

Computational Statistics

Dec 01, 2021

Let \hat{f} be the kernel density estimator:

Then Let $R(x) = E((f(x) - \hat{f}(x))^2)$ be the risk at x . Then

$$R(x) = \frac{1}{4} \sigma_k^4 h^4 f''(x)^2 + \frac{f(x)}{nh} \int K^2(x) dx + o\left(\frac{1}{n}\right) + o(h^6).$$

Proof: $E(\hat{f}(x)) = E\left(\frac{1}{n} \sum_i \frac{1}{h} K\left(\frac{x-x_i}{h}\right)\right)$

$$= E\left(\frac{1}{h} K\left(\frac{x-x_i}{h}\right)\right)$$

$$= \frac{1}{h} \int K\left(\frac{x-t}{h}\right) f(t) dt$$

$$= \int K(u) f(x-hu) du \quad , \quad \text{expand } f \text{ around } hu=0.$$

$$= \int K(u) \left(f(x) - hu f'(x) + \frac{h^2 u^2}{2} f''(x) + \dots \right) du$$

$$= f(x) + \frac{1}{2} h^2 f''(x) \underbrace{\int u^2 K(u) du}_{\sigma_k^2} + \dots$$

assuming K is even.

$$\Rightarrow \text{bias} = E(\hat{f}(x) - f(x)) = \frac{1}{2} h^2 \sigma_k^2 f''(x) + o(h^4)$$

$$\text{Similarly, } \text{var}(\hat{f}(x)) = \frac{f(x)}{nh} \int K^2(u) du + o\left(\frac{1}{n}\right).$$

$$\Rightarrow R = \text{bias}^2 + \text{variance}$$

□

Then for the optimal bandwidth,

$$\text{soln. } \frac{dR}{dh} = 0 \quad \Rightarrow \quad h \sim \frac{\sigma_k^2}{n^{1/5}}$$

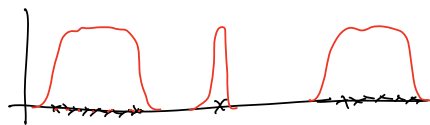
$$\Rightarrow R \sim \mathcal{O}\left(\frac{1}{n^{4/5}}\right)$$

vs for the histogram $\cdot R \sim \mathcal{O}\left(\frac{1}{n^{2/3}}\right)$

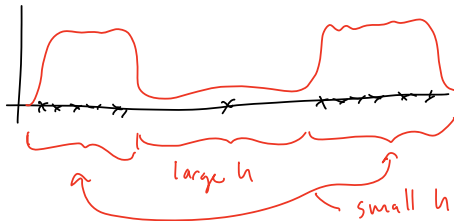
Note Assuming only that $\int (f'')^2 < \infty$, the rate of $\frac{1}{n^{4/5}}$ is the best that can be obtained

Adaptive Methods Choose h locally depending on clustering of data and other considerations.

Ex:



uniformly
small h



Multivariate Version

Same mathematical idea as in the one-dimensional case.

One option is to use what is known as a product kernel =

$$K_h^d(\underbrace{x_1, \dots, x_d}_x) = \prod_{j=1}^d \frac{1}{h_j} K\left(\frac{x_j - x_j'}{h_j}\right)$$

K_h^d must satisfy
kernel properties.

$$\begin{aligned} \text{then } \hat{f}(\vec{x}) &= \frac{1}{n} \sum_{i=1}^n K_h^d(\vec{x} - \vec{x}_i) \\ &= \frac{1}{n} \sum_{i=1}^n \prod_{j=1}^d \frac{1}{h_j} K\left(\frac{x_j - x_{ij}}{h_j}\right) \end{aligned}$$

Risk can be estimated in the same way using multivariable Taylor series for f .

Curse of Dimensionality

If we want the risk $R \sim 0.1$ at $\vec{x} = 0$ for $f \sim \text{Normal}(0,1) \in \mathbb{R}^d$, using the optimal bandwidth then $n \sim c^d$:

d	n
1	4
2	19
4	223
8	43,700
9	187,000
10	842,000

Resampling Techniques

First: Empirical distribution function

Let x_1, \dots, x_n be samples from some unknown distribution F .

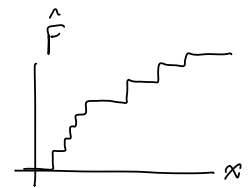
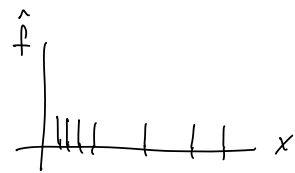
Then \hat{f}_n , \hat{F}_n are the empirical PDF and CDF:

$$\hat{f}_n(x) = \begin{cases} \frac{1}{n} & , \text{ if } x = x_i \text{ (assume } x_i \neq x_j \text{ if } i \neq j) \\ 0 & , \text{ otherwise} \end{cases}$$

And then
$$\hat{F}(x) = \int_{-\infty}^x \hat{f}(x) dx$$

$$= \int_{-\infty}^x d\hat{F}(x)$$

$$= \frac{m}{n} \quad \text{where } m = \# x_i \leq x.$$



Ex: If $\hat{X} \sim \hat{F}$, then $E(\hat{X}) = \int x d\hat{F}(x) = \sum_{i=1}^n x_i \frac{1}{n}$

The Jackknife

Goal: Partition observations in order to estimate properties of an estimator.

Suppose we have a random sample y_1, \dots, y_n , and we compute a statistic $T = T(y_1, \dots, y_n)$ to estimate θ , a parameter. (E.g. $T = \frac{1}{n} \sum y_i$, $\approx E(Y) = \theta$).

(1) Partition data set into r groups, each of size k ($n = kr$).

(2) Remove j^{th} group and re-compute the estimator from the remaining samples: call it $T_{(-j)}$

E.g. $T_{(-j)} = \frac{1}{n-k} \sum y_{i \neq j}$

T and $T_{(-j)}$ will have similar properties: bias, etc.

Another estimate for θ is the average of the $T_{(-j)}$'s:

$$\hat{\theta} = \overline{T_{(-j)}} = \frac{1}{r} \sum_{j=1}^r T_{(-j)}$$

Why do this? The original T gives only one value, and therefore $\text{Var}(T)$ can be hard to estimate. By subsampling, we are generating approximate samples and can compute sample variances.

Consider: the weighted difference:

$$T_j^* = rT - (r-1)T_{(-j)}$$

↑
pseudovalues

The "jackknifed" T is then

$$\begin{aligned} J(T) &= \frac{1}{r} \sum_{j=1}^r T_j^* \\ &= \bar{T}^* \end{aligned}$$

Often it is optimal to take $k=1$ and $r=n$ (similar to leave-one-out cross validation)

Variance Estimation

The T_j^* 's are not independent, but if we treat them independently we can use $\text{Var}(J(T))$ as an estimate for $\text{var}(T)$:

$$\hat{\text{var}}(J(T)) = \frac{1}{r(r-1)} \underbrace{\sum_{j=1}^r (T_j^* - J(T))^2}_{\text{sample variance}}$$

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Bias Correction

Recall the bias of an estimator is

$$\text{bias}(T) = E(T) - \theta \quad (*)$$

Assume this can be written as

$$\begin{aligned} &= \sum_{q=1}^{\infty} \frac{a_q}{n^q} && \left(\text{constant bias can be easily fixed} \right) \\ &= \frac{a_1}{n} + \frac{a_2}{n^2} + \dots \end{aligned}$$

What is the bias of $J(T)$ if $(*)$ is true? (assume $k=1$)

$$\begin{aligned} \text{Bias}(J(T)) &= E(J(T)) - \theta \\ &= n(E(T) - \theta) - \frac{n-1}{n} \sum_{j=1}^n E(T_{(j)} - \theta) \\ &= n \sum_1^{\infty} \frac{a_q}{n^q} - (n-1) \sum_1^{\infty} \frac{a_q}{(n-1)^q} \\ &= a_2 \left(\frac{1}{n} - \frac{1}{n-1} \right) + a_3 \left(\frac{1}{n^2} - \frac{1}{(n-1)^2} \right) + \dots \\ &= -a_2 \left(\frac{1}{n(n-1)} \right) + \dots = O\left(\frac{1}{n^2}\right) \quad \text{A reduction!} \end{aligned}$$

Bootstrap (Ch 13 in Gentle)

Goal: Estimate standard errors and confidence sets for statistics.

Outline: Given $X_1, \dots, X_n \sim F$, statistic $T = g(X_1, \dots, X_n)$,
want $\text{Var}_F(T)$.
↪ dependence on unknown distribution F .

Ex: $T = \bar{X}$

$$\text{Var}_F = \frac{\sigma^2}{n}$$

if $\text{var} X_i = \sigma^2$

$$= \int (x - \mu)^2 dF(x)$$

↙ function of F .

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The idea of the bootstrap:

① Estimate $\text{Var}_F(T)$ with $\text{Var}_F(T)$.

② Use simulation to approximate $\text{Var}_F(T)$.

In this example, step 2 is not needed because

$$\text{Var}_F(T) = \frac{\hat{\sigma}^2}{n} \quad \text{when} \quad \sigma^2 = \frac{1}{n} \sum (X_i - \bar{X})^2.$$

What is simulation? Drawing samples from some distribution, and computing averages.

Ex: Draw Y_1, \dots, Y_m from a distribution G , by the law of large numbers

$$\bar{Y} = \frac{1}{m} \sum_{j=1}^m Y_j \xrightarrow{\mathbb{P}} \mathbb{E}(Y) = \int y dG(y) \quad \text{as } m \rightarrow \infty.$$

Choosing m large enough means that $\bar{Y} \approx \mathbb{E}(Y)$, use this as an estimate for $\mathbb{E}(Y)$.

Also if h is some function with $\int h(y) dy < \infty$,

$$\text{then} \quad \frac{1}{m} \sum h(Y_j) \xrightarrow{\mathbb{P}} \mathbb{E}(h(Y)) = \int h(y) dG(y).$$

$$\begin{aligned} \text{Ex:} \quad \frac{1}{m} \sum (Y_i - \bar{Y})^2 &= \frac{1}{m} \sum Y_i^2 - \left(\frac{1}{m} \sum Y_i \right)^2 \\ &\xrightarrow{\mathbb{P}} \int y^2 dG(y) - \left(\int y dG(y) \right)^2 \\ &= \text{Var}(Y). \end{aligned}$$

Bootstrap Variance Estimate

If we have data X_i , but F is unknown, then estimate F with \hat{F} , and draw from \hat{F} .

\Rightarrow Draw X_1^*, \dots, X_n^* from X_1, \dots, X_n with replacement.

\Rightarrow Compute $T^* = g(X_1^*, \dots, X_n^*)$

Note Some of the X_i^* will be duplicates.

Variance Algorithm

DO $i = 1, \dots, m$

Draw X_1^*, \dots, X_n^* from \hat{F}

Compute $T_i^* = g(X_1^*, \dots, X_n^*)$

$$\text{COMPUTE } v_{\text{boot}} = \frac{1}{m} \sum_{j=1}^m (T_j^* - \bar{T}^*)^2$$

\uparrow
bootstrap estimate
of the variance

$$\Rightarrow \hat{se} = \sqrt{v_{\text{boot}}}$$

We can use exactly the same algorithm to estimate the variance of median, mode, or any other integrable statistic. $\int g < \infty$.

Bootstrap Confidence Intervals

Method 1 If T is approximately normal, e.g. an MLE, the T^* is also approximately normal (and so is v_{boot})

\Rightarrow a $1-\alpha$ confidence interval for T is :

$$CI = \left(\underset{\substack{\uparrow \\ \text{actual } T \\ \text{from data}}}{T} - z_{\alpha/2} \hat{se}_{boot}, T + z_{\alpha/2} \hat{se}_{boot} \right)$$

$\nwarrow \sqrt{v_{boot}}$

Method 3 Percentile Intervals (obvious idea)

Generate T_1^*, \dots, T_m^* using simulation,

and let $T_{\alpha/2}^*$ be the $\alpha/2$ percentile from T_1^*, \dots, T_m^*

$$\Rightarrow CI = \left(T_{\alpha/2}^*, T_{1-\alpha/2}^* \right)$$

Requires some justification, see appendix.