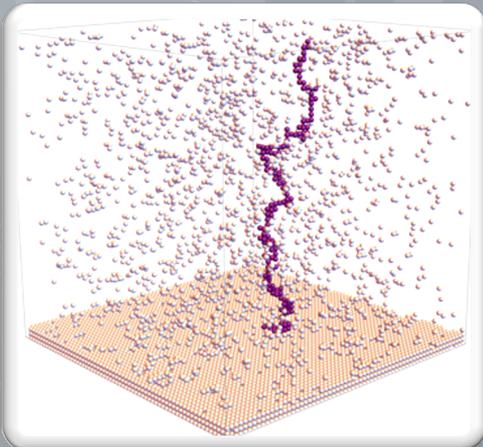


MIT

Dec 2019

# Maximum of 3D Ising interfaces

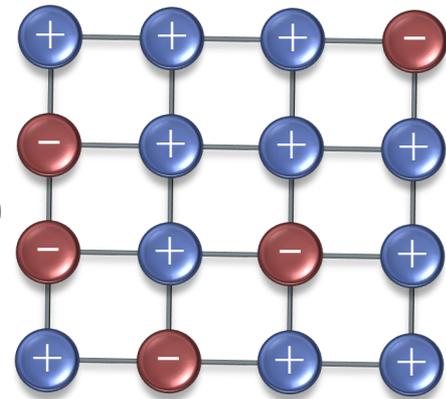


**Eyal Lubetzky**  
Courant Institute (NYU)

based on joint works with  
Reza Gheissari (UC Berkeley)

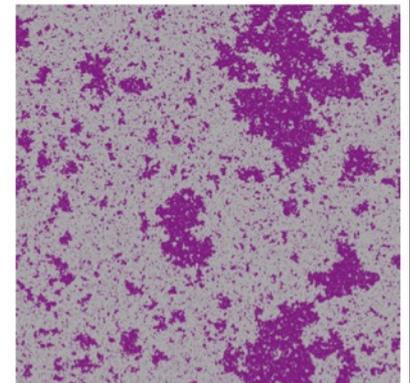
# Definition: the classical Ising model

- ▶ Underlying geometry: finite  $\Lambda \subset \mathbb{Z}^d$ .
- ▶ Set of possible configurations:  
$$\Omega = \{\pm 1\}^\Lambda$$
  
(each *site* receives a plus/minus *spin*)
- ▶ Probability of a configuration  $\sigma \in \Omega$  given by the *Gibbs distribution*:



$$\mu_\Lambda(\sigma) = \frac{1}{Z(\beta)} \exp\left(-\beta \sum_{x \sim y} \mathbf{1}_{\{\sigma_x \neq \sigma_y\}}\right)$$

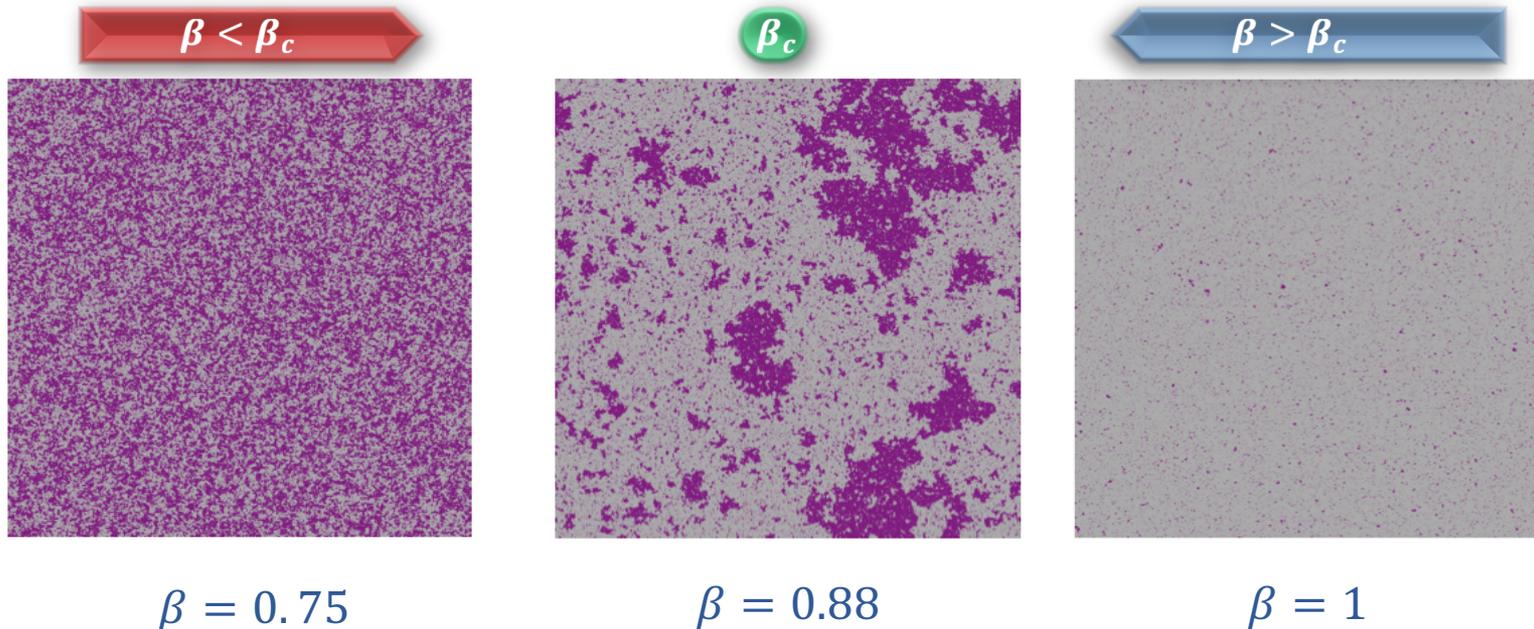
- ▶  $\beta \geq 0$ : the inverse temperature
- ▶  $Z(\beta)$ : the partition function



# The Ising model phase transition

- Underlying geometry:  $\Lambda =$  finite 2D grid.
- Set of possible configurations:  $\Omega = \{\pm 1\}^\Lambda$
- Probability of a configuration:  $\mu_\Lambda(\sigma) = \frac{1}{Z(\beta)} \exp\left(-\beta \sum_{x \sim y} \mathbf{1}_{\{\sigma_x \neq \sigma_y\}}\right)$

Local (nearest-neighbor) interactions have macroscopic effects:

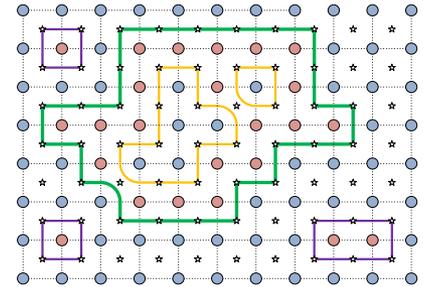


# Low temperature representation in 2D

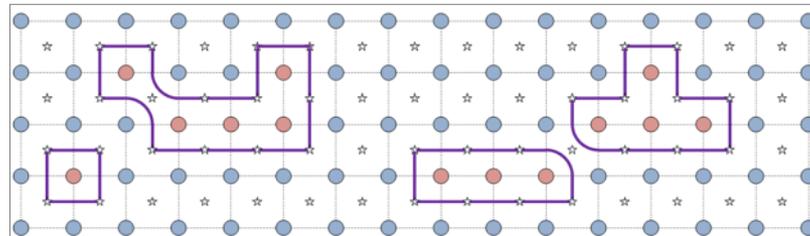
▶ Setting:  $\Lambda \subset \mathbb{Z}^2$  is an  $n \times n$  box with -plus boundary.

- ▶ Draw a dual-edge  $(u, v)^*$  if  $\sigma_x \neq \sigma_y$
- ▶ Bijection between a dual-loop collection and the Ising configuration  $\sigma$ .
- ▶ Induced distribution on the dual-loops:

$$\mu_{\Lambda}^+(\{\gamma_1, \gamma_2, \dots\}) = \frac{1}{z(\beta)} e^{-\beta \sum |\gamma_i|}$$

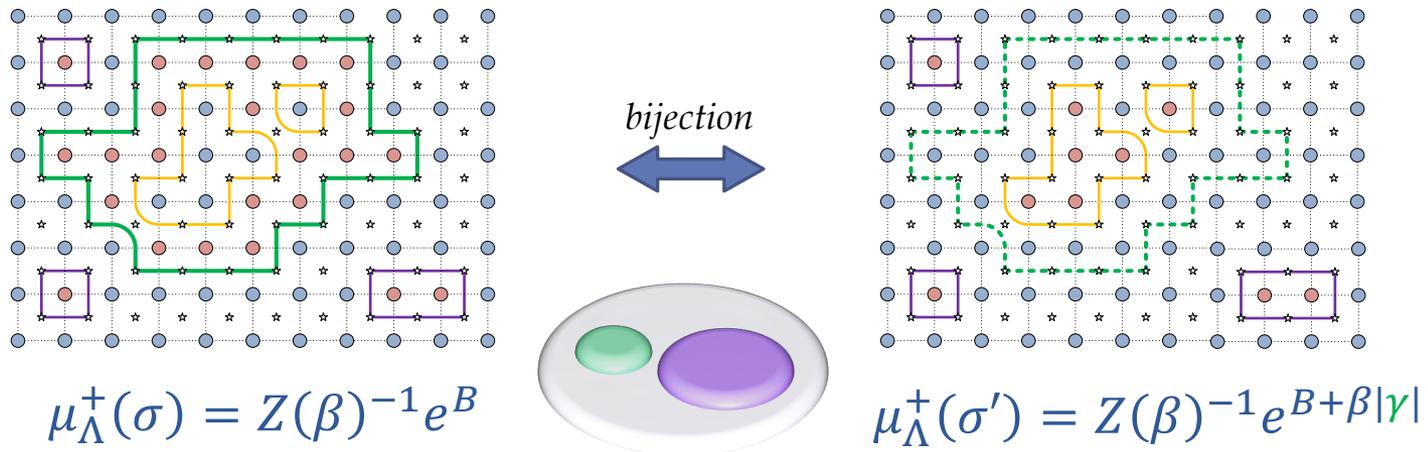


▶ [Peierls '36]: proof of a phase transition for  $\beta > \beta_0$ :  
1st moment argument on # of sites inside a -“island”



# Peierls' phase transition argument

- ▶ Setting:  $\Lambda \subset \mathbb{Z}^2$  is an  $n \times n$  box with -plus boundary.
- ▶ For any  $\sigma$  containing  $\gamma$  flip *all spins in the interior of  $\gamma$*  :



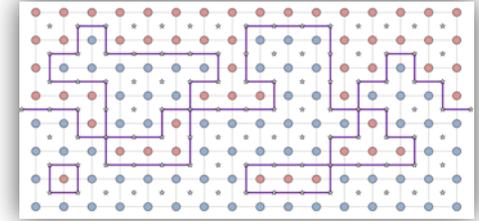
$$\Rightarrow \mu_{\Lambda}^+(\gamma \text{ belongs to loop collection}) \leq e^{-\beta|\gamma|}.$$

- ▶ For a site  $x$ : at most  $e^{c\ell}$  contours  $\gamma$  of length  $\ell$  around  $x$ , and each such  $\gamma$  costs  $e^{-\beta\ell}$ ; overall:

$$\mu_{\Lambda}^+(\sigma_x = -1) \leq e^{-4(\beta-c)}.$$

# 2D Ising interfaces

? ▶ What does the interface between the  $\oplus$  and  $\ominus$  phases look like at  $\beta > \beta_c$ ?

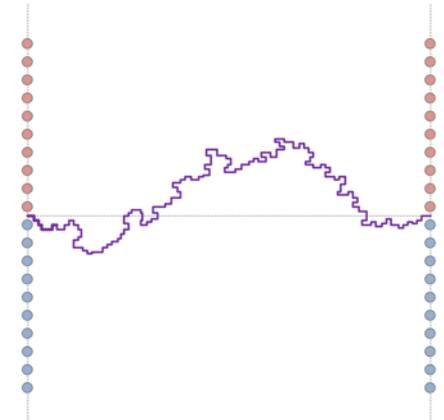


▶  $\mu_{\Lambda}^{\mp}$ : Ising model on

▶ 2D cylinder  $\Lambda = \llbracket -n, n \rrbracket \times (\mathbb{Z} + \frac{1}{2})$

▶ Boundary conditions:  $\begin{cases} - & \text{upper half-plane} \\ + & \text{lower half-plane} \end{cases}$

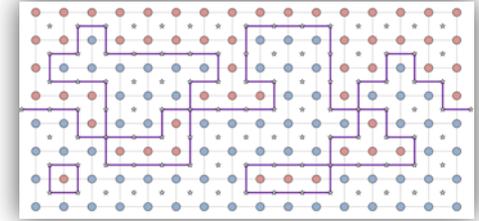
▶ Draw a dual-edge  $(u, v)^*$  if  $\sigma_x \neq \sigma_y$ .



▶ **Interface:** (max) connected set  $\mathcal{J}$  of dual-edges separating the infinite  $+$  and  $-$  components of the boundary.

# 2D Ising interfaces: roughness

- ? ▶ What does the interface between the  $\oplus$  and  $\ominus$  phases look like at  $\beta > \beta_c$ ?

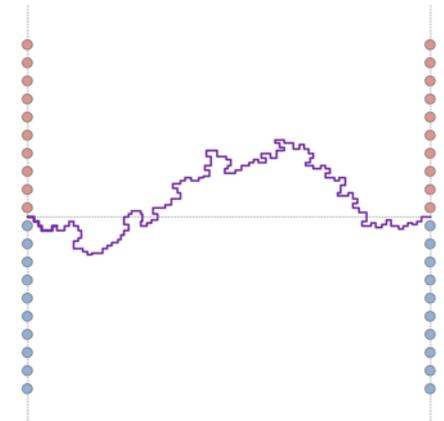


- ▶ 2D Ising model w. Dobrushin's boundary conditions  $\mu_{\Lambda_n}^{\mp}$  :

- ▶ Interface has a scaling limit:

$$\frac{J(x/n)}{\sqrt{c_\beta n}} \rightarrow \text{Brownian bridge}$$

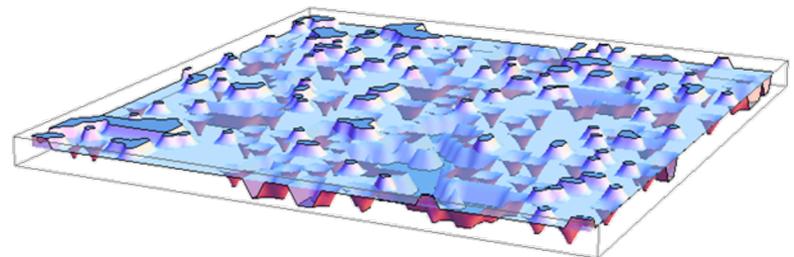
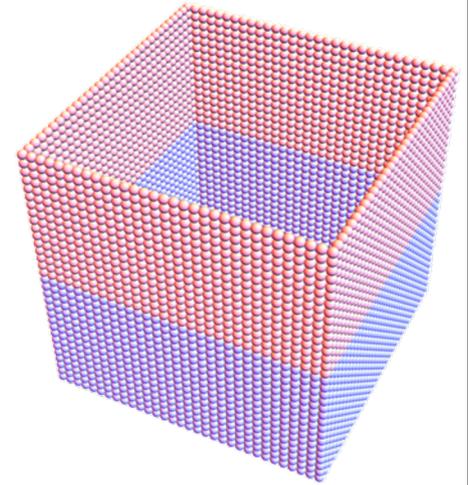
- ▶ Interface is *rough*: fluctuations of  $\sqrt{n}$
- ▶ Maximum  $M_n$  is  $O_P(\sqrt{n})$ , and  $M_n - \mathbb{E}[M_n]$  is also  $O_P(\sqrt{n})$ .



[Higuchi '79], [Dobrushin, Hryniv '97], [Hryniv '98],  
[Dobrushin, Kotecky, Shlosman '92]

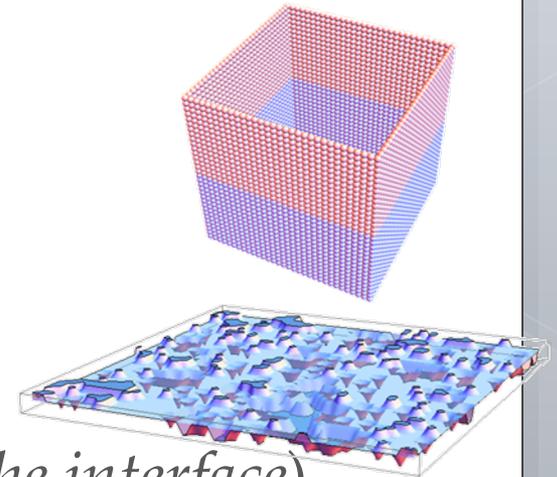
# 3D Ising Interfaces

- ▶  $\mu_{\Lambda}^{\mp}$ : Ising model on
  - 3D cylinder  $\Lambda = \llbracket -n, n \rrbracket^2 \times (\mathbb{Z} + \frac{1}{2})$
  - Boundary conditions:  $\begin{cases} - & \text{upper half-space} \\ + & \text{lower half-space} \end{cases}$
  - Draw a dual-face  $(u, v)^*$  if  $\sigma_x \neq \sigma_y$ .
- ▶ **Interface:** (max) connected set  $\mathcal{I}$  of faces separating the infinite  $+$  and  $-$  components of the boundary.



# 3D Ising interfaces: rigidity

- ▶  $\mu_\Lambda^\mp$  : Ising model on
  - 3D cylinder  $\Lambda = \llbracket -n, n \rrbracket^2 \times (\mathbb{Z} + \frac{1}{2})$
  - Boundary conditions:  $\begin{cases} - & \text{upper half-space} \\ + & \text{lower half-space} \end{cases}$



- ▶ THEOREM: [Dobrushin '72] (*rigidity of the interface*)

There exists  $\beta_0 > 0$  such that  $\forall \beta > \beta_0$  and  $\forall x_1, x_2, h$ ,

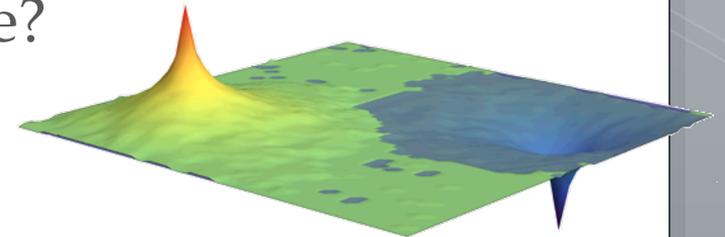
$$\mu_\Lambda^\mp(\mathcal{J} \ni (x_1, x_2, h)) \leq \exp\left(-\frac{1}{3} \beta h\right)$$

- ▶ COROLLARY: [Dobrushin '72, '73] for  $\beta > \beta_0$ :

1.  $\exists$  non-translation invariant  $\mathbb{Z}^3$  Gibbs measures
2. Maximum height of  $\mathcal{J}$  is  $O_P(\log n)$ .

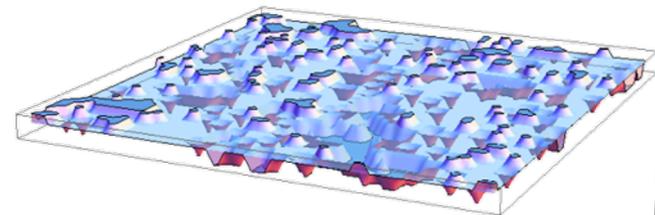
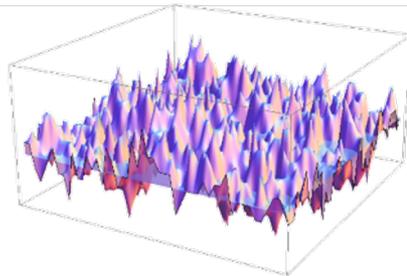
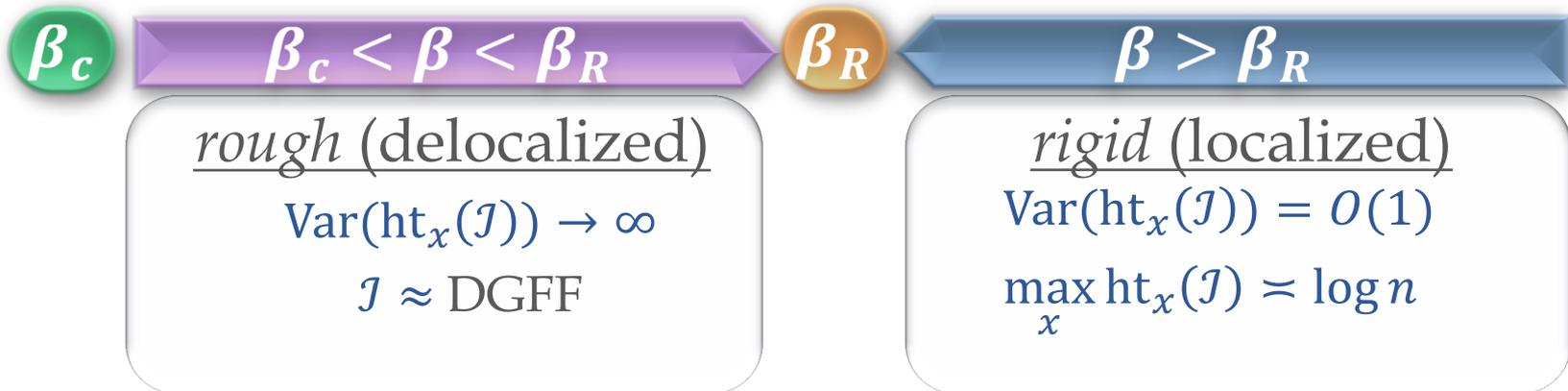
# Plus/minus interface in 3D Ising

- ▶  $M_n$  = maximum height of the interface  $\mathcal{J}$  in 3D Ising with Dobrushin's boundary conditions.
  - ▶ [Dobrushin '72]:  $\exists C_\beta$  s.t.  $\mu_\Lambda^\mp(M_n \leq C_\beta \log n) \rightarrow 1$ .
  - ▶  $\Rightarrow$  (via straightforward matching order lower bound) the maximum of the interface has **order  $\log n$** .
- ▶ Asymptotics of the maximum (LLN)? Tightness?
- ▶ Structure of interface conditioned on LDs?
  - ▶ conditioned on  $(x_1, x_2, 0)$  belonging to a “pillar” reaching height  $h$ , what can we say about that pillar, e.g., its surface area? its volume?  $xy$ -coords of its tip?



# 3D Ising Roughening phase transition

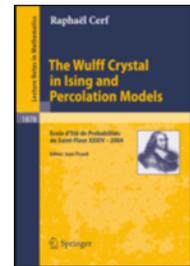
- ▶ Conj.: Roughening phase transition in 3D at  $\beta_R \approx 0.83$ :



“Evidence that  $T_R < T_c(3)$  strictly was obtained by Weeks et al. (1973) ... To this day, there still appears to be no proof that  $T_R < T_c(3)$ .” [Abraham ‘86]

# Related work on 3D Ising interfaces

- ▶ Alternative simpler argument by [van Beijeren '75] for [Dobrushin '72]'s result on the rigidity of the 3D Ising interface.
- ▶ Rigidity argument extended to
  - Widom–Rowlinson model [Bricmont, Lebowitz, Pfister, Olivieri '79a], [Bricmont, Lebowitz, Pfister '79b, '79c]
  - Super-critical percolation / random cluster model conditioned to have interfaces [Gielis, Grimmett '02]
- ▶ Tilted interfaces: [Cerf, Kenyon '01] (zero temperature, 111 interface), [Miracle Sole '95] (1-step interface), [Sheffield '03] ( $|\nabla\phi|^p$  models), **many** works on the conjectured behavior, related to the (non-)existence of non-translational invariant Gibbs measures
- ▶ Wulff shape, large deviations for the magnetization, surface tension [Pisztora '96], [Bodineau '96], [Cerf, Pisztora '00], [Bodineau '05], [Cerf '06]
- ▶ Plus/minus phases away from the interface [Zhou '19]

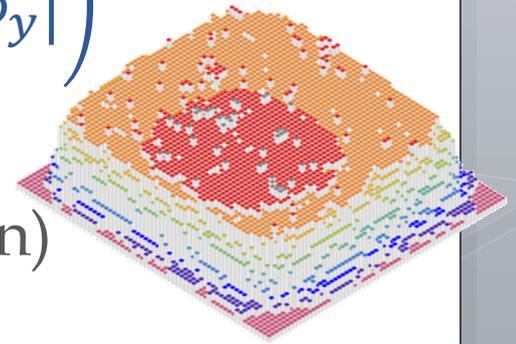


# Approximating random surface models

- ▶ DEFINITION:  $(2+1)$ -dimensional SOS above a wall [Temperley '52] probability measure on height functions  $\phi$  on  $\Lambda = \{1, \dots, L\}^2$  with  $\Lambda \ni x \mapsto \phi_x \in \mathbb{Z}$  and  $\phi_x = 0$  for  $x \notin \Lambda$  given by

$$\pi_{\Lambda}(\phi) = \frac{1}{Z_{\beta, \Lambda}} \exp \left( -\beta \sum_{x \sim y} |\phi_x - \phi_y| \right)$$

- ▶ no bubbles (distribution on interfaces)
- ▶ no overhangs (interface = height function)



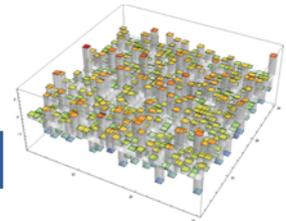
- ▶  $|\nabla \phi|^p$  model:  $\pi_{\Lambda}(\phi) \propto e^{-\beta \sum_{x \sim y} |\phi_x - \phi_y|^p}$  for  $p \geq 1$   
( $p = 1$  is SOS;  $p = 2$  is the discrete Gaussian;  $p = \infty$  is RSOS)

# SOS: roughening transition

- ▶ (2+1)**D** surface *delocalized* (rough) at  $\beta \ll 1$ :

$$\text{Var}(\phi_x) \asymp \log n, \quad \mathbb{E} \phi_x \phi_y \asymp \log|x - y|$$

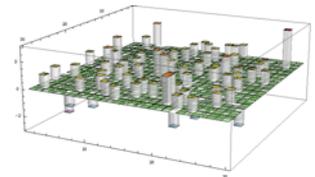
[Fröhlich, Spencer ('81), ('83)]



- ▶ (2+1)**D** surface *localized* (rigid) at  $\beta \gg 1$ :

$$\text{Var}(\phi_x) \asymp 1, \quad \mathbb{E} \phi_x \phi_y \simeq e^{-c|x-y|}$$

[Gallavotti, Martin-Löf, Miracle-Solé ('73)], [Brandenberger, Wayne ('82)]



- ▶ Maximum  $M_n$  of the rigid (2+1)**D** surface at  $\beta \gg 1$ :

- $\mathbb{E}[M_n] \asymp \beta^{-1} \log n$  [Bricmont, El-Mellouki, Fröhlich '86]

- $M_n = \frac{1}{2\beta} \log n + O(1)$  (+shape theorem, with and w/o a floor)

[Caputo, L., Martinelli, Sly, Toninelli '12, '14, '16]

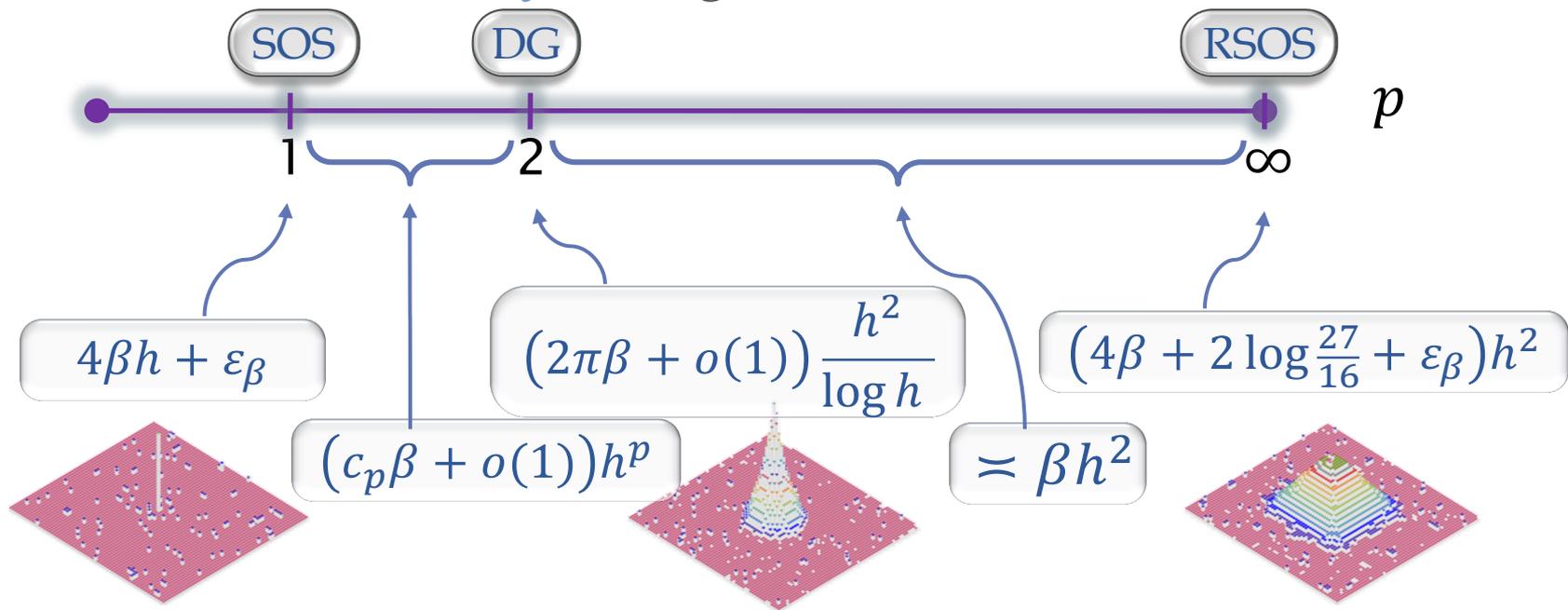
# Maximum dominated by LD at origin

- ▶ Maximum governed by  $\infty$ -volume large deviation rate

$$\lim_{h \rightarrow \infty} -\frac{1}{h^a} \log \pi_{\mathbb{Z}^2}(\phi_x \geq h)$$

which is tied to the shape of *tall pillars*:

- ▶ [L., Martinelli, Sly '16]: general  $|\nabla\phi|^p$  surface models:



# LLN for the maximum

- ▶ Recall:  $M_n$  = maximum of the interface  $\mathcal{J}$  in 3D Ising with Dobrushin's b.c.; [Dobrushin '72]:  $M_n = O_P(\log n)$ .
- ▶ THEOREM: ([Gheissari, L. '19a])

There exists  $\beta_0$  such that for all  $\beta > \beta_0$ ,

$$\lim_{n \rightarrow \infty} \frac{M_n}{\log n} = \frac{2}{\alpha}, \quad \text{in probability,}$$

LLN

where

$$\alpha(\beta) = \lim_{h \rightarrow \infty} -\frac{1}{h} \log \mu_{\mathbb{Z}^3}^{\mp} \left( (0,0,0) \overset{+}{\longleftrightarrow} (\mathbb{R}^2 \times \{h\}) \right)$$

and satisfies  $\alpha(\beta)/\beta \rightarrow 4$  as  $\beta \rightarrow \infty$ .

- ▶ existence of the limit  $\alpha$  nontrivial: relies on new results on the interface shape conditioned on LD.

# Tightness and tails for the maximum

► THEOREM: ([Gheissari, L. '19b])

1. There exists  $\beta_0$  such that for all  $\beta > \beta_0$ ,

$$M_n - \mathbb{E}M_n = O_P(1).$$

2. There exist  $C, \bar{\alpha}, \underline{\alpha}$  such that  $\forall r \geq 1$ ,

$$\begin{cases} e^{-(\bar{\alpha}r+C)} \leq \mu_n^{\bar{\cdot}}(M_n \geq \mathbb{E}[M_n] + r) \leq e^{-(\underline{\alpha}r-C)} \\ e^{-e^{\bar{\alpha}r+C}} \leq \mu_n^{\bar{\cdot}}(M_n \leq \mathbb{E}[M_n] - r) \leq e^{-e^{\underline{\alpha}r-C}} \end{cases}$$

where  $\bar{\alpha}/\underline{\alpha} \rightarrow 1$  as  $\beta \rightarrow \infty$ .

Tightness  
Gumbel tails

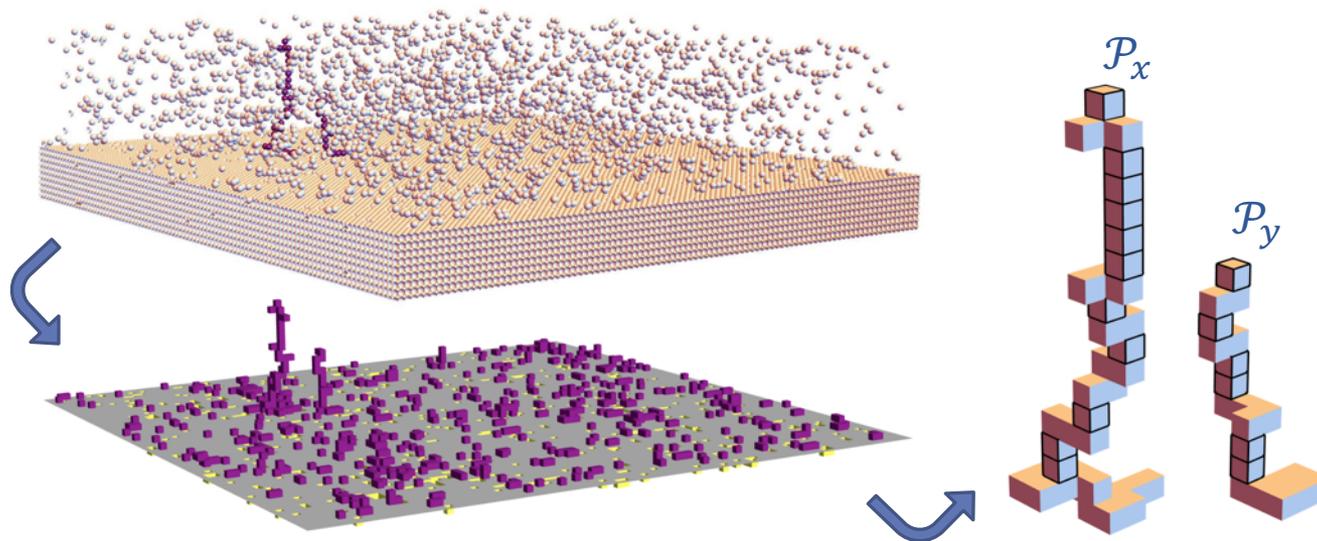
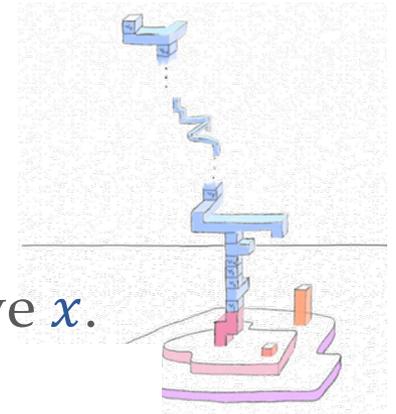
► PROPOSITION: ([Gheissari, L. '19b])

There *does not* exist a deterministic sequence  $(m_n)$  s.t.  $(M_n - m_n)$  converges weakly to a nondegenerate law.

# Pillars in the 3D Ising interface

DEFINITION: [ $\mathcal{P}_x$ , the **pillar** at  $x \in \mathbb{R}^2 \times \{0\}$ ]

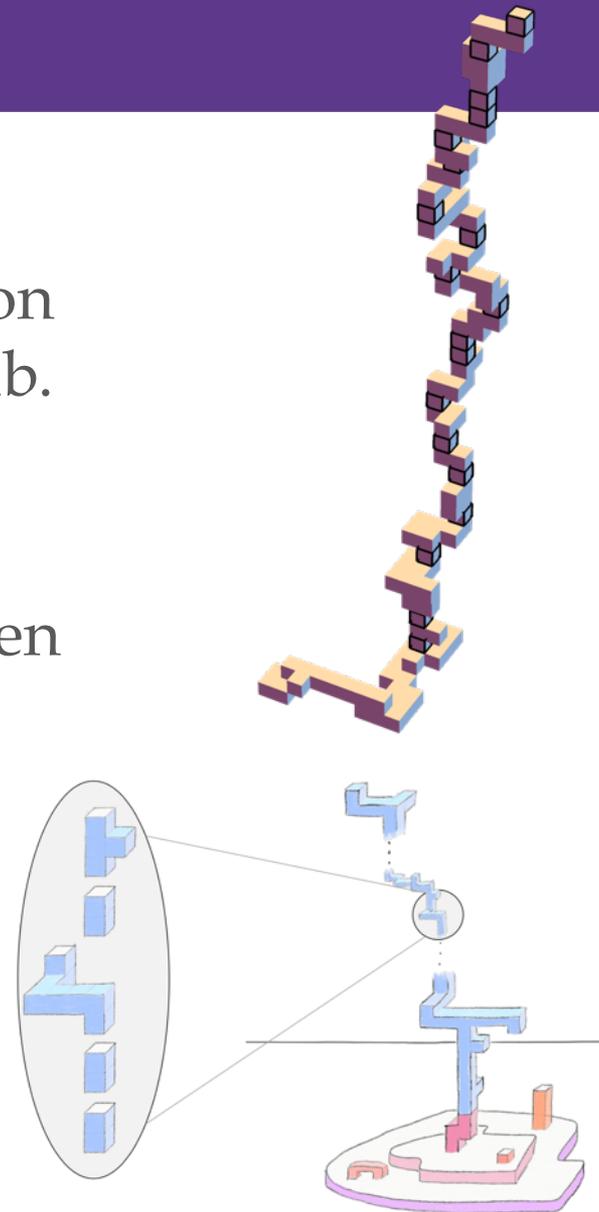
1. Fill in all the bubbles to obtain the interface  $\mathcal{I}$
2. Discard  $\mathbb{R}^2 \times (-\infty, 0)$  from the sites below  $\mathcal{I}$
3. The pillar  $\mathcal{P}_x$  is the remaining component above  $x$ .



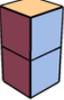
Goal: second moment argument for  $M_n = \max_x \text{ht}(\mathcal{P}_x)$

# Decomposition of pillars

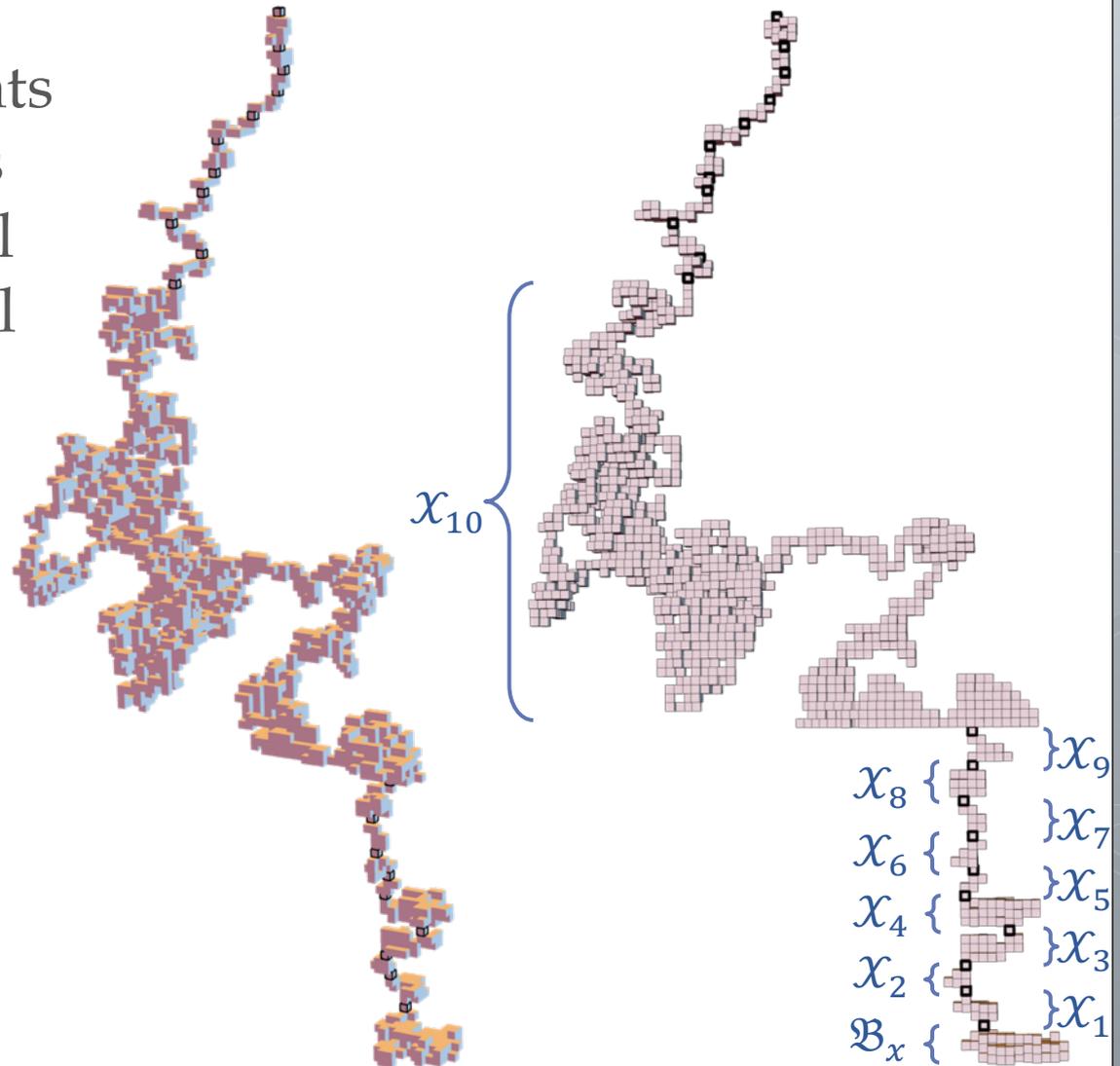
- ▶ DEFINITION: [**cutpoint** of the pillar]  
a cell  $v_i$  which is the only intersection of the pillar  $\mathcal{P}_x$  with a horizontal slab.
- ▶ DEFINITION: [**pillar increment**]  
 $\mathcal{X}_i =$  segment of  $\mathcal{P}_x$  bounded between the cutpoints  $v_i, v_{i+1}$  (inclusively).
- ▶ Decompose  $\mathcal{P}_x$  into:
  1. *increments*  $(\mathcal{X}_1, \mathcal{X}_2, \dots, \mathcal{X}_T)$
  2. *base*  $\mathcal{B}_x = \mathcal{P}_x \cap (\mathbb{R}^2 \times [0, \text{ht}(v_1)])$



# Decomposition of pillars

- ▶ Typical increments are perturbations (with exponential tails) of the trivial increment 

- ▶ But: (rarely) they can be quite complex...



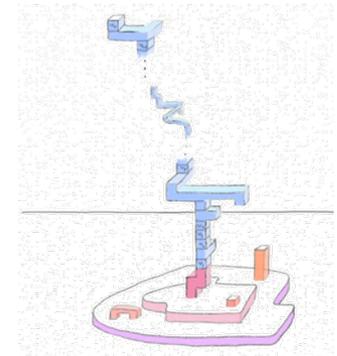
# Key ingredient: shape of tall pillars

▶ THEOREM: ([Gheissari, L. '19a,'19b])

$\exists \beta_0$  s.t. for  $\forall \beta > \beta_0$  and every  $x = (x_1, x_2, 0)$  is in the bulk (distance  $\geq h^2$  from  $\partial\Lambda$ ), conditional on  $\text{ht}(\mathcal{P}_x) \geq h$ ,

1. W.h.p.  $\mathcal{P}_x$  has at least  $(1 - \epsilon_\beta)h$  increments.
2.  $\forall t$ , the size of the increment  $\mathcal{X}_t$  has an exponential tail.
3. Base  $\mathcal{B}_x$  has an exponential tail on its diameter, height.

▶ Used to decorrelate  $\text{ht}(\mathcal{P}_x)$  and  $\text{ht}(\mathcal{P}_y)$  as part of the 2nd moment argument.



# Cluster expansion & Dobrushin's approach

- ▶ Peierls' classical phase transition argument eliminates bubbles, but is not enough to "flatten" the interface.
- ▶ Instead: do Peierls on *interfaces* via *cluster expansion*:

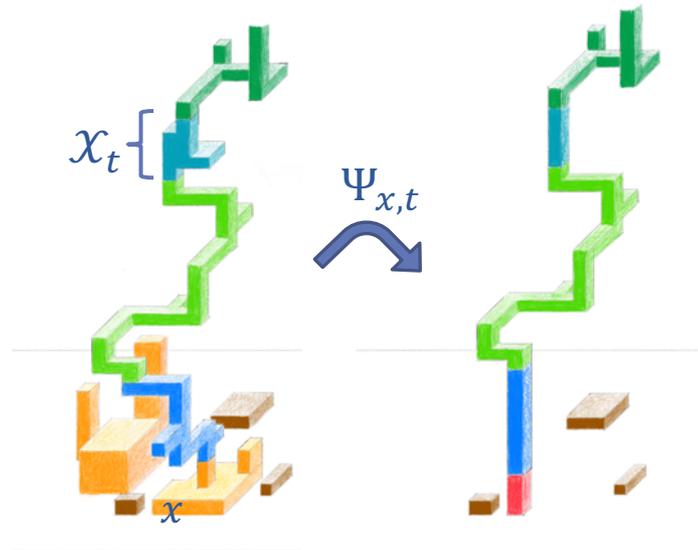
THEOREM: ([Minlos, Sinai '67], [Dobrushin '72])

$$\mu(\mathcal{J}) \propto \exp \left[ -\beta |\mathcal{J}| + \sum_{f \in \mathcal{J}} \mathbf{g}(f, \mathcal{J}) \right]$$

where  $\mathbf{g} \leq K_0$  and  $|\mathbf{g}(f, \mathcal{J}) - \mathbf{g}(f', \mathcal{J}')| \leq e^{-\bar{c} \mathbf{r}(f, \mathcal{J}, f', \mathcal{J}')}.$

- ▶ [Dobrushin '72] decomposed  $\mathcal{J}$  into groups of walls & ceilings, then defined a map that deletes a wall around  $x$ , flattening  $\mathcal{J}$  (2D analysis).

# The interface map $\Psi_{x,t}$

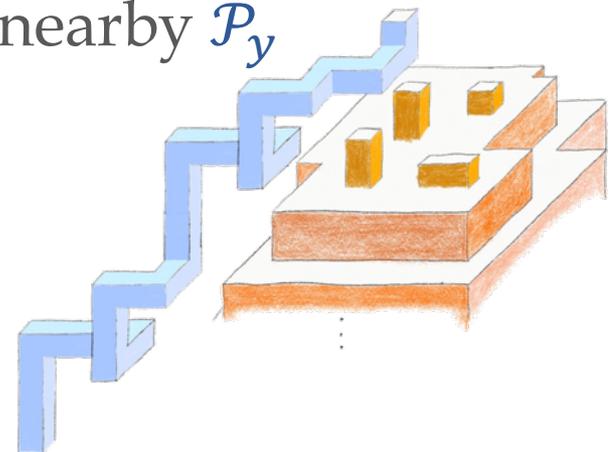
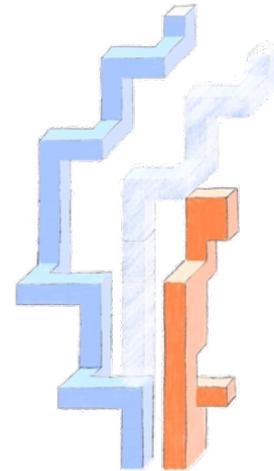


$\Psi_{x,t}: \{\mathcal{J}: \text{ht}(\mathcal{P}_x) \geq h, |\mathcal{B}_x| \vee |\mathcal{X}_t| \geq r\} \rightarrow \{\mathcal{J}: \text{ht}(\mathcal{P}_x) \geq h\}$  s.t.

1. Energy control:  $\mu(\mathcal{J}) \leq e^{-c\beta(|\mathcal{J}|-|\Psi_{x,t}(\mathcal{J})|)} \mu(\Psi_{x,t}(\mathcal{J}))$
2. Multiplicity control: at most  $e^{c\ell}$  many  $\mathcal{J} \in \Psi_{x,t}^{-1}(\mathcal{J}')$  such that  $|\mathcal{J}| - |\mathcal{J}'| = \ell$ .

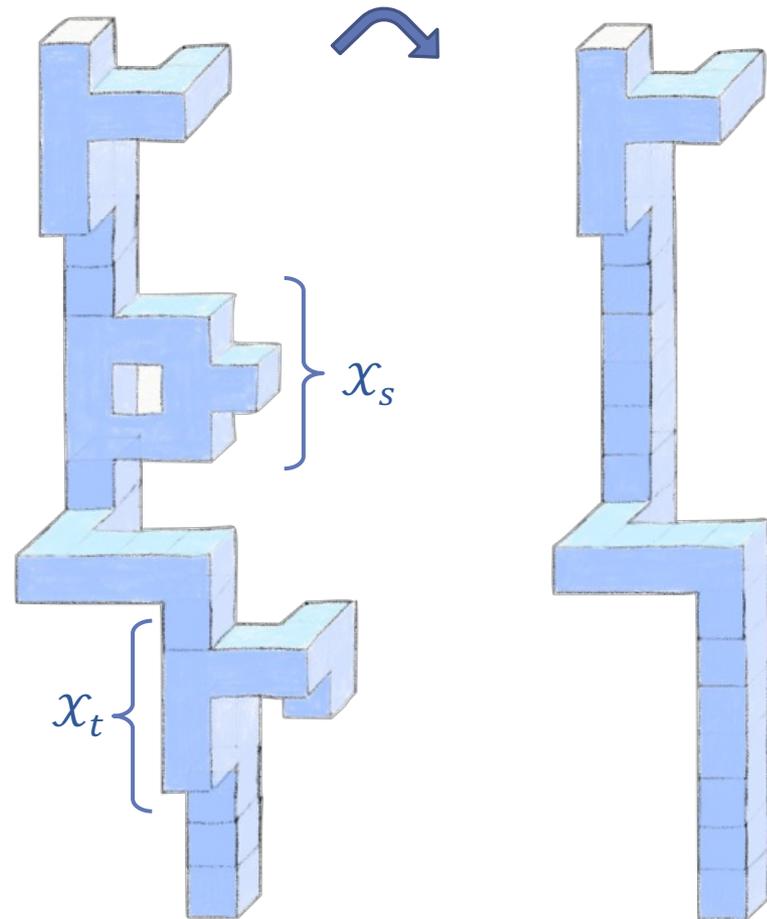
# Challenges due to interacting pillars

- ▶ The map  $\Psi_{x,t}$  induces
  1. horizontal shifts
  2. vertical shifts (down & up)
- ▶ The pillar  $\mathcal{P}_x$  to hit a nearby  $\mathcal{P}_y$  (possibly making the map not well-defined)
- ▶ The pillar may get very close to a nearby  $\mathcal{P}_y$  and heavily interact with it (destroying the energy control).



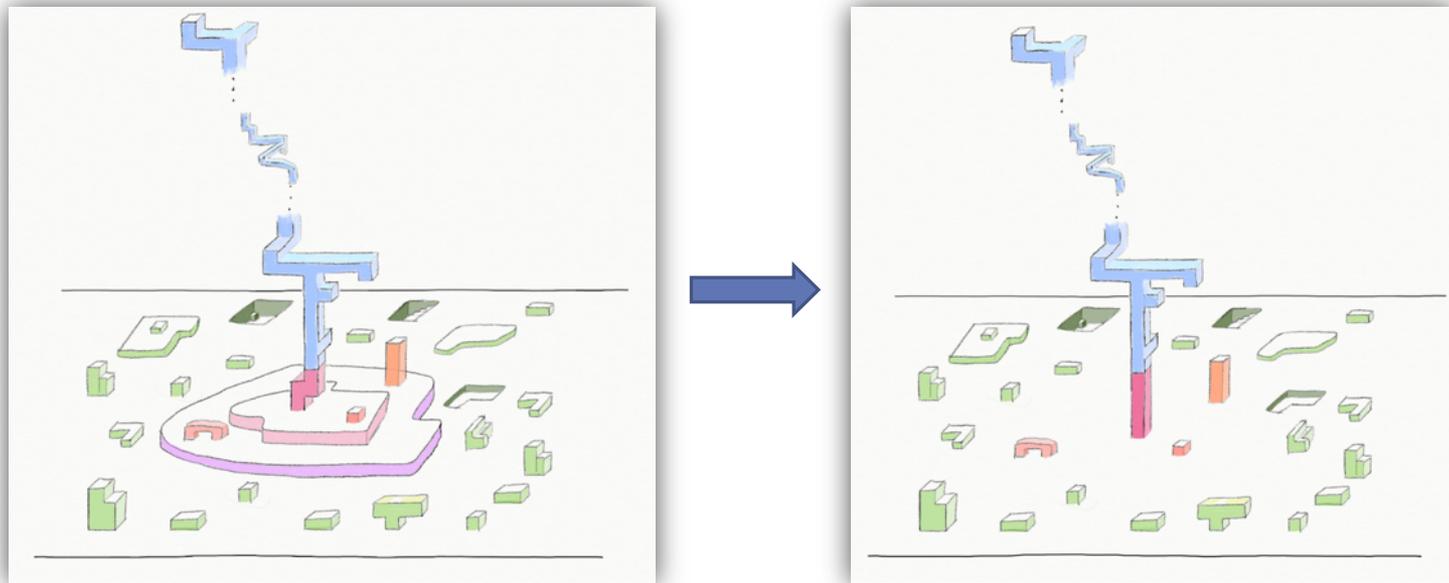
# A basic $\Psi_{x,t}$ for controlling increments

- ▶ Target the structure of the increment  $\mathcal{X}_t$  by:
  - ▶ straightening  $\mathcal{X}_t$  if its size is too large.
  - ▶ straightening any other increment  $\mathcal{X}_s$  for  $s \geq t$  whose size is at least  $e^{c|s-t|}$  (too large w.r.t.  $\mathcal{X}_t$ ).



# A basic $\Psi_{x,t}$ for controlling increments

- ▶ Base is delicate: incorporates interaction with other nearby pillars in the interface...
- ▶ Trying to extend the definition of the base so as to rule out such interactions gives an  $O(\log h)$  error on its size: sufficient for LLN but *not for tightness*.



# An algorithmic procedure to define $\Psi_{x,t}$

- ▶ Defining  $\Psi_{x,t}$  :
  - $\forall j \geq 1$ , determine whether to straighten  $\mathcal{P}_x$  at the increment  $\mathcal{X}_j$ . If so:
    - $\forall y \neq x$ , determine whether this action may cause  $\mathcal{P}_x$  to draw to closely to  $\mathcal{P}_y$ . If so, delete  $\mathcal{P}_y$  as well.
- ▶ Delicate balance between deleting too little (energy control) and deleting too much (multiplicity control).

---

## Algorithm 1: The map $\Psi_{x,t}$

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1 Let  $\{\tilde{W}_y : y \in \mathcal{L}_{0,n}\}$  be the standard wall representation of the interface  $\mathcal{I} \setminus \mathcal{S}_x$ . Also let  $\mathcal{O}_{v_1}$  be the
   nested sequence of walls of  $v_1$ , so that  $\partial_{\text{ST}} \mathcal{O}_{v_1} = \tilde{\mathfrak{W}}_{v_1}$ .

   // Base modification
2 Mark  $[x] = \{x\} \cup \partial_0 x$  and  $\rho(v_1)$  for deletion (where  $\partial_0 x$  denotes the four faces in  $\mathcal{L}_0$  adjacent to  $x$ ).
3 if the interface with standard wall representation  $\tilde{\mathfrak{W}}_{v_1}$  has a cut-height then
   | Let  $h^\dagger$  be the height of the highest such cut-height.
   | Let  $y^\dagger$  be the index of a wall that intersects  $(\mathcal{P}_x \setminus \mathcal{O}_{v_1}) \cap \mathcal{L}_{h^\dagger}$  and mark  $y^\dagger$  for deletion.

   // Spine modification (A): the 1st increment
4 Set  $s_1 \leftarrow 0$  and  $y_A^* \leftarrow \emptyset$ .
   for  $j = 1$  to  $\mathcal{F} + 1$  do
     | Let  $s \leftarrow s_j$  and  $s_{j+1} \leftarrow s_j$ .
     | if  $m(\mathcal{X}_j) \geq j - 1$  then // (A1)
     |   | Let  $s_{j+1} \leftarrow j$ .
     |   | if  $\mathfrak{D}_x(\tilde{W}_y, j, -v_{s+1}, 0) \leq m(\tilde{W}_y)$  for some  $y$  then // (A2)
     |   |   | Let  $s_{j+1} \leftarrow j$  and mark for deletion every  $y$  for which (A2) holds.
     |   | if  $\mathfrak{D}_x(\tilde{W}_y, j, -v_{s+1}, 0) \leq (j-1)/2$  for some  $y$  then // (A3)
     |   |   | Let  $s_{j+1} \leftarrow j$  and let  $y_A^*$  be the minimal index  $y$  for which (A3) holds.
     |   | Let  $j^* \leftarrow s_{\mathcal{F}+2}$  and mark  $y_A^*$  for deletion.

     // Spine modification (B): the  $t$ -th increment
5 if  $t > j^*$  then
     | Set  $s_t \leftarrow t - 1$  and  $y_B^* \leftarrow \emptyset$ .
     | for  $k = t$  to  $\mathcal{F} + 1$  do
       | Let  $s \leftarrow s_k$  and  $s_{k+1} \leftarrow s_k$ .
       | if  $m(\mathcal{X}_k) \geq k - t$  then // (B1)
       |   | Let  $s_{k+1} \leftarrow k$ .
       |   | if  $\mathfrak{D}_x(\tilde{W}_y, j, -v_{s+1}, v_t - v_{j+1}) \leq m(\tilde{W}_y)$  for some  $y$  then // (B2)
       |   |   | Let  $s_{k+1} \leftarrow k$  and mark for deletion every  $y$  for which (B2) holds.
       |   | if  $\mathfrak{D}_x(\tilde{W}_y, j, -v_{s+1}, v_t - v_{j+1}) \leq (k-t)/2$  for some  $y$  then // (B3)
       |   |   | Let  $s_{k+1} \leftarrow k$  and let  $y_B^*$  be the minimal index  $y$  for which (B3) holds.
       |   | Let  $k^* \leftarrow s_{\mathcal{F}+2}$  and mark  $y_B^*$  for deletion.
     | else
     |   | Let  $k^* \leftarrow j^*$ .

6 foreach index  $y \in \mathcal{L}_{0,n}$  marked for deletion do delete  $\tilde{\mathfrak{W}}_y$  from the standard wall representation ( $\tilde{W}_y$ ).
7 Add a standard wall  $W_x^{\mathcal{F}}$  consisting of  $\text{ht}(v_1) - \frac{1}{2}$  trivial increments above  $x$ .
8 Let  $\mathcal{K}$  be the (unique) interface with the resulting standard wall representation.
9 Denoting by  $(\mathcal{X}_i)_{i \geq 1}$  the increment sequence of  $\mathcal{S}_x$ , set
   S ← { (  $\overbrace{(\mathcal{X}_\emptyset, \mathcal{X}_\emptyset, \dots, \mathcal{X}_\emptyset, \mathcal{X}_{j^*+1}, \dots, \mathcal{X}_{t-1}, \mathcal{X}_\emptyset, \mathcal{X}_\emptyset, \dots, \mathcal{X}_\emptyset, \mathcal{X}_{k^*+1}, \dots)}$  ) if  $t > j^*$ ,
         {  $\overbrace{(\mathcal{X}_\emptyset, \mathcal{X}_\emptyset, \dots, \mathcal{X}_\emptyset, \mathcal{X}_{j^*+1}, \dots)}$  ) if  $t \leq j^*$ .
         |  $\text{ht}(v_{j^*+1}) - \text{ht}(v_1)$ 
         |  $\text{ht}(v_{k^*+1}) - \text{ht}(v_1)$ 
         |  $\text{ht}(v_{j^*+1}) - \text{ht}(v_1)$ 
         |  $\text{ht}(v_{j^*+1}) - \text{ht}(v_1)$ 

10 Obtain  $\Psi_{x,t}(\mathcal{I})$  by appending the spine with increment sequence  $\mathcal{S}$  to  $\mathcal{K}$  at  $x + (0, 0, \text{ht}(v_1))$ .

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# LLN: sub/super-multiplicativity?

- ▶ Important ingredient for the LLN: establishing

$$\exists \lim_{h \rightarrow \infty} -\frac{1}{h} \log \mu_{\Lambda}^{\bar{\Gamma}}(\text{ht}(\mathcal{P}_x) \geq h).$$

- ▶ Natural route: establish sub/super-multiplicativity:

1. Move from  $\{\text{ht}(\mathcal{P}_x) \geq h\}$  to a comparable event in  $\mathbb{Z}^3$ :

$$A_h = \left\{ x \overset{+}{\longleftrightarrow} \mathbb{R}^2 \times \{h\} \text{ in } \mathbb{R}^2 \times [0, \infty) \right\}.$$

2. If translation invariant, FKG can typically give

$$\mu_{\mathbb{Z}^3}^{\bar{\Gamma}} \left( 0 \overset{+}{\longleftrightarrow} (0,0, h_1 + h_2) \right) \geq \mu_{\mathbb{Z}^3}^{\bar{\Gamma}} \left( 0 \overset{+}{\longleftrightarrow} (0,0, h_1) \right) \mu_{\mathbb{Z}^3}^{\bar{\Gamma}} \left( 0 \overset{+}{\longleftrightarrow} (0,0, h_2) \right).$$

3. **But**  $\mu_{\mathbb{Z}^3}^{\bar{\Gamma}}$  is more negative at height  $h_1$  than at height 0 !

# LLN: sub-multiplicativity

- ▶ To show that  $\mu_{\mathbb{Z}^3}^{\bar{+}}(\text{ht}(\mathcal{P}_x) \geq h)$  is sub-multiplicative:
  1. Move from  $\{\text{ht}(\mathcal{P}_x) \geq h\}$  to a comparable event in  $\mathbb{Z}^3$ :
$$A_h = \left\{ x \overset{+}{\leftrightarrow} \mathbb{R}^2 \times \{h\} \text{ in } \mathbb{R}^2 \times [0, \infty) \right\}.$$
  2. Condition on the  $+$ -cluster of  $x$  in  $\mathbb{R}^2 \times [0, h_1]$ .  
*Note: this cluster contains **positive** information, notably in its intersection with  $\mathbb{R}^2 \times \{0\}$  ...*
- ▶ Need to show:
  - For LLN: effect of this positive information is  $e^{o(h_1)}$ .
  - For tightness: effect of this positive information is  $O(1)$  !
- ▶ Key: structure of  $\mathcal{P}_x$  conditioned on  $\{\text{ht}(\mathcal{P}_x) \geq h_1\}$ .

# 2 → 2 maps: mixing and stationarity

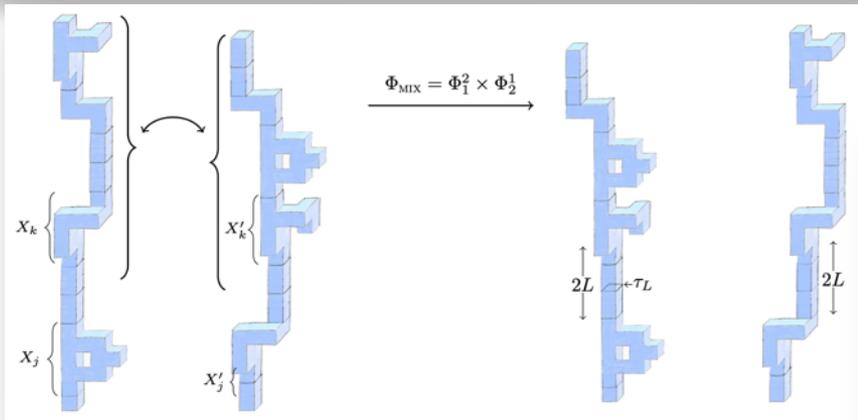
► More refined info on shape conditional on  $ht(\mathcal{P}_x) \geq h$ :

THEOREM: ([Gheissari, L. '19a])

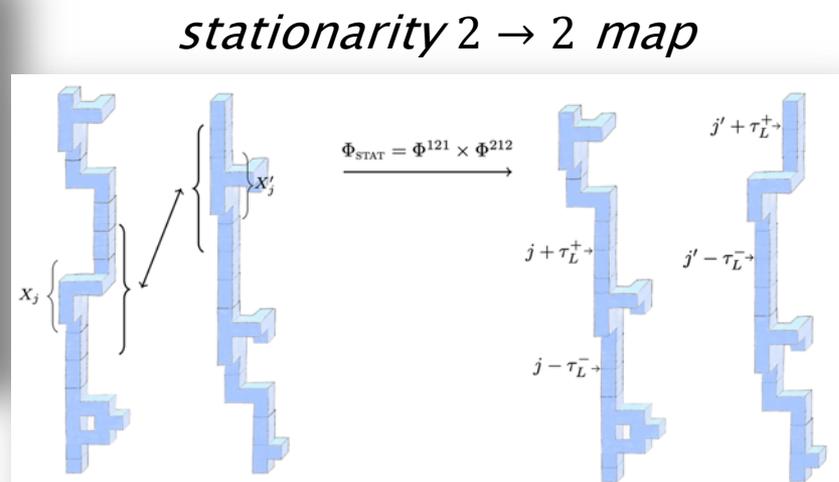
3. (mixing)  $\forall i, j, \text{Cov}(X_i, X_j) \leq C|j - i|^{-100}$ .

4. (stationarity)  $\exists$  stationary distribution  $\nu$  on  $\mathfrak{X}^{\mathbb{Z}}$  such that

$$\left( \dots, X_{h/2-1}, X_{h/2}, X_{h/2+1}, \dots \right) \xrightarrow{h \rightarrow \infty} \nu$$



*mixing 2 → 2 map*



*stationarity 2 → 2 map*

# CLT for pillar increments

▶ THEOREM: ([Gheissari, L. '19a])

For every  $\kappa$  there exists  $\beta_0(\kappa)$  such that for all  $\beta > \beta_0$ :  
If  $f: \mathfrak{X} \rightarrow \mathbb{R}$  is a non-constant functional on increments s.t.

$$f(X) \leq \exp[\kappa |X|] \quad \forall X$$

and  $x = (x_1, x_2, 0)$  is in the bulk, then conditional on  $\mathcal{P}_x$   
having at least  $1 \ll T_n \ll n$  increments,

$$\frac{1}{\sqrt{T_n}} \sum_{i \leq T_n} (f(X_i) - \mathbb{E}f(X_i)) \xrightarrow{d} \mathcal{N}(0, \sigma)$$

for some  $\sigma(\beta, f) > 0$ .

- ▶ Proof uses a Stein's method treatment of stationary mixing sequences of random variables à la [Bolthausen '82].

# CLT for location of tip, volume, surface area

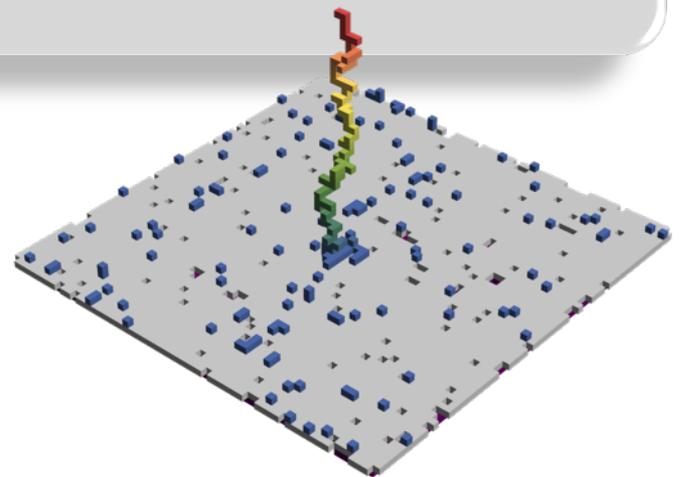
- ▶ COROLLARY: ([Gheissari, L. '19a])

Let  $(Y_1, Y_2, \text{ht}(\mathcal{P}_x))$  be the location of the tip of the pillar  $\mathcal{P}_x$ .  
Conditional on  $\mathcal{P}_x$  having at least  $1 \ll T_n \ll n$  increments,

$$\frac{(Y_1, Y_2, \text{ht}(\mathcal{P}_x)) - (x_1, x_2, \lambda T_n)}{\sqrt{T_n}} \xrightarrow{d} \mathcal{N}\left(0, \begin{pmatrix} \sigma^2 & 0 & 0 \\ 0 & \sigma^2 & 0 \\ 0 & 0 & (\sigma')^2 \end{pmatrix}\right)$$

for some  $\sigma, \sigma' > 0$ .

- ▶ CLT also holds, e.g., for the surface area and volume of  $\mathcal{P}_x$ .



# Open problems

- ▶ Open problems on  $M_n$  :

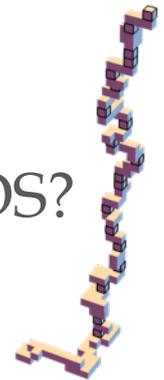
- How does the LD quantity  $\alpha$  depend on  $\beta$ ?

(*know*:  $\alpha = (4 \pm o_\beta(1))\beta$ .)

Is  $\alpha < 4\beta$ , so Ising interfaces are **rougher** than SOS?

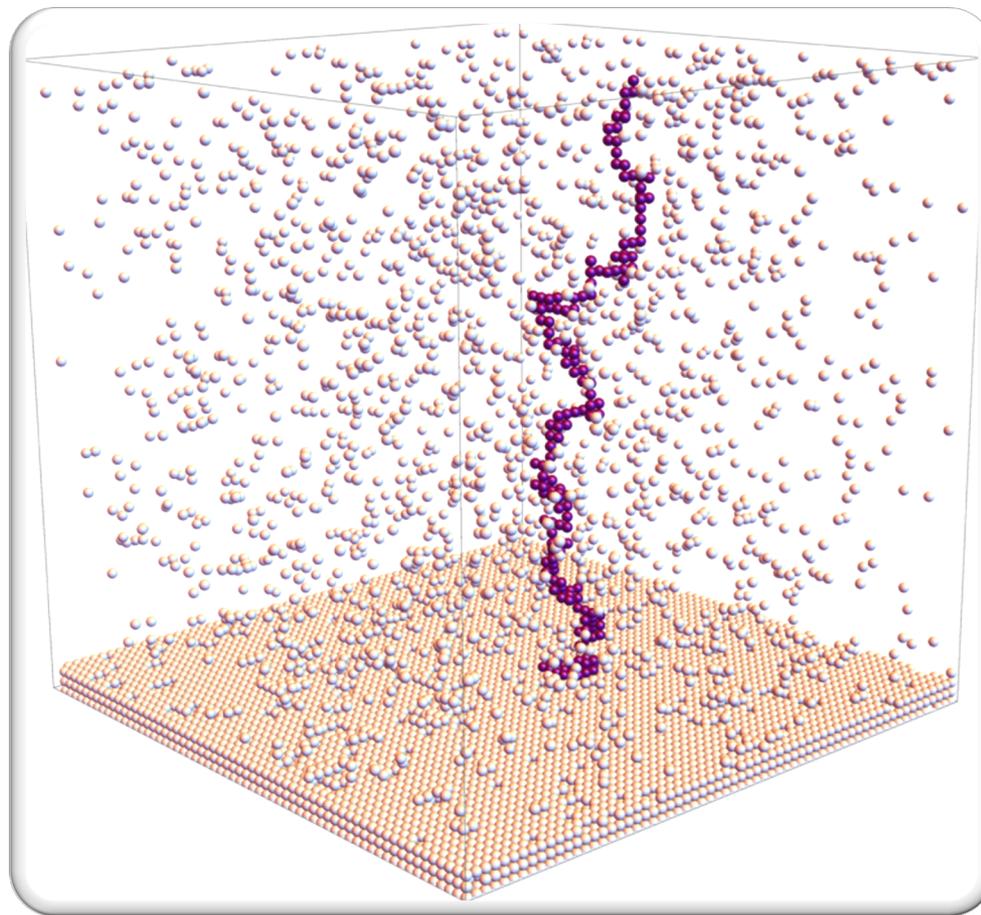
- Asymptotics of  $\mathbb{E}[M_n]$ ?

(*know*:  $\frac{2}{\alpha_\beta} \log n + o_n(\log n)$ .)



- ▶ Major open problems on the interface  $\mathcal{I}$ :

- **Roughness** of *tilted* interfaces? (*conj.*:  $\text{Var}(\text{ht}_x(\mathcal{I})) \asymp \log n$ )
- *Roughening phase transition*? (*conj.*:  $\beta_R > \beta_c \iff d = 3$ ).



Thank you!