

Moment generating Function:

For a random variable X ,

$$M_x(t) = E[e^{tx}]$$

$$= \int_a^b e^{tx} f(x) dx = \int_{-\infty}^{\infty} e^{tx} f(x) \underset{\substack{\downarrow \\ \text{Indicator}}}{\mathbb{1}_D}(x) dx$$

Compare with the Laplace Transform:

$$\mathcal{L}f(s) = \int_0^{\infty} e^{-st} f(t) dt$$

$$\Rightarrow M(0) = \int e^0 f(x) dx = 1$$

$$M'(t) = \int x e^{tx} f(x) dx$$

$$M'(0) = \int x f(x) dx = E[X].$$

$$M^{(n)}(0) = \int x^n f(x) dx$$

$$= E[X^n].$$

$$\varphi_x(t) = E[e^{itx}]$$

$$\overset{\uparrow}{=} \int e^{itx} f(x) dx \quad \text{Fourier transform of } f$$

Characteristic function.

If X, Y are independent, then for $Z = X + Y$

$$\begin{aligned}
 \Rightarrow M_Z(t) &= E[e^{tZ}] \\
 &= E[e^{t(X+Y)}] \\
 &= E[e^{tX} e^{tY}] \\
 &= \iint e^{tx} e^{ty} f(x,y) dx dy \\
 &= \iint e^{tx} e^{ty} \underbrace{f_x(x) f_y(y)}_{\text{---}} dx dy \\
 &= M_X(t) M_Y(t).
 \end{aligned}$$

Multivariate Normal Random Variables

Z_1, \dots, Z_n are $N(0,1)$ and independent:

$$\vec{X} = \begin{pmatrix} X_1 \\ \vdots \\ X_m \end{pmatrix} = A \vec{Z} + \vec{\mu} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ \vdots & \ddots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix} \begin{pmatrix} Z_1 \\ \vdots \\ Z_n \end{pmatrix} + \begin{pmatrix} \mu_1 \\ \vdots \\ \mu_m \end{pmatrix}.$$

$$X_j \sim N(\mu_j, \sum_{k=1}^n a_{jk}^2)$$

Normal random variables
are invariant under affine
transformations.

Since the Z_j 's were independent, they are also uncorrelated: $\text{Cov}(Z_j, Z_k) = 0$ if $j \neq k$.

$$\begin{aligned} \Rightarrow \text{Cov}(X_i, X_j) &= \text{Cov}\left(\mu_i + \sum_k a_{ik} Z_k, \mu_j + \sum_{k'} a_{jk'} Z_{k'}\right) \\ &= E\left[\left(\sum_k a_{ik} Z_k\right)\left(\sum_{k'} a_{jk'} Z_{k'}\right)\right] \\ &= E\left[\sum_{k, k'} a_{ik} a_{jk'} Z_k Z_{k'}\right] \\ &= \sum_{k, k'} a_{ik} a_{jk'} E[Z_k Z_{k'}] \\ &= \sum_k a_{ik} a_{jk} \end{aligned}$$

If $C = A A^T$

then $\quad = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & & a_{mn} \end{pmatrix} \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}$

$$C_{ij} = \sum_k a_{ik} a_{jk} \quad \leftarrow \text{Cov of } X_i, X_j$$

Covariance matrix of $\begin{matrix} X_1 \\ \vdots \\ X_m \end{matrix}$

- C is $m \times m$
- is symmetric
- semi-positive definite

The joint pdf of X_1, \dots, X_m

$$\Rightarrow f(x_1, \dots, x_m) = \frac{1}{(2\pi)^{m/2} \sqrt{\det C}} e^{-\frac{1}{2}(\vec{x} - \vec{\mu})^T C^{-1} (\vec{x} - \vec{\mu})}$$

Let $m = n$.

pdf for Z_1, \dots, Z_m .

$$f(z_1, \dots, z_m) = f(z_1) \dots f(z_m)$$

$$= \frac{1}{(2\pi)^{m/2}} e^{-\frac{1}{2}(z_1^2 + z_2^2 + \dots + z_m^2)}$$

$$= \frac{1}{(2\pi)^{m/2}} e^{-\frac{1}{2} \vec{z}^T \vec{z}}$$

$$\int_S \frac{1}{(2\pi)^{m/2}} e^{-\frac{1}{2} \vec{z}^T \vec{z}} dz_1 \dots dz_m$$

$$\text{Let } \vec{z} = A^{-1} \vec{x}$$

$$A \vec{z} = \vec{x}$$

$$\text{and } \vec{z}^T \vec{z} = \vec{x}^T C^{-1} \vec{x}$$

$$= \vec{x}^T (A^T C^{-1})^{-1} \vec{x}$$

$$= \vec{x}^T A^T A^{-1} \vec{x}$$

$$= (\vec{A} \vec{x})^T (\vec{A} \vec{x})$$