Concerted effort of centrosomal and Golgiderived microtubules is required for proper Golgi complex assembly but not for maintenance

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ABSTRACT Assembly of an integral Golgi complex is driven by microtubule (MT)-dependent transport. Conversely, the Golgi itself functions as an unconventional MT-organizing center (MTOC). This raises the question of whether Golgi assembly requires centrosomal MTs or can be self-organized, relying on its own MTOC activity. The computational model presented here predicts that each MT population is capable of gathering Golgi stacks but not of establishing Golgi complex integrity or polarity. In contrast, the concerted effort of two MT populations would assemble an integral, polarized Golgi complex. Indeed, while laser ablation of the centrosome did not alter already-formed Golgi complexes, acentrosomal cells fail to reassemble an integral complex upon nocodazole washout. Moreover, polarity of post-Golgi trafficking was compromised under these conditions, leading to strong deficiency in polarized cell migration. Our data indicate that centrosomal MTs complement Golgi self-organization for proper Golgi assembly and motile-cell polarization.

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INTRODUCTION

The Golgi complex in the majority of interphase mammalian cells is present as a single organelle that supports integrated protein processing and sorting (Burkhardt, 1998; Thyberg and Moskalewski, 1999; Mironov and Beznoussenko, 2010; Lowe, 2011). When the cell enters mitosis, the Golgi breaks down and subsequent daughter cells generate this organelle anew. Golgi membranes fuse and stack into multiple ministacks throughout the cytoplasm. Thereafter these

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ministacks are transported by the molecular motor dynein along the newly emerging interphase microtubule (MT) network and assemble to form a single complex. Mechanisms responsible for proper formation and positioning of the Golgi complex are essential for the cell (Rios and Bornens, 2003; Lowe, 2011).

Several recent studies demonstrate that in mammalian cells the Golgi acts as a major MT-organizing center (MTOC) in addition to the centrosome (Chabin-Brion et al., 2001; Efimov et al., 2007; Rivero et al., 2009). Prior to this finding, it was assumed that Golgi assembly is driven by the radial MT array emanating from the centrosome (Thyberg and Moskalewski, 1999; Mironov and Beznoussenko, 2010). However, our recent analyses of Golgi-derived MTs indicated that this MT subpopulation is specifically essential for proper Golgi assembly and integrity (Miller et al., 2009). It still remains unknown whether Golgi assembly can be supported exclusively by its own MTOC activities or whether it requires centrosomal MTs. Intuitively, the radial array of MTs formed by the centrosome would provide an important spatial cue for the collection of scattered Golgi stacks in the cell center. However, it is also conceivable that Golgi self-assembly does not rely on the centrosome, as the Golgi can accumulate in the central cell area in the absence of the centrosome by a yet unclear mechanism (Tangemo et al., 2011). In this regard, noncentrosomal MTs can self-organize into

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Abbreviations used: BFA, breffeldin A; CLASP, CLIP-associated protein; DIC, differential interference contrast; EMTB, ensconsin MT-binding domain; FRAP, fluorescence recovery after photobleaching; Ig, immunoglobulin; MT, microtubule; MTOC, MT-organizing center; NA, numerical aperture; RPE1, retinal pigment epithelium 1; siRNA, small interfering RNA; TGN, *trans*-Golgi network; YFP, yellow fluorescent protein.

radial arrays in a dynein-dependent manner (Mitchison, 1992; Nedelec et al., 1997; Surrey et al., 2001; Cytrynbaum et al., 2004). Furthermore, dynein activity combined with MT nucleation on the surface of melanin granules (melanosomes) is sufficient to aggregate the melanosomes in the center of fish melanophores (Malikov et al., 2005). A similar mechanism may be sufficient for the assembly of the Golgi. However, unlike melanosomes, single Golgi stacks are structurally and functionally asymmetric (Cole et al., 1996), and the Golgi complex is not a random collection of vesicles but rather a highly organized, continuous membrane organelle (Snapp et al., 2003; Mironov and Beznoussenko, 2010). Thus, even if the self-organization mechanisms are sufficient to aggregate Golgi stacks, it is not clear whether self-organization would provide for correct positioning and subsequent fusion of the Golgi elements.

In this study, we have developed a computational model that evaluates contributions of specific MT arrays in the Golgi assembly. The model supports our previous conclusion that both MT arrays are involved in the Golgi assembly (Miller *et al.*, 2009), suggesting the concerted effort of both MT arrays bring coordination of the Golgi assembly to a new level, as neither MT array on its own provides polarity and integrity of the complex. More specifically, the model illustrates how decreased formation of Golgi-derived MTs modulates the Golgi organization and predicts an essential role of the radial centrosomal array for Golgi integrity and polarity.

Accordingly, we experimentally tested the role of the centrosomal MT array in Golgi organization and function. We used a highly focused laser beam to physically ablate the centrosome that prevents formation of the centrosomal MTs. In contrast to genetic manipulations, physical ablation of the centrosome does not affect MT nucleation at other locales (Khodjakov et al., 2000; Khodjakov and Rieder, 2001). Without the centrosome, Golgi-associated MT nucleation remains normal (Efimov et al., 2007). Unexpectedly, we find that the centrosome per se is not required for the maintenance and function of the already-assembled Golgi complex. However, the MT network in acentrosomal cells fails to correctly assemble the Golgi, which leads to inefficiency in polarized post-Golgi trafficking, as predicted by the model. Moreover, our work indicates that the role of the centrosome in the control of polarized cell migration is indirect. When the Golgi and/or Golgi-derived MT array is already assembled, ablation of the centrosome has no effect on the cell polarization and motility. However, when emerging MTs assemble the Golgi in the absence of the centrosome, the cell is incapable of polarized cell migration. These data strongly suggest that the centrosome modulates cell polarization and motility through Golgi organization and trafficking.

RESULTS

Efficient Golgi complex assembly requires two MT populations

To visualize the process of MT-dependent Golgi assembly by emerging MT network in interphase cells, we applied nocodazole washout assay. Retinal pigment epithelium 1 (RPE1) cells, which demonstrate two prominent MT arrays (that is, emanating from the Golgi and the centrosome), were cotransfected with mCherry-Rab6 as a Golgi marker and 3GFP-EMTB (ensconsin MT-binding domain) as an MT marker. If MTs are depolymerized by nocodazole, the Golgi randomly disperses in the cytoplasm (Supplemental Figure S1); however, a fully functional Golgi complex assembles within 60 min upon nocodazole washout (Miller *et al.*, 2009). After full MT depolymerization, nocodazole was removed, and the Golgi assembly was recorded (Figure 1 and Supplemental Movies S1–S6). Consistent with our previous finding (Miller *et al.*, 2009), when two types of regrowing MTs are involved (Figure 1, A–Aii, and Movie S1), Golgi ministacks are clustered together throughout the cell and at the same time, these clusters are being relocated to the cell center, resulting in the formation of an integral Golgi complex (Movie S2).

To test the role of the centrosomal MT array, we laser-ablated the centrosome in cultured RPE1 cells that stably express centrin1-GFP (Efimov et al., 2007; Uetake and Sluder, 2007; Figure S2). We have previously demonstrated that the Golgi remains fully capable of MT nucleation and organization, while centrosome-derived MTs do not form after centrosome ablation (Efimov et al., 2007). Immunofluorescence analyses of cells fixed at different time points after centrosome ablation confirmed that the MT network and the Golgi complex remained similar to control cells that contained centrosomes (Figure S2). When the centrosome was ablated in nocodazole-treated cells coexpressing mCherry-Rab6 and 3GFP-EMTB, and the drug was subsequently washed out (Figure 1, B-Bii), MTs were readily formed at dispersed Golgi stacks (Movie S3) and drove Golgi stacks together. Subsequently, the Golgi was self-organized in the perinuclear area in the absence of the centrosome (Movie S4). However, assembly appeared incomplete and morphology of the complex was aberrant, suggestive of a significant role for the centrosome in the Golgi assembly process.

The same assay was applied to cells in which Golgi-derived MTs were suppressed by CLIP-associated protein (CLASP) depletion (Figure S3) to test the involvement of the Golgi-derived MTs in Golgi assembly (Figure 1, C–Cii). In this case, MTs were formed predominantly at the centrosomes (Movie S5), and resulting Golgi integrity was diminished (Figure 1Cii and Movie S6), indicating that the centrosomal array on its own is insufficient for correct Golgi assembly. This result is consistent with our previous finding that Golgi-derived MTs are needed for Golgi assembly (Miller *et al.*, 2009).

Combined, these data suggest that de novo Golgi complex assembly requires contributions from both centrosomal and Golgiderived MTs.

Computational model supports necessity of two geometrically distinct MT populations for the assembly of integral Golgi complex

To evaluate relative significance of each type of MT in Golgi assembly, we modeled this process in silico. We used agent-based, threedimensional simulations (Alberts and Odell, 2004; Paul *et al.*, 2009) of the assembly process. The geometry and dimensions in the simulations are close to those observed. The model simulations seen in Movies S7–S10 (snapshots are depicted in Figure 2, A–C) revealed that the Golgi assembly occurs in three stages in control cells: 1) Ministacks in close proximity interact among themselves and form intermediate fragments. 2) As a result, these fragments are more frequently captured and transported by centrosomal MTs and accumulate around the centrosome. 3) In the vicinity of the centrosome, fragments interact once again to form bigger Golgi stacks. The predicted time series for the fragment numbers are in excellent agreement with the experimental data (Figure 2E).

In acentrosomal cells, assembly is almost as rapid as in control cells (Figure 2, E and F). However, acentrosomal assembly is not able to make a single complex: it creates Golgi fragments very dispersed in size (Figures 2B and S4B), unlike the uniformly large stacks that emerge in control cells (Figures 2A and S4A), so that the average radius of Golgi fragments at each time point is decreased and the spanning cluster radius is increased (Figure S5, A–C). Some smaller fragments, most notably those "behind" the nucleus, remain uncaptured in the absence of the centrosomal MT array, because the fragments at opposite sides of the nucleus do not "see"





each other. Accordingly, the compactness of the resulting complex is decreased in acentrosomal cells (Figure S5D).

In the CLASP-depleted cell, the centrosomal MTs bring many fragments to the center, but many other ministacks remain uncaptured (Figure 2C). Thus one significant function of Golgi-derived MTs in Golgi assembly is the premerging of ministacks into larger fragments that are more easily captured by the centrosomal radial array, thereby significantly accelerating the assembly (Figures 2, E and F, and S5, A and B). Moreover, the best fitting to experimental data was achieved upon assumption that centrosomal and Golgi-derived MTs were equally good at capturing, but only Golgi-derived MTs were effective at fusing, Golgi fragments. Owing to insufficient clustering and fusion, assembly in CLASP-depleted cells is inefficient (Figure S5C), and the radius of Golgi fragments remains significantly lower than in control cells. In addition, compactness of the assembly (see Supplemental Material) worsens in the CLASP-depleted cells (Figure S5D). Predicted Golgi organization reaches its steady state at 1 h of assembly and does not change after 3 h of assembly (Figure S6).

Centrosome is required for the assembly of the integral Golgi complex in nocodazole washout assay

Dynamics of the Golgi assembly were in excellent agreement with the model

frames from live-cell imaging sequence of the same cell. After complete MT depolymerization by nocodazole, Golgi marked by mCherry-Rab6 is dispersed throughout the cell (noc). After nocodazole washout, Golgi ministacks cluster all over the cell (at 11 and 27 min recovery) and at the same time are being collected in the cell center (at 27 min and 1 h, 45 min recovery). (B-Bii) Acentrosomal cell, treated as in (A). (Bi and Bii) In the absence of the centrosome, all MTs organized at initial stage of recovery (4 min) are formed at the Golgi (solid arrows). Box from (B) is enlarged in (Bi). (Bii) Selected frames from live-cell imaging sequence. After nocodazole washout, Golgi ministacks are being collected in the cell center but integral Golgi ribbon is not formed. (C-Cii) CLASPdepleted cell, treated as in (A). (Ci and Cii) MTs organized at initial stage of recovery (5 min) are predominantly centrosomal (open arrow). Golgi-derived MTs are significantly diminished (solid arrows). Box from (C) is enlarged in (Ci). (Cii) Selected frames from live-cell imaging sequence. After nocodazole washout, Golgi ministacks are being collected in the cell center without significant clustering.



FIGURE 2: In silico, both MT arrays are required for the proper Golgi assembly. (A–C) Snapshots from the simulations. Top, initial configuration; bottom, predicted state of the system after assembly for 60 min. Centrosome- and Golginucleated MTs are shown in yellow and cyan, respectively. In the control and acentrosomal cases, each initial Golgi fragment nucleates ~ 4 MTs, whereas in the CLASP-depleted case, each initial Golgi fragment nucleates ~1–2 MTs. Red/green ministack surfaces correspond to *trans/cis* sides, respectively. (A) In control, the majority of multiple Golgi fragments assemble within 60 min into the integral Golgi ribbon in the vicinity of the centrosome. It is oriented with *trans* (MT-nucleating) surface away from the nucleus. (B) Without centrosomal MTs, the majority of fragments selfassemble, albeit to a random location near the nucleus. (C) When CLASP is depleted, ministacks collected in the vicinity of the centrosome remain unfused and are randomly oriented. Many fragments remain scattered away from the centrosome after 60 min. (D) Side view of the control simulation snapshot. (E) Average number of Golgi fragments in control, CLASP-depleted, and acentrosomal cells plotted as a function of time. Solid curves: simulations; symbols: experimental data obtained from images like Figure 1, as described in the Supplemental Material. (F) Average predicted number of Golgi fragments in control, CLASP-depleted, and acentrosomal cells plotted as a function of time.

predictions (Figure 2E). Moreover, model-predicted defects of the Golgi shape and integrity in CLASP-depleted cells was supported by our previous experimental findings (Miller *et al.*, 2009).

To test the model predictions for the acentrosomal Golgi assembly, we assessed the morphological features of a Golgi complex assembled in the absence of centrosomal MTs. The Golgi was assembled upon nocodazole washout in acentrosomal cells, as described for Figure 1B. Two hours after nocodazole washout of acentrosomal cells, morphology of the Golgi complex was compared with control conditions, including untreated centrosomal cells, untreated cells lacking centrosomes, and centrosomal cells 2 h after nocodazole washout. Distribution of *cis*-Golgi (GM130, Figure 3, A–D) as well as *trans*-Golgi network (TGN; GCC185, unpublished data) Golgi markers was detected by immunofluorescence analysis. The structure of the Golgi complex assembled without the centrosome was abnormal, though the Golgi stacks were collected in the cell center (Figure 3D). Circularity and compactness parameters (see Supplemental Material) were used to quantitatively assess the structural complexity and integrity of the Golgi complex. In accordance with the model predictions, high circularity indicated randomization and low compactness reflected insufficient integrity of the Golgi ribbon assembled without centrosomal input. In contrast, morphology and quantitative parameters of the Golgi complex assembled after nocodazole washout in cells containing centrosomes (Figure 3C) were indistinguishable from the Golgi in nontreated cells (Figure 3A).

We next assessed the role of the centrosomal array in integrity of the Golgi complex by fluorescence recovery after photobleaching (FRAP) analyses of yellow fluorescent protein (YFP)-GalT dynamics (Figure 3, G–L; as in Snapp et *al.*, 2003; Miller et *al.*, 2009). Our model predicts that the Golgi complex assembled in the absence of



FIGURE 3: Golgi complex organization in centrosomal and acentrosomal cells. (A–D) The Golgi revealed by immunostaining for GM130. (A) Nontreated centrosomal cell; (B) acentrosomal cell; (C) centrosomal cell fixed 2 h after nocodazole washout; and (D) acentrosomal cell fixed 2 h after nocodazole washout. (E) Compactness of Golgi complex (percentage of space within the Golgi area occupied by GM130) in the four types of cells corresponding to (A–D). (F) Circularity [4π *(area/perimeter²)] of the Golgi complex in the four types of cells corresponding to (A–D). Data from more than three independent experiments; n = 10 for each condition. *, p < 0.05; **, p < 0.01 in unpaired Student's t test between bars marked with black and white asterisks. Error bars represent SEM. (G–L) FRAP analyses of Golgi ribbon continuity. (G–J and L) frames from live-cell imaging sequences in which YFP-GaIT was used as an integral Golgi marker. (G) Nontreated centrosomal cell; (H) centrosomal cell 2 h after nocodazole washout; (I) acentrosomal cell; (J) and (L) acentrosomal cell 2 h after nocodazole washout. For each example, a frame prior to bleaching (prebleach), after bleaching (3 s), and upon fluorescence recovery (60 s) is shown. White circles indicate bleached regions of interest. In contrast to fast recovery in (G–J), detached Golgi fragment in (L) does not recover, indicating that connection with the Golgi ribbon is lost. See also solid black line in (K). (K) Quantification of FRAP as in (G–J) and (L). Error bars represent SEM.

the centrosome consists of large clusters within which the Golgi fragments have sufficient conditions for fusion and smaller fragments that stay unassociated with large clusters. Indeed, rates of fluorescence recovery in acentrosomal cells fell into two distinct groups (Figure 3, J–L). The first group (Figure 3, J and K) did not significantly differ from the recovery rates in control centrosomal cells, either untreated or recovered after nocodazole treatment. The second group was observed in smaller Golgi fragments and was characterized by very slow recovery rates (Figure 3, K and L). Thus the large Golgi clusters presented integral Golgi ribbons, but the small fragments did not establish functional contact with the major Golgi mass. These data indicate that the centrosome supports the proper assembly of the integral Golgi complex.

Alternative mechanisms of collecting Golgi stacks in the cell center substitute for role of the centrosome in the Golgi complex integrity

Interestingly, the morphology of the existing Golgi complex was not affected by the centrosome ablation per se (Figure 3, A and B). In both centrosomal and acentrosomal cells, a typical Golgi ribbon morphology with similar circularity and compactness parameters was observed (Figure 3, E and F). Moreover, FRAP rates for acentrosomal cells with preexisting Golgi complex did not differ from control centrosomal cells (Figure 3, G–I and K), revealing that the continuity of the existing Golgi ribbon was unaltered by centrosome ablation. This result suggests the centrosome is not required for the maintenance of already-assembled Golgi complexes. According to our model, the centrosome provides the radial signal for Golgi assembly, and it is possible that Golgi-derived MTs are sufficient to support Golgi integrity when it is already collected in the cell center.

To test this possibility, we applied cold treatment that results in MT depolymerization without Golgi scattering throughout the cell (Figure S7, B and C). Cell were put on ice for 40 min and analyzed thereafter. As expected, the Golgi remained in the cell center both in centrosomal and acentrosomal cells and maintained an overall polarized shape with low circularity index (Figure 4, A-D and F). However, the Golgi ribbon was fragmented without MTs, regardless of the presence of the centrosome, indicating that Golgi integrity is MT-dependent (Figures 4E and S7C). Indeed, initial Golgi integrity was recovered upon MT regrowth both in centrosomal and acentrosomal cells. This result indicates that Golgi-derived MTs are necessary and sufficient to support Golgi ribbon continuity, as long as Golgi ministacks are collected in advance through centrosomal guidance. This result is in accordance with our computational model, which predicts that the role of the centrosome in Golgi assembly is restricted to organizing a radial array of MTs, which brings Golgi clusters to the cell center.

We were able to further test whether the radial array of MTs can perform the function of the centrosome in Golgi assembly. After 1–2 h of breffeldin A (BFA) treatment, the Golgi can no longer be detected in RPE cells (Figure S7, D and E), while the MT array is similar to those of untreated cells (Figure S7). We and others have shown previously that noncentrosomal MTs in this case can still be formed at random cytosolic sites (Efimov *et al.*, 2007; Rivero *et al.*, 2009). Interestingly, centrosome ablation, which completely abolishes new formation of centrosomal MTs (Khodjakov *et al.*, 2000; Khodjakov and Rieder, 2001), only slightly disorganizes the MT network, which remains primarily radial (Figure 4, G–I). Such organization is likely due to the high stability of MT parts in the cell center, which is evident from high tubulin acetylation levels in this area (Figure 4, G–L). We took advantage of this experimental condition to investigate efficiency of Golgi assembly in the presence of the radial MT array, but in the absence of the centrosome. Golgi complexes assembled 2 h after BFA washout demonstrate compactness and circularity parameters indistinguishable from those assembled in the presence of the centrosome in nocodazole washout experiments (Figure 4, M–P). We assume that, once stabilized, MTs in the cell center persist throughout the BFA treatment and fulfill the role of the radial MT population during Golgi assembly, while the nonradial MT population, which forms at emerging Golgi stacks, allows for ministack clustering.

Computational model predicts that collaboration of two MT populations is required for the establishment of overall Golgi polarity

Computational simulations of the Golgi assembly revealed that participation of both MT arrays in the process is critical for the resulting complex integrity and compactness. Additionally, a requirement of both arrays for overall Golgi asymmetry was revealed. In particular, the control assembly driven by collaboration of centrosomal and Golgi-derived MTs focuses the stacks in a narrow angular space, placing them exactly in front of the centrosome. In CLASP-depleted cells, this focusing is significantly impaired, and in the acentrosomal case, it is nonexistent (Figure 5, A-C), in agreement with experimental data (Figure S8). Moreover, summarized cis-trans orientation of stacks within the Golgi assembled by both MT populations is polarized, while it is random in acentrosomal or CLASP-depleted cells (Figure 2, A-C). Since Golgi-derived MTs in the model form at the trans side only, angular distribution of Golgi-derived MTs reflects polarization of the Golgi complex and is highly directional in control cells, but not when the Golgi is assembled by solely Golgi-derived or centrosomal MTs (Figure 5, D and E). Thus our model predicts that Golgi complex assembled by concerted effort of two MT arrays acquires an important property, which makes it qualitatively different from Golgi complexes assembled by either MT population alone.

Directionality of post-Golgi vesicular trafficking is disorganized in cells in which the Golgi is assembled in the absence of radial MTs

Overall polarity of the Golgi complex and directionality of MT arrays is essential for the directionality of post-Golgi trafficking, which in motile cells is necessary for directional cell migration. Our previous data (Miller et al., 2009) indicate that the model predictions for CLASP-depleted cells are correct, and polarity of both MT array and post-Golgi trafficking is lost. To evaluate model predictions for acentrosomal cells, we compared RPE1 cells in which the Golgi was assembled in the absence of the centrosome with control conditions, including untreated centrosomal cells, untreated cells lacking centrosomes, and centrosomal cells 2 h after nocodazole washout. In accordance with the model predictions, the distribution of MTs in acentrosomal cells after nocodazole washout was less polarized than in control cells or acentrosomal cells with preexisting Golgi complex (Figure 6, A-D). As post-Golgi vesicular trafficking is considered the major functional readout of the MT array directionality, we analyzed the movements of exocytic vesicles labeled with mCherry-Rab6 (Grigoriev et al., 2007). Transport of individual Rab6-marked vesicles from the Golgi toward the plasma membrane was tracked (Figure 6, E–H), and the directionality of vesicle tracks was quantified for the "forward," "rear," "left," and "right" quadrants (Figure 6I). As expected, nontreated centrosomal cells and centrosomal cells after nocodazole washout



FIGURE 4: Golgi complex organization in centrosomal and acentrosomal cells influenced by cold or BFA. (A–D), (M), and (N) the Golgi revealed by immunostaining for GM130. (A) centrosomal cell fixed after 40 min on ice; (B) acentrosomal cell fixed after 40 min on ice; (C) centrosomal cell fixed 2 h after cold treatment; and (D) acentrosomal cell fixed 2 h after cold treatment. (E) Compactness of Golgi complex (percentage of space within the Golgi area occupied by GM130) in the four types of cells corresponding to (A–D). (F) Circularity [4π *(area/perimeter²)] of the Golgi complex in the four types of cells corresponding to (A–D). Data from three independent experiments. p < 0.01 in unpaired Student's t test between bars marked with single and double asterisks; p < 0.05 between white and black asterisks. Error bars represent SEM. (G–L) MT organization in nontreated (G) and (J), BFA-treated centrosomal (H) and (K), and BFA-treated acentrosomal (I) and (L) cells. Immunostaining: (G–I) Tubulin, red; acetylated tubulin, green (far red, pseudocolored); centrin-GFP, blue (pseudocolored). (J–L) Acetylated tubulin, green (far red, pseudocolored); centrin-GFP, red (pseudocolored). Arrow, centrosome. (M) Centrosomal cell fixed 2 h after BFA washout; (D) acentrosomal cell fixed 2 h after BFA washout. (O) Compactness and (P) circularity of the Golgi complex in cells corresponding to (M–N). Data from five independent experiments. p > 0.05 in unpaired Student's t test. Error bars represent SEM.



FIGURE 5: Both centrosomal and Golgi-derived MTs are required for the proper polarization of the Golgi and MT array in silico. (A–C) Simulation results for the angular distribution of Golgi fragments before (0 min) and after (60 min) the assembly. Initially, Golgi fragments are distributed uniformly across the cell. The minimum at 270° is due to the excluded volume of the nucleus. In the control case (A), significant focusing of the Golgi density to 90° is predicted. In the acentrosomal case (B), no organization in the angular space is predicted. In the CLASP-depleted case (C), little focusing to 90° is predicted. (D) Computed angular distribution of the Golgi-derived MTs after 60 min of assembly. Ninety degrees corresponds to outward-pointing normal to the nuclear surface. Significant polarization of MTs in angular space takes place in control cell, but not in CLASP-depleted and acentrosomal cells. (E) Predicted quantitative measure of the MT array polarization calculated as defined in the Supplemental Material on modeling Golgi assembly.

exhibited polarized trafficking toward the leading edge (Figure 6, E" and G"). No changes were observed in the trafficking pattern of untreated acentrosomal cells (Figure 6F"). In contrast, polarity of post-Golgi trafficking in acentrosomal cells after nocodazole washout was significantly disturbed (Figure 6H"). In these cells, the trafficking pattern was more random, with fewer front-directed tracks (Figure 6J). Thus alteration in the trafficking directionality correlates with abnormal Golgi complex organization (Figure 3) and changes in MT distribution but not directly with the presence of the centrosome. These results are in agreement with the theoretical predictions (Figure 5).

Directionality of migration is decreased in cells in which the Golgi is assembled in the absence of radial MTs

Our demonstration that directionality of post-Golgi vesicular trafficking is affected only in cells in which the Golgi is assembled in the absence of the centrosomes allowed us to address a long-standing question of whether the centrosome is directly required for directional cell migration (Schliwa *et al.*, 1999; Etienne-Manneville, 2004; Wakida *et al.*, 2010) or whether its role is mediated by the downstream effects on Golgi organization and transport (Miller *et al.*, 2009; Yadav *et al.*, 2009; Hurtado *et al.*, 2011).

We monitored single-cell migration for centrosomal and acentrosomal cells over a 4-h period in untreated cells or in cells after nocodazole recovery, cold treatment, or BFA treatment. Total migration distance and directional persistence of migration (total migration distance divided by the length of cell migration track) were analyzed (Figure S9A). Both parameters were indistinguishable between the untreated centrosomal and acentrosomal cells, revealing that the centrosome is not required for directional migration in the presence of a functional Golgi complex (Figure 7, A and B, E and F, I, and J). The Golgi complex reorientation toward the leading edge, which is often referred to as a typical feature of directionally moving cells (Schliwa et al., 1999; Etienne-Manneville, 2004) was not altered by centrosome ablation (Figure S10). Motility of centrosomal cells released from nocodazole was similar to that of untreated controls (Figure 7, C, G, I, and J). In contrast, both the total migration distance and directional persistence of acentrosomal cells released from nocodazole were strongly decreased (Figure 7, D, H, I, and J). Thus abnormal Golgi organization and randomized post-Golgi trafficking correlate with the deficiency in directional migration.

To additionally test the motile properties of acentrosomal cells in which the Golgi was assembled in the presence of an alternative radial stimulus, we monitored the motility of cells recovered after cold or BFA treatments (Figure S11). Overall, cell motility parameters were similar to those of centrosomal cells under the same conditions. However, directional persistence of acentrosomal cell



FIGURE 6: Polarity of MTs and trafficking requires presence of the Golgi complex assembled by both MT arrays. (A and E–E") Nontreated centrosomal cell; (B and F–F") acentrosomal cell; (C and G–G") centrosomal cell 2 h after nocodazole washout; (D and H–H") acentrosomal cell 2 h after nocodazole washout. (A–D) MT organization revealed by tubulin immunostaining. Asterisks indicate leading edges. For clarity, fluorescence images are presented in inverted contrast. (E–H") Post-Golgi vesicular trafficking analyzed in live mCherry-Rab6–expressing cells. (E–H) First frames from the time-lapse movies; (E'–H') time projections of 2-min movies recorded at 1-s intervals. (E–H") Post-Golgi vesicle tracks superimposed on DIC images. Front of cell (asterisks) is designated according to the leading-edge protrusion. (I) quadrant distribution of vesicle trajectories in the experimental condition types corresponding to (E–H). (J) Percentage of front-oriented trafficking in the four experimental conditions corresponding to (E–H). n = 10, at least three independent experiments for each condition.



FIGURE 7: Migration and polarization ability of centrosomal and acentrosomal cells. (A–D) Random single-cell migration of: (A) nontreated centrosomal cell; (B) acentrosomal cell; (C) centrosomal cell starting 2 h after nocodazole washout; and (D) acentrosomal cell starting 2 h after nocodazole washout. Color-coded images depict positions of each cell at 1 h intervals. (E–H) Examples of migration trajectories (center of the nucleus) at 4-h observation periods in the four experimental conditions corresponding to (A–D). (I) Total cell migration distance and (J) directional persistence of migration in the four experimental conditions corresponding to (A–D). *, p < 0.05 in unpaired Student's t test between bars marked with black and white asterisks. Error bars represent SEM. (K–N) Distribution of protrusions during 30-min time-lapse imaging in experimental conditions corresponding to (A–D). Blue, contours of cells at the first frame of the time-lapse sequence; magenta, cell protrusions formed every 3 min throughout the time-lapse sequence. (O) Momentary polarization index in the four experimental conditions corresponding to contex corresponding to (A–D). *, p < 0.01 in unpaired Student's t test between bars marked with black and white asterisks. (P) Time taken to restore the Golgi orientation from the back to the front of migrating cells after a cell turn has turned; shown for three cellular conditions. p > 0.05 in unpaired Student's t test.

migration after cold treatment was slightly lower than in centrosomal cells (0.75 times), though significantly higher than in cells recovered after nocodazole (1.85 times). This result suggests the centrosomal MTs likely provide an additional, though minor, polarization signal that does not depend on the Golgi, or the Golgi complex recovered after cold treatment has defects in its organization that could not be detected by our analyses.

The inability of cells with an abnormal Golgi to migrate directionally may reflect defects in polarization of a cell at each particular time point (momentary polarization) or this inability may arise from frequent changes in the direction of polarized migration. To discriminate between these two possibilities, we monitored formation of the leading-edge protrusions over a 30-min period at 3-min temporal resolution and analyzed polarity of the protrusion (Figure S9B). In the directionally migrating cells with intact Golgi, protrusions formed predominantly at the leading edge (Figure 7, K–M and O). In contrast, after nocodazole washout, acentrosomal cells exhibited a random distribution of protrusions, indicating these cells lacked the ability to achieve morphological polarization (Figure 7, N and O). Thus proper organization of the Golgi and directionality of polarized trafficking is associated with momentary motile-cell polarity (Figure 7P).

DISCUSSION

Golgi assembly from the scattered ministacks is an essential process that occurs every time a cell exits mitotic division. Previously we demonstrated that Golgi-derived MTs are indispensable for the Golgi complex assembly (Miller *et al.*, 2009); this was further confirmed by a recent study (Hurtado *et al.*, 2011). Our current results reveal that the two MT arrays act in concert and are both essential for Golgi integrity and polarity.

We have shown previously that these two MT arrays are characterized by distinct geometries (Efimov *et al.*, 2007). In particular, the centrosome produces a strictly radial MT array (Bergen *et al.*, 1980; Salaycik *et al.*, 2005), Golgi-derived MTs intrinsically grow tangentially to a stack of origin, and their directions are random when ministacks are dispersed throughout the cell (Miller *et al.*, 2009). An intriguing question is whether this distinct geometry or another distinction of the two MT populations is a critical factor for their specific functions.

Our data indicate that the radial centrosomal MT array is necessary for arranging the Golgi complex organization in the course of assembly from scattered ministacks. At the same time, Golgi-derived MTs are critical for efficient Golgi fragment merging and Golgi ribbon continuity (Miller et al., 2009; Hurtado et al., 2011). Unexpectedly, the computation simulation presented here predicts that even aberrant Golgi assembly observed in CLASP-depleted cells (Miller et al., 2009) partially relies on Golgi-derived MTs formed due to incomplete CLASP depletion. The model also predicts that Golgiderived MTs support fusion of ministacks upon clustering much more efficiently than centrosomal MTs. Indeed, Golgi-derived MTs are likely biochemically different from centrosomal ones, as indicated by the enrichment of CLASPs specifically at Golgi-derived MTs (Efimov et al., 2007). This property may be important for efficient ministack coalescence at an MT and subsequent fusion. However, when only Golgi-derived MTs are present, scattered ministacks cannot be properly collected into a single integral complex. The strong centripetal signal provided by the radial centrosomal array is likely necessary to properly coalesce scattered Golgi clusters and finalize Golgi assembly. This function of the centrosomal array can be substituted by prior positioning of ministacks in the cell center (cold recovery) or by a radial array of stable MTs (BFA recovery), indicating that the centripetal signal, and not other properties of the

centrosomal array, is important for this function. We conclude that most likely both geometric and biochemical properties of Golgiderived MTs, but only geometric organization of the radial centrosomal array, are important for Golgi integrity.

We further demonstrate that the concerted effort of two MT arrays is necessary and sufficient for Golgi complex polarity. MTs assemble the Golgi complex by bringing together single Golgi stacks. cis-trans polarity of these stacks does not require MTs, as single polar stacks exist in a nocodazole-treated cell (Cole et al., 1996), can be reconstituted in a tube (Tang et al., 2008), and can emerge in the absence of the centrosome (Tangemo et al., 2011). However, our data indicate that Golgi complex collected and assembled in the absence of radial MTs lacks its overall polarity, as illustrated by observed randomization of the Golgi shape (increased circularity) and of post-Golgi trafficking directionality. Similarly, the Golgi assembled solely by centrosomal MTs lack polarity (Miller et al., 2009; Hurtado et al., 2011). Lack of polarity in a complex composed of polar stacks may arise from insufficient complex integrity and randomized mutual positioning of polar Golgi fragments within the complex. Indeed, in silico simulations predict that lack of either one of the MT arrays leads to the loss of complex polarity associated with integrity disturbance and shape randomization. Thus our results strongly indicate that neither MT subpopulation alone is capable of substituting for the concerted effort of centrosomal and Golgi-derived MTs in the Golgi assembly. We propose that mutual stack positioning requires both strong radial signal and tangential forces driving single stacks together. Interestingly, similar collaboration of centrosomal and noncentrosomal MTOCs is important for efficient mitotic spindle formation (O'Connell and Khodjakov, 2007).

Improperly assembled Golgi complex produces nondirectional post-Golgi trafficking. This may occur through loss of MT network polarity (Musch, 2004; Hoogenraad and Bradke, 2009). Decreased trafficking polarity in the absence of the centrosome correlates with the decrease in the polarity of the MT network, which in this case forms as a whole at the Golgi (Efimov et al., 2007). Golgiderived MTs are initiated at one distinct side of a Golgi stack (at the TGN, according to our data [Efimov et al., 2007], or cis-Golgi, as proposed by others [Rivero et al., 2009]). We propose that these MT nucleation sites are located randomly within the fragmented Golgi complex formed without a centrosome, leading to randomization of a normally polar Golgi-derived MT array, and subsequently, post-Golgi trafficking. Of note, endoplasmic reticulum-to-Golgi trafficking apparently can be supported by Golgiderived MTs only, since already-assembled Golgi is properly maintained in acentrosomal cells.

Interestingly, our computational model also predicts that correct assembly of the fully functional Golgi complex requires two MT arrays but not a previously proposed direct centrosome-Golgi interaction (Rios et al., 2004; Bornens, 2008; Hurtado et al., 2011). We also show that the Golgi correctly assembles without the centrosome in acentrosomal cells recovering after cold treatment. This argues that the role of the centrosome in Golgi organization is likely restricted to the role of dynein-dependent centripetal transport of scattered ministacks during the new Golgi assembly. Also, alreadyassembled Golgi is capable of maintaining polarization and integrity without the centrosome. Thus, while multifunctional Golgi matrix protein GM130 was shown to regulate the centrosomal organization and function (Kodani and Sutterlin, 2008; Kodani et al., 2009), there is likely no direct functional feedback from the centrosome to the Golgi. Our findings argue that the centrosome is not needed for Golgi organization and function when Golgi translocation to the cell center is complete.

The role of the centrosome in polarized cell motility has been intensively investigated in the last decade (Zmuda and Rivas, 1998; Etienne-Manneville, 2004; de Anda et al., 2005; Li and Gundersen, 2008). More recent study implicates mutual positioning of the centrosome and the Golgi in motile-cell polarity (Hurtado et al., 2011). Surprisingly, our results demonstrate that directional migration of cells with an alternative source of polarized MT array, such as RPEs, does not require the centrosome per se. Acentrosomal cells become depolarized and seize migration only upon nocodazole washout. Thus certain polarity cues established by the centrosome are lost during nocodazole treatment. Our data implicate proper Golgi organization as the major contributor to this mechanism, which is consistent with the fact that nonspecific Golgi dispersal prevents directional motility (Prigozhina and Waterman-Storer, 2004; Yadav et al., 2009). We propose that the centrosome supports polarized cell migration indirectly, via organizing integral Golgi complex in an MT-dependent manner. Golgi polarity, in turn, provides asymmetry of the noncentrosomal (Golgi-derived) MT array, which supports trafficking polarity as well as other asymmetric MT-dependent processes (focal adhesion disassembly, mRNA delivery, etc.). It is interesting that polarity of migration is also abolished in cell types in which MT asymmetry is lost after the centrosome ablation (Wakida et al., 2010).

Our data also indicate that additional, yet minor, Golgi-independent polarity features exist that are stable upon centrosome ablation but lost during the MT-depolymerization period. These features appear to depend directly on the centrosome, because acentrosomal cells move slightly less directionally after cold treatment than do centrosomal cells, despite their proper Golgi organization. This minor polarity regulation may be provided directly by the centrosomal MTs or through a centrosome–Golgi connection that has been proposed to play a role in cell polarity (Hurtado *et al.*, 2011). Our data also argue that this centrosome–Golgi connection is essential only temporally during the Golgi assembly phase.

To conclude, we establish in this study that the centrosomal array alone or the Golgi-derived array alone is insufficient for correct Golgi assembly from scattered ministacks. Only the concerted effort of both MT arrays results in an integral Golgi complex possessing the overall polarity necessary for polarized trafficking and cell motility.

MATERIALS AND METHODS

Computational modeling

To simulate the Golgi assembly model, we implemented time-dependent, explicit, agent-based simulations (Alberts and Odell, 2004; Paul et al., 2009). The Golgi assembly process is modeled in an oblate-spheroidal cell (Figure 2, A–D) with a spherical nucleus located nonconcentrically and a centrosome near the nuclear surface facing distal cell boundary. In the beginning of each simulation, two classes of objects-ministacks and MTs-were constructed, and their positions and sizes were then changed in the three-dimensional space according to the computational rules described below. Initially, 150-200 spherical Golgi fragments, each consisting of two hemispheres 0.2-µm in radius representing trans and cis sides, are uniformly and randomly distributed within the cell. The trans surface of each ministack nucleates 2-4 MTs in control and acentrosomal cells and 0-2 MTs in CLASP-depleted cells. Fitting of the simulation results to the experimental data (Figure 2E) illustrates that the dynamics of Golgi assembly in CLASP-depleted cells still involves a small number of Golgi-derived MTs, consistent with the fact that CLASP depletion was below 100% (Efimov et al., 2007; Miller et al., 2009). In addition, 250-300 MTs are nucleated from the centrosome in control and CLASP-depleted cells. MTs undergo dynamic instability; when a growing MT plus end encounters a Golgi fragment, a capture event takes place. If a centrosomal MT makes the capture, the fragment is transported by dynein motors toward the centrosome, but if it is a Golgi-derived MT, two fragments—captor and captured—glide toward each other with rates graded by their sizes. The fragments brought together by a Golgi-nucleated MT merge upon colocalization after a certain delay time. The *cis*-*trans* orientation of the merged fragment is equal to the geometric average of the initial orientations of two merged fragments. The surface area of the resulting fragment is equal to the sum of the areas of the merged fragments. A stack that is bigger than a threshold size starts to flatten against the nucleus. A constant average number of MTs is nucleated per unit surface area of the *trans* side of the resulting fragment. Additional model assumptions, variations, parameters, and simulation details can be found in the Supplemental Material.

Cells

Immortalized human pigment epithelial cells hTert-RPE1 (Clontech, Mountain View, CA) that stably express centrin1-GFP (see Uetake *et al.*, 2007) were maintained in DMEM/F12 with 10% fetal bovine serum at 37°C in 5% CO₂. Cells were plated on glass coverslips coated with 5 μ g/ml fibronectin 24 h prior to experiments. For laser microsurgery and live-cell observations, these coverslips were mounted in Rose chambers (Khodjakov and Rieder, 2001). Alternatively, glass bottom dishes (MatTek, Ashland, MA) were used in some experiments. In all live-cell experiments, cells were maintained on the microscope stage at 37°C.

Small interfering RNA depletion

Two different combinations of mixed small interfering RNA (siRNA) oligonucleotides against *CLASP1* and *CLASP2* were transfected into cells using HiPerFect (Qiagen, Valencia, CA), as described previously (Miller et al., 2009). Experiments were conducted 72 h after transfection, as at this time minimal protein levels were detected. Non-targeting siRNA (Dharmacon, Chicago, IL) was used for controls.

Treatments

Nocodazole (2.5 μ g/ml) or BFA (5 μ g/ml) was added to the culture media for 2 h. For washout, cells were rinsed five times and transferred to fresh, warm (37°C) medium for 2 h.

For cold treatment, cells were placed on ice for 40 min. For recovery, cells were placed to 37° C for 2 h.

In cell migration assays, time-lapse sequences were initiated 2 h after drug washout or temperature release, and cells were monitored for 4-8 h.

Transfection and immunostaining

3GFP-EMTB, ensconsin MT-binding domain (a gift from J. C. Bulinski, Columbia University, New York, NY) and/or mCherry-Rab6 (a gift from A. Akhmanova, Rotterdam, The Netherlands), or YFPGalT (Clontech) were transiently expressed in RPE1 cells. Fugene6 (Roche, Indianapolis, IN) was used for transfection according to the manufacturer's protocols.

The following antibodies were used: mouse monoclonal anti-GM130 (Transduction Laboratories, San Jose, CA), guinea pig polyclonal anti–GCC185 VU-140 (Efimov *et al.*, 2007), rabbit polyclonal acti–CLASPs VU-83 (Efimov *et al.*, 2007), mouse monoclonal anti– α -tubulin DM1a (Sigma-Aldrich, St. Louis, MO), rabbit polyclonal anti-tubulin (Abcam, Cambridge, MA), mouse monoclonal anti–Ac tubulin (Sigma-Aldrich). Alexa Fluor 488– and Alexa Fluor 568–conjugated highly cross-absorbed goat anti–mouse immunoglobulin G (IgG) antibodies, Alexa Fluor 568–and Alexa Fluor 633–conjugated highly cross-absorbed goat anti–rabbit IgG antibodies, and Alexa Fluor 568 anti–guinea pig IgG (Molecular Probes, Eugene, OR) were used as secondary antibodies. For immunostaining, cells were fixed for 15 min (room temp.) in 2% paraformaldehyde, 0.1% glutaraldehyde, and 0.5% saponin in cytoskeleton buffer (10 mM 2-(*N*morpholino)ethanesulfonic acid, 150 mM NaCL, 5 mM ethylene glycol tetraacetic acid, 5 mM glucose, and 5 mM MgCL₂, pH 6.1).

Immunofluorescence and live-cell imaging

Confocal stacks were taken with Leica TCS SP5 laser-scanning confocal system using a 100×, 1.47 numerical aperture (NA) Plan Apo lens, or with a Yokogawa QLC-100/CSU-10 spinning-disk head (Visitec assembled by Vashaw, Norcross, GA) attached to a Nikon TE2000E microscope using a 100×, 1.4 NA Plan Apo lens and a back-illuminated EMCCD camera (Cascade 512B; Photometrics, Tucson, AZ) driven by IPLab software (Scanalytics, Rockville, MD). For cell motility assays, differential interference contrast differential interference contrast (DIC) and two-color fluorescence images were recorded using 20×, 0.75 NA Plan Apo lens and an interline CCD camera (CoolSnap HQ; Photometrics).

Centrosome ablation and FRAP

The detailed layout of our laser microablation system is described elsewhere (Magidson *et al.*, 2007). Briefly, 532-nm laser pulses generated by a Q-switched Nd:YAG laser were focused on the specimen with a 100×, 1.4 NA Plan Apo lens. Centrosome ablation was achieved by a series of two to four laser pulses (~0.5 each) aimed sequentially at the two centrin-GFP–labeled centrioles. For each cell, success of the ablation was confirmed by collecting an image stack ~30 min after the operation. Owing to dynamic exchange of centrin-GFP, lack of localized centrin-GFP fluorescence proves that the centrosome was destroyed (Magidson *et al.*, 2007).

The unique morphology of centrin-GFP–labeled centrosomes (two diffraction-limited spots) allowed us to unambiguously delineate this organelle, even when cells coexpressed centrin-GFP and green-labeled Golgi markers. Further, centrin-GFP–labeled centrosomes remained clearly delineated in cells expressing 3GFP-EMTB when MTs were depolymerized with nocodazole.

The same microscopy workstation was utilized in the FRAP experiments, except a continuous-wave 488-nm laser beam was used in the latter case. Golgi stacks were photobleached with 1.5-s exposure to the beam. Recovery of the Golgi-associated fluorescence was measured on a single focal plan recorded at 3-s intervals.

In both laser microsurgery and FRAP experiments, images were recorded with a back-illuminated EM-CCD camera (Cascade 512B; Photometrics, Tuscon, AZ) in spinning-disk confocal mode (GSU-10; Yokogawa). All light sources were shuttered by either fast mechanical shutters (Vincent Associates, Falmouth, MA) or acousto-optic tunable filters (Solamere Technology Group, Salt Lake City, UT), such that cells were exposed to light only during actual image acquisition.

Image acquisition and processing

Figure 1: Maximum-intensity projection of confocal stacks (0.40- μ m spacing, over thickness of 1.2 μ m). Figure 3, A–D: Maximum-intensity projection of confocal stacks (0.20- μ m spacing, over whole cell); Figure 3, G–J, L: Single plane confocal video frame. Figure 4, A–D and G–N: Maximum-intensity projection of confocal stacks (0.20- μ m spacing, over whole cell); Figure 6, A–D: Wide-field fluorescence, inverted images; Figure 6, A'–D': Maximum-intensity projection over time of time-lapse wild-field fluorescence, inverted images, 2-min recording with 1 s between frames and 300-ms exposure time; Figure 6, A'–D': DIC images with superimposed

tracks of post-Golgi vesicle movement (see "Post-Golgi vesicle tracking" in the Supplemental Material). Figure 6, G–J: Inverted maximum-intensity projection of confocal stacks (0.20-µm spacing, over whole cell). Figure 7, A–D: False-colored DIC video frames superimposed on one image, 1 h between frames, 100-ms exposure time. Figure S2: Maximum-intensity projection of confocal stacks (0.20-µm spacing, over whole cell). Figure S3, B and C: Wide-field fluorescence images. Figure S7: Maximum-intensity projection of confocal stacks (0.20-µm spacing, over whole cell). Figure S10: DIC (A–L) or phase (M–R) merged with wide-field fluorescence video frames, 30 min between frames, 100-ms exposure time for DIC and 200-ms exposure time for red fluorescent channel (pseudocolored green in the images). Figure S11, A–D: Pseudocolored DIC or phasecontrast video frames superimposed on one image, 1 h between frames, 100-ms exposure time.

Statistical analysis

Statistical significance was determined by Student's *t* test (two-tailed, unpaired).

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Supplemental Figures



Figure S1. Random distribution of ministacks in nocodazole-treated cells as confirmed by the following test: in pre-assembly snapshots of scattered Golgi-ministacks, a circular disc of radius 5 μ m (25 pixel) is placed randomly in the cell and the number of mini-stacks within the disc is counted (blue). The bar graph shows almost a constant number of mini-stacks found within the disc as it is moved randomly throughout the cell. Larger discs of radius 10 μ m (green) or 15 μ m (red) show similar behavior. The average number of mini-stacks within the disc increases proportionally to the area of the disc. Two examples are shown.



Figure S2. Centrosome ablation does not disrupt the Golgi or the MT network. A-B, an RPE1 cell expressing centrin-GFP before and after laser ablation of the centrosome (arrows). This cell was fixed after 2 hours of random migration and immunostained for the Golgi marker GM130 and MTs. C, Immunofluorescence image of the cell presented in A-B. GM130, red. Tubulin (far-red, false-colored blue). **D**, A bystander cell in the same preparation. Notice the intact centrosome (arrow). Golgi morphology and the MT network look similar in C and D.



Figure S3: CLASP depletion in RPE1 cells. A, CLASP1 and CLASP2 detected by western blotting, actin, loading control. **B, C,** Immunostaining confirms that as compared with control non-targeted siRNA transfected cells (B), CLASPs are considerably depleted and evenly distributed in knockdown cell population (C).



Figure S4: Predicted size distribution of Golgi fragments. Histograms of sizes are shown for 20 (top) and 60 (bottom) min of assembly. **A**, In control, the drift in size space starts after 20 min (see small number of ~ 1cubic micron-large fragments), and by 60 min a significant number of fragments are voluminous. Note that the total volume of large fragments is greater than that of small fragments. **B**, In the acentrosomal case, large fragments do appear, but their size distribution is very dispersed. **C**, In the CLASP-depleted case, large fragments do not evolve.



Figure S5: Predicted statistics of Golgi assembly. **A**, The total numbers of disjointed Golgi fragments is small and similar in control and acentrosomal cases, but is four-fold greater in the CLASP depleted case. **B**, Average radii of Golgi fragments in all 3 cases. **C**, Golgi fragments are distributed over a wider area in the CLASP depleted and acentrosomal cases after 60 min of assembly than in the control case. Spanning cluster's center is at the 'centre-of-mass' of all Golgi fragments, and its radius is $R_{span} = sum (m_i r_i)/sum(r_i)$, where m_i and r_i are the volume and distance from the centre-of-mass of the i'th fragment. **D**, Predicted compactness of Golgi cluster for control, acentrosomal and CLASP depleted cases after 60 min of assembly. Compactness is defined as the ratio (Golgi area within spanning cluster)/(total area of the spanning cluster= πR_{span}^2).



Figure S6: Predicted long term behavior of Golgi assembly. Overall Golgi organization (A), number of fragments (B) and angular distribution of the Golgi (C) do not differ significantly from those at 1 hour of assembly, indicating that the assembly has reached steady state at the 1 hour time point.



Figure S7: Independent disassembly of MTs and Golgi. Immunostaining. Tubulin, red, GM130, green (far red, false-colored). Centrin-GFP, blue (false-colored). In contrast to a control cell (A), cold-treated cells lack the MT network (B, C) and BFA-treated cells lack the Golgi apparatus (D, E). No striking difference observed between centrosomal (B, D) and acentrosomal cells (C, E).



Figure S8: Experimental data for the angular distribution of Golgi fragments before (0 min) and after (60 min) assembly. **A**, Total area (in pixels) of Golgi fragments in each of the eight 45-degree wide sectors. The inset shows the geometry: zero degree corresponds to the right tangent to the nucleus from the centrosome. 90 degrees correspond to the outward normal to the nuclear surface. After 60 min of assembly, significant focusing in angular space takes place in control cell, and the most of Golgi ministacks are right in front of the centrosome. **B**, Normalized Golgi area averaged from 3 control cells shows the same effect as in A. **C**, In the CLASP depleted case (result from averaging 2-cell data), there is almost no focusing, and the maximum of the Golgi density deviates from 90 degrees.



Figure S9. Metrics of the motility assays used in the study. A, Directional migration metric. Results of quantification are presented in Fig. 3 I, J. **B**, Momentary polarization metric. Results of quantification are presented in Fig. 3 K-O. **C**, Golgi repositioning metric. Time between cell configurations 2 and 3 is presented in Fig. 3P.



Fig S10. Repositioning of the Golgi during spontaneous turns in migrating cells. A-R, Selected frames from time-lapse movies presenting mCherry-Rab6 fluorescence (green) superimposed on DIC (A-L) or phase-contract (M-R) images. **A-D**, untreated centrosomal cell, **E-H**, untreated acentrosomal cell; **I-L**, centrosomal cell released from 2-hr nocodazole treatment; **M-R**, acentrosomal cell released from 2-hr after nocodazole washout. Time 0 corresponds to 2 hrs after nocodazole washout. Red letters *N* denote nuclei; asterisks denote leading edges.



Fig. S11. Migration of centrosomal and acentrosomal cells after ice or BFA treatment. A-

D, Random single cell migration of: **A**, centrosomal cell fixed 2h after ice treatment; **B**, acentrosomal cell starting 2h after ice treatment; **C**, centrosomal cell starting 2h after BFA washout; **D**, acentrosomal cell starting 2h after BFA washout. Color-coded images depict positions of each cell at 1h intervals. **E**, directional persistence of migration and **J**, total cell migration distance, in the four experimental conditions corresponding to A-D. Asterisk indicates P<0.05 in unpaired Student's t-test between bars marked with black and white asterisks. Error bars represent SEM.

Supplemental information on modeling Golgi assembly

To simulate Golgi assembly, we used agent-based object-oriented methodology (Alberts and Odell, 2004). Our discrete stochastic model is 3-dimensional. Parameters of the model are gathered in the table below. The geometry of the cell consists of an oblate-spheroidal space occluded by a spherical nucleus. Initially, ~ 150 Golgi fragments (ministacks) of radius 0.2 μ m are uniformly randomly distributed within the cell space excluding the nuclear space. Experimental observations suggest that the cell and the nucleus are not concentric; the latter is usually located closer to the side of the cell. Therefore we assume certain displacement of the nuclear center relative to the cell center resembling observed geometry. The centrosome in the model, similar to the observation, is located near the nuclear surface, at the side distal to the cell boundary.

In the model, three classes of objects are implemented: (i) Golgi-generated and centrosomal MTs; (ii) Golgi fragments (ministacks, clusters); (iii) obstacles such as nuclear surface and cell boundary. The objects behave according to the rules described below. Golgi fragments are spherical; two hemispheres represent trans- and cis- sides respectively.

Simulated dynamic MTs are either linear or curved, as observed (with fixed radius of curvature close to that observed). Entire population of the centrosomal MTs is divided among the straight and curved MTs in a 2:1 ratio. This ratio is chosen because it appears to be optimal in terms of the speed and completeness of the assembly when varied between 1:1 and 3:1. A simple reason could be this: Because of excluded volume of the nucleus, straight centrosomal MTs can grow and span approximately 2/3 of the cell space. Therefore, remaining 1/3 space is given to the curved MTs to probe and catch targets. Each MT is represented by short rigid segments of equal lengths connected to each other. The minus-ends are anchored at the centrosome and Golgi, while the plus-ends undergo growth and shortening by adding or losing segments with constant rates V_{q} and V_{s} respectively. The catastrophe (f_{cat}) and rescue (f_{res}) frequencies are chosen to minimize the Golgi assembly time. Multiple simulations were made to find the optimal parameters. It turns out that the optimal regime corresponds to no rescues, f_{res} = 0 (MT growing in the direction where no Golgi fragments are located has to shrink to zero and start to grow in the new direction.) Optimal catastrophe frequency corresponds to MTs growing to the average length $< L_{MT} >$ comparable to the cell size; $f_{cat} = V_g / < L_{MT} >$. For simplicity we assumed these parameters to be the same for both centrosomal and Golgi-nucleated MTs.

A catastrophe also instantly takes place after a collision with the cell or nuclear boundary. Upon encountering a Golgi fragment, a MT may shrink or bypasses the Golgi fragment with probability P_{bypass} and grows further or catastrophes with probability (1 - P_{bypass}). We found that when probability P_{bypass} is below ~ 0.5, we could not fit the observed numbers of Golgi fragments as functions of time. For 0.5 < P_{bypass} < 1, the fits were good. The reported results are for P_{bypass} = 0.8. About 300 dynamic MTs are nucleated from the centrosome in random directions spanning the whole space, as well as from the trans- sides of the Golgi stacks spanning the half space determined by orientation of each stack.

Once a growing MT plus-end encounters an initial Golgi fragment, we assume that dynein motor(s) associated with the membrane transport it toward the MT minus-end with speed V_{Golgi} determined by a free speed of the dynein motors. Viscous resistance of the cytoplasm is negligible (Cytrynbaum *et al.*, 2003). We assume that the motors coat the Golgi stacks on both cis- and trans- sides. We tested the case in which only trans- sides are associated with the motors, and the assembly was too slow to reproduce the data. Two fragments touching each other merge after certain delay time τ_{merge} but only if they were brought together by a Golgi-generated MT. Two fragments brought together accidentally by two centrosomal MTs merged only with a significant delay. The underlying mechanism is based on the idea that a MT-motor-

dependent action is required to allow the fragments to fuse with each other. Once two fragments are successfully merged, they form a single spherical fragment with the trans/cis surface pointing in the direction determined as the geometric average of the directions of the original two fragments. During this process, the entire MT array of participating fragments is destroyed and a new array of MTs emerges after the merging is completed. In the control case, the number of MTs nucleated by the fused fragment is assumed to be proportional to its surface area. (Number of MTs nucleated from the merged fragment = (Initial average number of MTs per Golgi fragment)*S_{merged}/S_{min}, where S_{merged} and S_{min} are the surface areas of the merged and initial fragments respectively.) Within the delay time τ_{merge} , if one of the engaged fragments is captured by MTs from a different source, it is pulled away and merging is not accomplished. When Golgi fragments are pulled by centrosomal MTs, they pile up near the centrosome. When a Golgi fragment was closer than a threshold to the centrosome and was above a certain radius, it flattened along the nuclear surface, due to pulling forces from the centrosomal MTs pressing the fragments to the nucleus.

We have considered three scenarios for the nucleation of MTs at the Golgi surface: A) control, B) acentrosomal, and C) CLASP depleted. The number of MTs nucleated by each initial Golgi fragment is 3 - 4 in cases (A,B), 1 - 2 in case (C). In case (B), the centrosomal MT array is completely disrupted.

The polarization parameter reported in Fig. 4E was computed as the integral

$$\frac{\int_{0}^{2\pi} \cos(\theta - \theta_0) \times f(\theta) d\theta}{\int_{0}^{2\pi} f(\theta) d\theta}$$
, where $f(\theta)$ is the angular distribution of the MTs, and θ_0 is the

direction from the center of the nucleus to the centrosome.

We have simulated the model repeatedly varying parameters and repeating assembly simulations hundreds of times for each parameter value. Technical details of the simulations are the same as those reported in (Paul *et al.*, 2009). The numerical codes were implemented with C programming language. Numerical experiments were performed on an IBM dual CPU Opteron server.

Parameter	Description	Value
R _{cell}	Cell radius	20-30 µm *
d _{cell}	Cell thickness	1-1.5 µm *
R _{nuc}	Nuclear radius	10 µm *
R _{ves}	Initial Golgi fragment radius	0.15-0.2 µm *
NMT _{cent}	Number of centrosomal MTs	250-300 **
NMT _{Golgi}	Number of initial MTs per Golgi fragment	0-5 ***
V _{Golgi}	Dynein-driven speed of a small fragment	0.13 µm s⁻¹ ****
V _g	MT growth rate	0.1 µm s⁻¹ **
V _s	MT shortening rate	0.2 µm s⁻¹ **
f_{cat}	Optimal MT catastrophe frequency	0-0.002 s ⁻¹ *****
f _{res}	Optimal MT rescue frequency	0 s ⁻¹ *****
Z _{shift}	Shift of the nuclear center from the cell center	-10 µm *
H _{cent}	Centrosome distance from nucleus	1.35 µm *
T _{merge}	Ministack merging time	1 min *****
T _{flip}	Ministack flip time	1.5 min *****
$\sigma_{\rm MT}$	Number of MTs nucleated per µm ² surface	~ 4 ***
	area of a merged Golgi fragment	
${\cal P}_{ m bypass}$	Probability for a MT plus-end that runs into a Golgi fragment to bypass it	~ 0.5 – 1 ***

Parameters used in the simulation

* Based on our observations (this study): four cell images were used. For the radii, we measured the areas of the cell, nucleus and Golgi fragments, divided it by π , took the square root, and averaged for four images. We averaged the cell thickness from the side view along the length of the cell, and then averaged for four images.

** (Rusan et al., 2001; Burakov et al., 2003; Paul et al., 2009).

*** Inferred from from fitting the number of Golgi fragments as function of time, as well as based on previous results (Efimov *et al.*, 2007).

**** (Cytrynbaum *et al.*, 2003).

***** Obtained by numerical scan of the parameter space. Specifically, starting with 150 Golgi fragments, we ran the simulation for the control case and measured the time until the fragment number reduced to 25. The simulations were performed in the range of the catastrophe and rescue frequencies between 0 and 0.05/s with increment 0.001/s. We then plotted the assembly time as a function of catastrophe and rescue frequencies and determined their optimal values from the global minima of the obtained assembly time. The optimal frequency of rescue turned out to be lower than that reported for the peripheral parts of interphase cells. Our simulations predict that the Golgi assembly would slow down considerably if the rescue frequency is as high as reported for the peripheral parts of interphase cells. Interestingly, the frequency of rescue needed to best fit the experimental data resembles the frequency observed during prometaphase (Paul *et al.*, 2009). Note that interphase MT parameters were measured in steady-state while during prometaphase a new array of microtubules is assembled. The latter condition is more similar to the situation observed upon nocodazole washout.

****** These are maximal times that give good numerical fits to the data. Smaller times do not make the fits worse; greater times worsen the fits.

Supplemental Experimental Procedures and Data Analysis

The Golgi complex organization

Circularity and Compactness

For these measurements the Golgi was visualized via immunostaining for the cis-Golgi component GM130. The complex was freehand-outlined in maximal-intensity projections computed from complete Z-series collected at 0.2 µm steps.

ImageJ circularity plugin (rsb.info.nih.gov/ij/plugins/circularity.html) was used to compute the Circularity index [*Circularity* = $4\pi \cdot (area/perimeter^2)$].

Circularity index has been used to analyze overall cell shape (Patel *et al.*, 2008; Miller *et al.*, 2009) as well as to measure microfilament ring circularity during cellularization (Thomas and Wieschaus, 2004). A circularity value of 1 corresponds to a perfect circle.

To determine compactness the freehand-outline of the Golgi was thresholded to assign an integer pixel value within the selection and 0 value to the background. An imageJ plugin that calculates the percentage of non-zero pixels in the image or selection was used to determine the percentage of the area taken by the Golgi stacks inside the selection. Higher level of compactness indicates more dense Golgi structure while lower level of compactness corresponds to more dispersed and disorganized Golgi complex.

Post-Golgi vesicles tracking

Two-minute time-lapse wide-field fluorescence sequences of RPE1 cells expressing fluorescently-labeled Rab6 were recorded at 1-s intervals. Individual particles were tracked manually using the MTrackJ ImageJ plugin (www.imagescience.org/meijering/software/mtrackj/) Then the number of tracks was determined in each quadrant oriented with respect to the position of the cell's leading edge (front, left, back and right quadrants).

Directional persistence of cell migration.

4-hr long time-lapse DIC sequences were recorded at 3-min intervals. Positions of the nucleus were tracked manually using the MTrackJ ImageJ plugin (see above). Cell relocation was measured as the distance between the nucleus position at the start and at the finish. The length of tracks was deemed to represent the total distance of cells migration. Directional persistence was calculated as cell relocation divided by the length of the track (Fig. S2A). Directional persistence value of 1 corresponds to the strictly uni-directional migration.

Momentary polarity index

To evaluate ability of a cell to persistently maintain polarity, 30-min long time-lapse DIC sequences were recorded at 3-min intervals. Cell contours were freehand-outlined at each time-point. These outlines were superimposed on the next frame in the sequence, which allowed us to identify new-formed protrusions (Fig. S2B). Momentary polarity index was calculated as the ratio of the area of protrusion at the leading edge to the summarized area of protrusions along the whole cell perimeter. Momentary polarity index value of 1 indicates a maximally polarized cell, and value of ½ corresponds to an absolutely non-polarized cell.

The Golgi reorientation assay

To measure the time required for Golgi reorientation to the leading edge, multi-mode DIC/fluorescence time-lapses were recorded at 3-min intervals. Positions of the cell nucleus, the Golgi complex and the leading edge were manually tracked using MTrackJ ImageJ plugin (see above). For each frame, the angle between position of the Golgi complex center and the leading edge center with angular point corresponding to nucleus position was measured (Fig. S2C). An acute angle below 60° corresponded to the front position of the Golgi according to the leading edge, and an obtuse angle (over 90°) corresponded to the back position. Time from the cell turn (new leading edge formation) and the Golgi re-orientation toward the leading edge (below 60°) was measured for sharp turns upon which the Golgi was found behind the nucleus (at least 90° angle).

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