

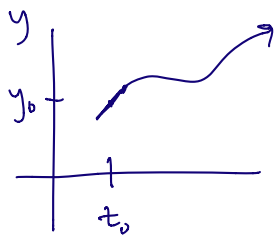
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Numerical Analysis

Ordinary Differential Equations:

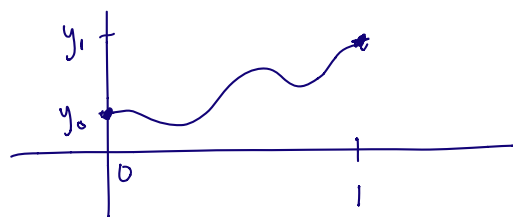
Initial value problem (IVP)

$$(*) \quad \begin{aligned} y'(t) &= f(t, y) \\ y(t_0) &= y_0 \end{aligned}$$



Boundary Value Problems

$$\begin{aligned} y'' + by' + cy &= 0 \\ y(0) &= y_0, \quad y(1) = y_1 \end{aligned}$$



The numerical methods used for solving these two problems are very different. We will focus only on initial value problems.

The solution to $(*)$ can be written down formally as:

$$y(t) = y_0 + \int_{t_0}^t f(\tau, y(\tau)) d\tau. \quad (**)$$

If f doesn't depend on y , we can straight forwardly evaluate: $\int_{t_0}^t f(\tau) d\tau$.

If f does depend on y , then we must solve $(**)$ for y .

All methods for solving IVPs are merely approximating the formal solution in $(**)$.

□

The local uniqueness of the solution to (*) is established by Picard's Theorem, see page 311 in the textbook. Basically, if f is continuous and bounded in a neighborhood of (t_0, y_0) (remember $f = f(t, y)$), then a unique solution exists in some neighborhood of (t_0, y_0) .

Another way of viewing numerical solutions to (*) is to directly approximate the differential part:

For some small $h > 0$,

$$y'(t) \approx \underbrace{\frac{y(t+h) - y(t)}{h}}_{\text{Finite Difference}} \approx f(t, y(t))$$

\Rightarrow Given $y(t)$, to approximate $y(t+h)$ we write:

$$\frac{y(t+h) - y(t)}{h} \approx f(t, y(t))$$

$$\Rightarrow y(t+h) \approx y(t) + \underbrace{h \cdot f(t, y(t))}_{\int_t^{t+h} f(\tau, y(\tau)) d\tau} \quad \left(\text{compare with } (***) \right)$$

This scheme is called the Forward Euler Method.

Let's turn to Finite Differences for a bit:

- ① Approximation error
- ② Floating point round off error.

How good is the Forward Difference at approximating y' in the presence of round-off error:

$$\frac{y(t+h) - y(t)}{h} \xrightarrow{\text{f.p.}} \frac{y(t+h)(1+\delta_1) - y(t)(1+\delta_2)}{h}$$

round off error, $|\delta_i| < \epsilon$
↑
machine precision

$$= \frac{y(t+h) - y(t)}{h} + \frac{y(t+h)\delta_1 - y(t)\delta_2}{h}$$

Ignore the round-off error in $t, h, t+h$.

$$= \frac{\left(y(t) + h y'(t) + \frac{h^2}{2} y''(\xi) \right) - y(t)}{h} + \frac{y(t+h)\delta_1 - y(t)\delta_2}{h}$$

$$= y'(t) + \frac{h}{2} y''(\xi) + \frac{y(t+h)\delta_1 - y(t)\delta_2}{h}$$

The total error is given as $\text{Err}(h) = y'(t) - \frac{y(t+h) - y(t)}{h}$

$$\Rightarrow |\text{Err}(h)| \leq \left| \frac{h}{2} y''(\xi) \right| + \left| \frac{y(t+h)\delta_1 + y(t)\delta_2}{h} \right|$$

$$\leq \underbrace{\left| \frac{h}{2} y''(\xi) \right|}_{\mathcal{O}(h)} + \underbrace{\left(|y(t+h)| + |y(t)| \right) \frac{\epsilon}{h}}_{\mathcal{O}\left(\frac{\epsilon}{h}\right)}$$

$\mathcal{O}(h)$ truncation error | 1st order approximation | $\mathcal{O}\left(\frac{\epsilon}{h}\right)$ round-off error.

To minimize $|\text{Err}(h)|$, h must be chosen to balance these terms:

$$h \sim \frac{\epsilon}{h} \Rightarrow h^2 \sim \epsilon \Rightarrow h \sim \sqrt{\epsilon}$$

If $\epsilon \sim 10^{-16}$ (in double precision), then choosing $h \sim 10^{-8}$ minimizes the error, which is the size of:

$$\begin{aligned} |\text{Err}(h)| &\sim \mathcal{O}(h) + \mathcal{O}\left(\frac{\epsilon}{h}\right) \\ &\sim 10^{-8} + \frac{10^{-16}}{10^{-8}} \sim 10^{-8} \end{aligned}$$

This is the best you can hope for from a forward difference approximation. [3]

An alternative approximation, the centered difference, has the property that:

$$\left| y'(t) - \frac{y(t+h) - y(t-h)}{2h} \right| \leq \underbrace{O(h^2)}_{\text{truncation error}} + \underbrace{O\left(\frac{\epsilon}{h}\right)}_{\text{round-off error}}$$

$\underbrace{\hspace{100px}}_{\text{2nd order approximation error}}$

Just like before, h must be chosen to balance these terms:

$$\Rightarrow h^2 \sim \frac{\epsilon}{h}$$

$$\Rightarrow h \sim \epsilon^{1/3} \quad \text{in order to minimize this total error.}$$

So if $h \sim 10^{-5}$, then the total error is

$$\begin{aligned} O(h^2) + O\left(\frac{\epsilon}{h}\right) &\sim 10^{-10} + \frac{10^{-16}}{10^{-5}} \\ &\sim 10^{-10} + 10^{-11} \\ &\sim 10^{-10} \end{aligned}$$

Richardson Extrapolation

What if we compute $f'(x) \approx \frac{f(x+h) - f(x-h)}{2h} = \phi_0(h)$

for several values of h ? Can we use this estimate to get a better estimate of $f'(x)$?

(Ignore round-off error for now).

The centered difference approximation is 2nd-order accurate:

$$\frac{f(x+h) - f(x-h)}{2h} = \phi_0(h) = f'(x) + \frac{h^2}{6} f^{(3)}(x) + O(h^4)$$

$$\text{Compute } \phi_0\left(\frac{h}{2}\right) = f'(x) + \frac{1}{6} \left(\frac{h}{2}\right)^2 f^{(3)}(x) + O(h^4)$$

$$= f'(x) + \frac{1}{6} \frac{1}{4} h^2 f^{(3)}(x) + O(h^4)$$

Can we take a linear combination of $\varphi_0(h)$ and $\varphi_0(\frac{h}{2})$ to kill the $\mathcal{O}(h^2)$ term?

$$\begin{aligned} 4 \cdot \varphi_0(\frac{h}{2}) - \varphi_0(h) &= 4f'(x) + \frac{1}{6}h^2 f^{(3)}(x) + \mathcal{O}(h^4) - f'(x) - \frac{1}{6}h^2 f^{(3)}(x) - \mathcal{O}(h^4) \\ &= 3f'(x) + \mathcal{O}(h^4) \end{aligned}$$

$$\Rightarrow f'(x) = \frac{4 \cdot \varphi_0(\frac{h}{2}) - \varphi_0(h)}{3} + \mathcal{O}(h^4)$$

4th order approximation to $f'(x)$.

We only used two 2nd order approximations to obtain a 4th order one.

If the round off error in ~~(xxx)~~ is $\mathcal{O}(\frac{\epsilon}{h})$, then h must be chosen to balance $h^4 \sim \frac{\epsilon}{h}$

$$\Rightarrow h \sim \underbrace{\epsilon^{1/5}}_{\sim 10^{-3}} \text{ minimizes the total error}$$

$$= \mathcal{O}(h^4) + \mathcal{O}(\frac{\epsilon}{h}) \sim 10^{-12} + \frac{10^{-16}}{10^{-3}} \sim \underline{10^{-12}}$$

Richardson extrapolation can be repeated several times:

$$\varphi_1(h) = \frac{4 \varphi_0(\frac{h}{2}) - \varphi_0(h)}{3} = f'(x) + \mathcal{O}(h^4)$$

$$\varphi_1(\frac{h}{2}) = \frac{4 \varphi_0(\frac{h}{4}) - \varphi_0(\frac{h}{2})}{3} = f'(x) + \mathcal{O}(\frac{h^4}{16})$$

$$\Rightarrow \frac{16 \varphi_1(\frac{h}{2}) - \varphi_1(h)}{15} = f'(x) + \mathcal{O}(h^6)$$

these truncation errors are specific to the original centered difference formula.