

Last timeMethods for finding a single λ, \underline{v} pair

$$A\underline{v} = \lambda\underline{v}$$

① Power Method

② Power Method with shift

③ Inverse Power Method With Shift

↙

$$\text{If } A\underline{v} = \lambda\underline{v}, \text{ then } (A - sI)^{-1}\underline{v} = \frac{1}{\lambda - s}\underline{v}$$

with proper choice of s , this eigenpair can be made to dominate the spectrum of

$$(A - sI)^{-1}$$

⇒ Each iteration of $(A - sI)^{-1}$ requires a "solve", or computation explicitly

Jacobi's Method

The power method and inverse power method only compute eigenpairs one at a time.

Note: The matrices A and $B = \underbrace{M^{-1}AM}_{\text{similarity transform}}$ have the same eigenvalues.

Pf: Look at their characteristic polynomials.

If M is chosen to be the matrix of eigenvectors, then B is diagonal with λ_i on the diagonal.

Ex: Let A be a ^{real} symmetric 2×2 matrix.

$$A = \begin{pmatrix} a & b \\ b & d \end{pmatrix}$$

Then its eigenvalues are real, and it is diagonalized by an orthogonal matrix V .

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All 2×2 orthogonal matrices can be parameterized as:

$$V = \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix} \quad \begin{pmatrix} 2 \times 2 \text{ rotation} \\ \text{matrix} \end{pmatrix}.$$

Then we want

$$V^T A V = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$$

The two equations for the 12 and 21 entries are:

$$\begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} \begin{pmatrix} a & b \\ b & d \end{pmatrix} \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}.$$

$$\begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} \begin{pmatrix} a \cos \varphi - b \sin \varphi & a \sin \varphi + b \cos \varphi \\ b \cos \varphi - d \sin \varphi & b \sin \varphi + d \cos \varphi \end{pmatrix}$$

$$\Rightarrow \begin{aligned} a \cos \varphi \sin \varphi + b \cos^2 \varphi - b \sin^2 \varphi - d \cos \varphi \sin \varphi &= 0 \\ a \cos \varphi \sin \varphi - b \sin^2 \varphi + b \cos^2 \varphi - d \cos \varphi \sin \varphi &= 0 \quad \checkmark \end{aligned}$$

How do we find φ ?

$$(a-d) \cos\varphi \sin\varphi + b(\cos^2\varphi - \sin^2\varphi) = 0$$

$$\Rightarrow (a-d) \frac{1}{2} \sin 2\varphi + b \cos 2\varphi = 0$$

$$\Rightarrow \tan 2\varphi = \frac{2b}{d-a}$$

$$\Rightarrow \varphi = \frac{1}{2} \operatorname{atan}\left(\frac{2b}{d-a}\right) \quad \left(\begin{array}{l} \text{in Fortran / C use} \\ \text{the function atan2(y,x).} \end{array} \right)$$

The Jacobi Method

Define $R^{pq}(\varphi) =$

$$\begin{array}{l} \text{row } p \rightarrow \\ \text{row } q \rightarrow \end{array} \left(\begin{array}{cccc} 1 & & & \\ & \dots & & \\ & \cos\varphi & & \sin\varphi \\ & & \dots & \\ & -\sin\varphi & & \cos\varphi \\ & & & \dots \\ & & & & 1 \end{array} \right)$$

$R^{pq}(\varphi)$ can be used to set the pq and qp elements of A to zero
 real symmetric.

① Set $A^{(0)} = A$

② Find pq element in $A^{(k)}$ with maximum abs.

③ Compute $\phi_k = \frac{1}{2} \operatorname{atan} \left(\frac{2a_{pq}^{(k)}}{a_{qq}^{(k)} - a_{pp}^{(k)}} \right)$

④ Set $A^{(k+1)} = R^{pq}(\phi_k)^T A^{(k)} R^{pq}(\phi_k)$

Continue until all $|a_{pq}^{(k)}| < \epsilon, p \neq q.$

Then $A^{(k)} \rightarrow \begin{pmatrix} \lambda_1 & & \\ & \dots & \\ & & \lambda_n \end{pmatrix}$

$R^{(k)} = R(\phi_1) \dots R(\phi_k) \rightarrow (\hat{v}_1 \dots \hat{v}_n)$

~~What can we say about convergence of Jacobi's method?~~

What can we say about convergence of Jacobi's Method?

Basically, we want to show that the off-diagonal elements go to zero. First, a Lemma.

Lemma: If R is an orthogonal transform,

then $\|A\|_F = \|R^T A R\|_F$.

↖ Frobenius norm.

$$\|A\|_F = \left(\sum_i \sum_j |a_{ij}|^2 \right)^{1/2}$$

Pf: ~~A and B~~

If $B = R^T A R$, then A and B have the same eigenvalues. $B^2 = (R^T A R)(R^T A R) = R^T A^2 R$.

So A^2 and B^2 have the same eigenvalues, therefore

$$\text{trace}(A^2) = \text{trace}(B^2)$$

But $\|A\|_F^2 = \text{trace}(A^T A) = \text{trace}(A^2) = \text{trace}(B^2) = \|B\|_F^2$.

Next, let's split the Frobenius norm into 2 pieces:

$$\text{call: } \|A\|_F^2 = S(A) = \sum_{i,j} |a_{ij}|^2$$

$$D(A) = \sum_i |a_{ii}|^2 \quad \text{diagonal part}$$

$$L(A) = \sum_{i \neq j} |a_{ij}|^2 \quad \text{off diagonal part}$$

$$\Rightarrow S(A) = D(A) + L(A) = \|A\|_F^2$$

Theorem Let $A^{(k)}$ be the iterates in the classical Jacobi method. Then

$$\lim_{k \rightarrow \infty} L(A^{(k)}) = 0$$

$$\lim_{k \rightarrow \infty} D(A^{(k)}) = \text{trace}(A^2).$$

Proof: Let a_{pq} be element of A with largest abs.

$$\text{Let } B = R^p(\varphi)^T A R^p(\varphi).$$

$$\text{Then } \begin{pmatrix} b_{pp} & b_{pq} \\ b_{qp} & b_{qq} \end{pmatrix} = \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix}^T \begin{pmatrix} a_{pp} & a_{pq} \\ a_{qp} & a_{qq} \end{pmatrix} \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix}$$

$$\text{and } b_{pq} = b_{qp} = 0.$$

$$\text{But from Lemma, } b_{pp}^2 + b_{qq}^2 = a_{pp}^2 + a_{qq}^2 + 2a_{pq}^2.$$

$$\text{Furthermore, } S(B) = D(B) + L(B)$$

$$= S(A)$$

$$= D(A) + L(A)$$

B has the same diagonal elements of A , except

$$\text{for } b_{pp} \text{ and } b_{qq}, \text{ so } D(B) = D(A) + 2a_{pq}^2$$

$$\Rightarrow L(B) = L(A) - 2a_{pq}^2.$$

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Since a_{pq} was the largest off diagonal element of A , $L(A) \leq n(n-1)a_{pq}^2$.

$$\Leftrightarrow a_{pq}^2 \geq \frac{L(A)}{n(n-1)}.$$

Therefore,

$$\begin{aligned} L(B) &= L(A) - 2a_{pq}^2 \\ &\leq L(A) - 2 \frac{L(A)}{n(n-1)} \\ &= L(A) \left(1 - \frac{2}{n(n-1)} \right) \end{aligned}$$

Re-labeling, $A^{(1)} = B$, we have that
 $A^{(0)} = A$

$$L(A^{(1)}) \leq \underbrace{\left(1 - \frac{2}{n(n-1)} \right)}_{< 1} L(A^{(0)})$$

$$\Rightarrow L(A^{(k+1)}) \leq \left(1 - \frac{2}{n(n-1)} \right)^k L(A^{(0)})$$

$\rightarrow 0$ as $k \rightarrow \infty$.

And since $S(A^{(k)}) = D(A^{(k)}) + L(A^{(k)})$
 $= \text{trace}(A^2),$

~~so~~ $L(A^{(k)}) \rightarrow 0$ we have that

$$\lim_{k \rightarrow \infty} D(A^{(k)}) = \text{trace}(A^2).$$

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What guarantees that

$$\lim_{k \rightarrow \infty} D(A^{(k)}) = \text{trace}(A^2)$$

implies that $A^{(k)} \rightarrow \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}$?

Idea Apply the Gerschgorin Theorem.

~~Since~~ $A^{(k)}$ and A have the same eigenvalues, and $L(A^{(k)}) \rightarrow 0$, the Gerschgorin disks of $A^{(k)}$ have radii going to 0 as well. Therefore, the eigenvalues of $A^{(k)}$, and therefore A , are on the limit of the diagonal of $A^{(k)}$.