

Hyperbolic groups generalize this: include: $\#$ hyperbolic plane ^{groups that act geometrically on complete mlds of negative curv. space.}

- include: ~~the~~ groups of isometries of hyperbolic space

- fundamental groups of negatively curved closed mlds.

Course version: - "random groups" $G = \langle a, b, c \mid abc^2 a^2 \dots \rangle$

- (can be weakened to δ -hyperbolic groups $w_i = 1, w_2 = 1, \dots, w_n = 1$)

where w_i are random words of length l , then $\#$

$P[G \#]$ then G is hyperbolic with high probability, then: if n is fixed $l \rightarrow \infty$

- random group presentations: $\langle a, b, c \mid w_1 = 1, w_2 = 1, \dots, w_n = 1 \rangle$

is usually hyperbolic ~~then~~ has a good course version!

This class is $\#$ closed under QI - remarkable thm of Gromov.

Nonpositive curv. is more fragile:

$C_0 = \text{CAT}(0)$ groups $\#$ includes

= groups that act geometrically on complete $\text{CAT}(0)$ spaces (incl. complete mlds w/ $K \leq 0$).

Includes abelian groups, but also a lot of nice Lie groups:

eg. $SL_n(\mathbb{R})$ acts on a nonpositively curved symmetric space.

Problem: This is not closed under QI's, ~~so various~~ ^{doesn't have a good course version.}

part of this map is devoted to weakenings that are a little more coarse: semi-hyperbolic, automatic, combable, etc.

that try to capture things like: unique geodesics, aspects of NPC, but there isn't one single notion of nonpositive curvature.

So, these ~~are~~ But these are geometrically nice.

If one edge is mostly "algebraically nice", the other is "geometrically nice".

that leaves the middle - where we have much loss of a threshold.

In fact, groups here are often hard to construct: Lie groups are around the edges, as show that they're infinite.

The edges ~~are~~ ~~are~~ a lot of groups that are "easy" to understand/construct.

- if you construct it out of simpler pieces - might be solvable, or
- if you it's a Lie group - left side of map.
- if you write down a group presentation - hyperbolic
- fundamental group of a manifold - why is the fund gp infinite?

Examples: These are two big paradigms for understanding groups:

Amenable: Decompose into simpler groups.

- Apply ~~to some~~

Hyperbolic: Look No tools of amenability, no tools from NPC, but there are a lot of groups out there.

Middle: everything else: A lot of interesting groups here:

- self-similar groups - subdirect products

- anything that doesn't fit in this amenable/hyperbolic binary

But it gets more difficult to construct, more difficult to prove infinite, etc.

~~if you just start writing down a group, how do you know it's a group,~~

~~how so there are various paths and dots here, but less obvious~~

~~here could be there are a lot of groups. and there's a lot we don't know.~~

E.g. there's a close relationship

E.g. these groups are groups where it's ^{usually} reasonably easy to show whether an elt is nontrivial: all these extensions, an elt is nontrivial if nonzero in any factor

- with NPC - an element is nontrivial if there's a geodesic that hits it

Even these other examples ~~generally~~ generally have good algorithms.

But there are a remarkable theorem of Novikov:

Thm (Novikov): There is a finitely-presented group with unsolvable word problem:

i.e. ~~there is a~~ $G = \langle g_1, \dots, g_n \mid r_1 = 1, r_2 = 1, \dots, r_s = 1 \rangle$

and there is no algorithm that takes a product

$w = g_{i_1}^{\pm 1} \dots g_{i_h}^{\pm 1}$ and returns whether $w = 1$.

Hyperbolic space and Hyperbolicity.

Today: One of the most important geometries in GGT: Hyperbolicity.

First, quick refresher on hyperbolic geometry: For $n \geq 2$
The hyperbolic n -space is the unique n -dimensional ^{complete} simply-connected n -manifold with constant sectional curvature -1 .

Two common ways to write it:

Disc model: $\mathbb{H}^n = D^n$ with metric $dg^2 = \frac{4 dx^2}{(1-r^2)^2}$

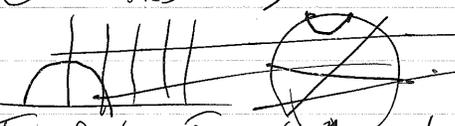
Upper half-space: $\mathbb{H}^n = \{(x_1, \dots, x_n) \mid x_n > 0\}$ $dg^2 = \frac{dx^2}{x^2}$

Models connected to conformal geometry: conformal metric on \mathbb{R}^n is a metric $dg^2 = h(x) dx^2$. conformal map: $M \rightarrow N$ is a map that preserves angles, acts as a scaling.

These are both conformal models: angles are preserved. Note that scaling factor goes to ∞ near boundary of each, so these are complete. And these are isometric: if $n=2$, can take $D^2 = \{z \mid |z| < 1\}$

$U^2 = \{z \mid \text{Im}(z) > 0\}$
and then $z \mapsto \frac{z-i}{z+i}$ sends U^2 to D^2 .

~~Geodesics are circles and lines that are orthogonal to ∂D^n or ∂U^n .~~



Isometries:

In fact, $\text{Isom}(\mathbb{H}^n) = \{ \text{conformal maps from } D^n \rightarrow D^n \}$
 $= \{ \text{conformal maps from } U^n \rightarrow U^n \}$.

If $n=2$, $\text{Isom}(\mathbb{H}^2) = \{ z \mapsto \frac{az+b}{cz+d} \mid ad-bc=1, a,b,c,d \in \mathbb{R} \}$
 $= \text{PSL}(2, \mathbb{R})$ (because $\frac{az+b}{cz+d} = \frac{(-a)z-b}{(-c)z-d}$)

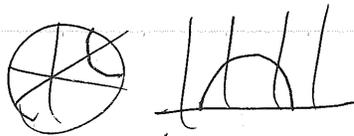
Notable examples: rotations, translations and scalings.

Key fact: ~~HTs send circles~~ (but note that by uniqueness, isom gr is transitive on n -frame bundle).

These rotations give us ~~By uniqueness, isom gr is transitive on unit-tangent bundle, so we should be able to use these to produce all geodesics: clearly, and are geodes, what are rest?~~

Prop: ~~Lemma~~: $z \mapsto \frac{az+b}{cz+d}$ sends (circles and lines) to (circles and lines)

- so all geodesics are circles or lines that are orthogonal to ∂D^n or ∂U^n .



What is the geometry like?

1. Geodesics spread faster than in Euclidean space!



circumference of circle is $2\pi r \exp r$ which is \exp in r , so \triangle grows \exp .

~~2. There are ultraparallel geodesics - No parallel lines, but:~~

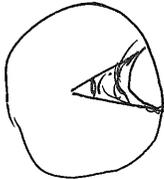
2. Triangles:



~~this distance isn't \exp , by triangle inequality:~~

$d(x,y) \geq 2r$. How much less?

what happens as $r \rightarrow \infty$?
 $2r - 2\epsilon \leq d(x,y) \leq 2r$

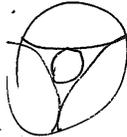


~~In fact,~~ This is a $\frac{2}{3}$ -ideal triangle: 2 vertices at ∞ .
Ideal triangle: all three to ∞ :

Easier to see in half-space:



and see that all are isometric



What does it mean that this is a triangle? All geodesics converge at ∞ .

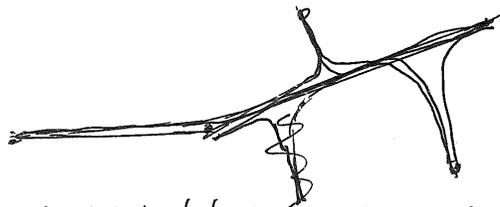
Exercise: - there's an incircle: calculate its radius.

- show that each side is contained in a δ -nbhd of the other 2.
- show that any triangle can be drawn as a subset of an ideal trian.
- show that any triangle has area $\leq \pi$.

3. tree-like structure: $\exists \delta > 0$ s.t.

Every edge of a triangle is contained in a δ -nbhd of the other 2.

So if we start taking quadrilaterals?



- every collection of n points is δ_n -close to a tree.

But! - Unlike a tree, H is 1-ended: the complement of any ball is connected.

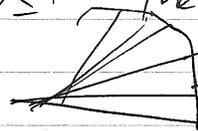
break.

Generalizing and coarsifying: How can we define hyperbolicity for groups? How do we define a notion of a hyperbolic Cayley graph?

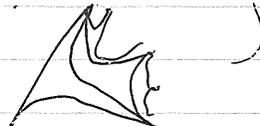
Def: Let $\delta > 0$. A ^{geodesic metric} space X is δ -hyperbolic if every geodesic triangle is δ -thin. That is, if $\gamma_1, \gamma_2, \gamma_3$ are three geodesics  then $\gamma_i \subset N_\delta(\gamma_{j+1} \cup \gamma_{i+2})$. $\forall i$.
(Note: A geodesic is an isometric embedding $I \rightarrow X$. (i.e. shortest path betw two pts).)

Then: - Geodesics are δ -close $\forall p, q \in X$, any two geodesics from p to q are δ -close.

- geodesics follow-travel: if $d(y, z) \leq 1$ then any geodesic $\overline{xy} \cup (\delta+1)$ -close to \overline{xz} .



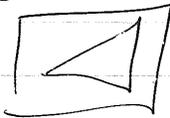
- polygons are thin: if $\gamma_1, \dots, \gamma_n$ form a geodesic n -gon, then $\gamma_i \subset N_\delta(\bigcup_{j \neq i} \gamma_j)$ (triangulate poly).

Qin Liu fact, can do better: 

- every triangle has a center p s.t. $d(p, \gamma_i) \leq \delta \forall i = 1, 2, 3$.

- X does not contain:

- large circles: 
circles bigger than 2δ .
isometrically embedded
copies of planes



Lemma: Let X be a δ -hyperbolic geodesic metric space.

Let $r > 0$ be large. If \overline{xy} is a geodesic of length $2r$, with midpoint m , then every path from x to y outside $B(m, r)$ has length at least $2r - \frac{1}{\delta}$.

Pf: ~~Subdivide~~ Let γ be a path outside $B(m, r)$, $L = \ell(\gamma)$ ^{const speed}
Subdivide γ into 2^k segments of length ≤ 2 , where

Let $k = \lceil \log_2 \ell(\gamma) \rceil$, let $x_i = \gamma(\frac{i}{2^k})$