

That was for vectors - how about for matrices?

Def: Matrix norm $\|A\|$: (same rules!)

(1) $\|A\| \geq 0$

(2) $\|\alpha A\| = |\alpha| \|A\|$

(3) $\|A+B\| \leq \|A\| + \|B\|$

[(4) $\|AB\| \leq \|A\| \cdot \|B\|$ (sometimes)]

If $\|\underline{u}\|$ is any norm on a vector, then the induced

matrix norm is:

$$\|A\| = \max_{\|\underline{u}\|=1} \|A\underline{u}\| = \max \frac{\|A\underline{u}\|}{\|\underline{u}\|}$$

\Rightarrow For any $\|\underline{u}\|$, $\|A\underline{u}\| \leq \|A\| \|\underline{u}\|$.

Thm: If $\|\underline{u}\| = \|\underline{u}\|_1 = \sum |u_i|$ then the induced

norm on ~~A~~ on matrix is:

$$\|A\| = \max_{j=1, \dots, n} \sum_{i=1}^m |a_{ij}| \quad \left(\begin{array}{l} \text{max over columns} \\ \text{sum over rows} \end{array} \right)$$

Pf: $\|A\underline{u}\| = \|\sum \underline{a}_j u_j\| \leq \sum \|\underline{a}_j\| |u_j| \leq \max \|\underline{a}_j\| \sum |u_j|$
 $= \max \|\underline{a}_j\| \|\underline{u}\|$

But $\underline{u} = \begin{pmatrix} 1 \\ 0 \\ \vdots \end{pmatrix} \Rightarrow \max \|\underline{a}_j\| \geq \|A\| \quad \square$

Alternatively:

$$\underline{\text{Thm}} \quad \|A\|_{\infty} = \max_{i=1, \dots, m} \sum_{j=1}^n |a_{ij}|$$

$$\underline{\text{Pf:}} \quad \|A\underline{u}\|_{\infty} = \max_{i=1, \dots, m} |(A\underline{u})_i| = \max_i \left| \sum_j a_{ij} u_j \right|$$

$$\leq \max_i \sum_j |a_{ij}| |u_j|$$

$$\leq \max_i \left(\max_j |u_j| \right) \sum_j |a_{ij}|$$

$$= \|\underline{u}\|_{\infty} \max_i \sum_j |a_{ij}|$$

\Leftarrow set $\underline{u} = \underline{1}$ to pick out maximal row.

Lastly, and most commonly used:

$$\underline{\text{Thm}} \quad \|A\|_2 = \sqrt{\max_j \lambda_j} \quad \text{of } A^t A$$

$$\underline{\text{Pf}} \quad \|A\underline{u}\|_2^2 = (A\underline{u}, A\underline{u}) = (\underline{u}, A^t A \underline{u})$$

$A^t A$ is SPD, and has real eigenvalues

$$\Rightarrow \text{diagonalizable} \Rightarrow (\underline{u}, P D P^t \underline{u})$$

$$= (P^t \underline{u}, D P^t \underline{u})$$

$$\max_{\underline{u}} (P^t \underline{u}, D P^t \underline{u}) = \max_{\underline{v}} (\underline{v}, D \underline{v}) = \text{largest eigenvalue.}$$

Condition number of a problem

\Rightarrow The sensitivity of the "problem" ~~to~~ at the solution.

Ex: For a function $y = f(x)$, how sensitive is

y to x ? ~~smaller estimate is the better~~

(The "problem" is computing $f(x)$.)

① In an absolute sense:

$$|y - y'| \approx \underbrace{C(x)}_{\text{absolute condition number}} |x - x'|$$

$$\Rightarrow C(x) \approx \frac{|y - y'|}{|x - x'|}$$

$$= \frac{|f(x) - f(x')|}{|x - x'|} \quad \text{for } x' \text{ close to } x,$$

$$C(x) \approx |f'(x)|.$$

② In a relative sense:

$$\frac{|x - x'|}{|x|} = \text{relative error}$$

$$\frac{|y' - y|}{|y|} \approx K(x) \left| \frac{x' - x}{x} \right|$$

$$\Rightarrow K(x) \approx \left| \frac{y' - y}{y} \right| \left| \frac{x}{x' - x} \right|$$

$$= \left| \frac{f'(x) - f(x)}{x' - x} \right| \left| \frac{x}{y} \right| = \left| \frac{x f'(x)}{f(x)} \right|$$

Ex: Let $y = x^{\frac{1}{3}} = f'(x)$

$$C(x) = \frac{1}{3} x^{-\frac{2}{3}}$$

$$K(x) = \frac{x f'(x)}{f(x)} = \frac{x \cdot \frac{1}{3} \cdot x^{-\frac{2}{3}}}{x^{\frac{1}{3}}} = \frac{\frac{1}{3} x^{\frac{1}{3}}}{x^{\frac{1}{3}}} = \frac{1}{3}$$

$$C(x) = \frac{1}{3} \frac{1}{x^{\frac{2}{3}}} < \infty \text{ for } x \text{ away from } 0$$



$K(x)$ is small everywhere

$$\begin{aligned} f(x+\epsilon) &\approx f(x) + f'(x)\epsilon \\ &\approx f(x) + \frac{1}{3} x^{-\frac{2}{3}} \epsilon \end{aligned}$$

$$\Rightarrow |f(x+\epsilon) - f(x)| \approx \frac{1}{3} x^{-\frac{2}{3}} \epsilon$$

large for x near 0.