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and the fluctuation - dissipation balance

condition

self adjoint

$$\rightarrow B B^* = \frac{1}{2} (N + N^*) = M(x) = M^*(x)$$

where $M(x)$ is the dissipative part of the mobility operator $N(x)$. The remaining part is conservative dynamics

skew adjoint

$$L = \frac{1}{2} (N^* - N) = -L^*$$

$$\frac{dH(x)}{dt} = \frac{\partial H}{\partial x} \cdot \frac{\partial x}{\partial t} = \frac{\partial H}{\partial x} \cdot M \cdot \frac{\partial H}{\partial x} \leq 0$$

Now we want to generalize this to more realistic fluids, where fluid flow is important.

As coarse-grained variables we must choose slow variables, and physical intuition suggests the conserved fields

$$X \equiv \begin{bmatrix} \rho(r, t) \\ \vec{j}(r, t) \\ e(r, t) \end{bmatrix} \left. \begin{array}{l} \text{mass} \\ \text{momentum} \\ \text{energy} \end{array} \right\} \text{density}$$

Defining these coarse variables precisely is rather non-trivial (see Thomas's talk),

but intuitively:

$$\left[\begin{array}{l} S(\vec{r}) \rightarrow \\ \vec{j} = S \vec{v} \\ \\ e = \frac{1}{2} S v^2 + \mathcal{E} \end{array} \right] \approx \sum_{i=1}^N \left[\begin{array}{l} m_i \\ m_i \vec{v}_i \\ \\ m_i \frac{v_i^2}{2} \end{array} \right] \delta_a(\vec{r} - \vec{r}_i)$$

internal energy
particles

Here $\delta_a(\vec{r})$ is a modified delta function of compact support of size $a =$
coarse-graining scale

We will consider here a simplified
isothermal model

$$T = \text{const}$$

which means we will assume that
 temperature is a fast variable maintained
 by contact with an external thermal
 (heat bath) and thus the
 internal energy

$$E(S, T) \approx E(S)$$

and

$$X \equiv \begin{bmatrix} S \\ j = S v \end{bmatrix} \leftarrow \begin{array}{l} \text{fluid} \\ \text{velocity} \end{array}$$

We postulate that the coarse-grained Hamiltonian or free-energy functional is

$$H[\rho, j] = \int \left[\frac{j^2}{2\rho} + \epsilon(\rho) \right] dr$$

|||
 $\frac{\rho v^2}{2}$ (kinetic energy)
 center-of-mass

and that the equilibrium Gibbs distribution is

$$P(x) = Z^{-1} \exp \left\{ - \frac{H[\rho, j]}{k_B T} \right\}$$

The coarse-grained dynamics is

$$\partial_t x = -N(x) \cdot \frac{\partial H}{\partial x} + \text{fluctuations}$$

where

$$\frac{\partial H}{\partial x} = \begin{bmatrix} \frac{\partial H}{\partial \mathbf{g}} \\ \frac{\partial H}{\partial \mathbf{j}} \end{bmatrix} = \begin{bmatrix} -\frac{\mathbf{j} \cdot \mathbf{2}}{2g^2} + \epsilon'(\mathbf{s}) \\ \frac{\mathbf{j}}{\mathbf{s}} = \vec{v} \end{bmatrix}$$

Now we need the mobility operator

$$N(x) =$$

$$\begin{bmatrix} N_{gg} & N_{g\omega} \\ N_{\omega g} & N_{\omega\omega} \end{bmatrix}$$

In fluids, mass is transported by advection (or convection), meaning, by directed (instead of diffusive) transport.

Mass conservation is thus microscopically exact and we postulate / state (see Landau - Lifshitz) that

MASS
CONSERVATION

$$\partial_t \rho = -\nabla \cdot (\mathbf{j}) = -\nabla \cdot (\rho \mathbf{v})$$

CONTINUITY
EQUATION

which can in fact be thought of as the correct definition for \mathbf{v} .

So we have

$$\textcircled{1} \quad N_{SS} = 0 \quad \text{and}$$

$$N_{S\psi} = -\frac{\partial}{\partial r} \cdot \mathcal{S}$$

so that $N_{S\psi} \cdot \frac{\partial H}{\partial j} = -\nabla \cdot \left(\mathcal{S} \frac{j}{S} \right) = -\nabla \cdot (j)$
for the continuity equation

$\textcircled{2}$ The reverse coupling $N_{\psi S}$ must be the skew adjoint of $N_{S\psi}$ since there is no dissipation associated with density, i.e., since

$$N_{SS} = 0$$

$$N_{\psi S} = -N_{S\psi}^* = -\mathcal{S} \frac{\partial}{\partial r}$$

This gives a term in the momentum equation

$$\begin{aligned} \partial_t j &= -\rho \frac{\partial}{\partial r} \left(\frac{\partial H}{\partial \rho} \right) + \dots = \\ &= \rho \frac{\partial}{\partial r} \left(\frac{v^2}{2} \right) - \rho \frac{\partial}{\partial r} [\epsilon'(\rho)] \end{aligned}$$

To write the second term more explicitly, we write

$$\rho \frac{\partial}{\partial r} [\epsilon'(\rho)] = \rho \frac{\nabla P}{\rho} = \nabla P$$

where $\boxed{P(\rho) = \rho \epsilon'(\rho) - \epsilon(\rho)}$ is the pressure

For the momentum-momentum coupling

N_{ov} we just state the result:

$$L_{ov} = \frac{\partial j}{\partial r} + j \frac{\partial}{\partial r} = - \left(\frac{\partial j}{\partial r} + j \frac{\partial}{\partial r} \right)^T$$

↑
advective or non-dissipative part of the
dynamics (skew-adjoint)

Component-wise

$$(L_{ov})_{\alpha\beta} = - \frac{\partial j_{\alpha}}{\partial r_{\beta}} - j_{\beta} \frac{\partial}{\partial r_{\alpha}}$$

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$$\left[(L_{\varphi\varphi}) \cdot \frac{\partial H}{\partial j} + \int_{\text{from } \mathcal{S}} \frac{\partial}{\partial r} \left(\frac{\varphi^2}{2} \right) \right]_{\alpha} =$$

$$\int \frac{\partial}{\partial r_{\alpha}} \left(\frac{\varphi_{\beta} \varphi_{\beta}}{2} \right) - \frac{\partial}{\partial r_{\beta}} j_{\alpha} \varphi_{\beta} - j_{\beta} \frac{\partial \varphi_{\beta}}{\partial r_{\alpha}}$$

$$= \int (\nabla \varphi) \cdot \varphi - \nabla \cdot (\varphi j) - (\nabla \varphi) \cdot j$$

$$= (\nabla \varphi) \cdot j - \nabla \cdot (\varphi j) - (\nabla \varphi) \cdot j = -\nabla \cdot (\varphi j)$$

which is a divergence of an advective flux $\boxed{\varphi \cdot j}$ as expected.

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Putting the pieces together, we get
for the non-dissipative (reversible,
conservative, Hamiltonian) dynamics
the Euler equations

$$\begin{cases} \partial_t \rho = -\nabla \cdot (\rho \mathbf{v}) \\ \partial_t (\rho \mathbf{v}) = -\nabla \cdot (\rho \mathbf{v} \mathbf{v}) - \nabla P(\rho) + \text{dissipation fluctuation} \end{cases}$$

⇓

$$\begin{cases} \rho (\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v}) = -\nabla P \\ \partial_t \rho + \mathbf{v} \cdot \nabla \rho = -\rho (\nabla \cdot \mathbf{v}) \end{cases}$$

Momentum, unlike mass, is transferred between particles via interactions (collisions, forces), i.e., non-advectively.

This would lead to additional stress terms in the momentum equation:

$$\partial_t \vec{j} = - \nabla \cdot (\overset{\leftrightarrow}{\sigma}) + \text{advective}$$

$$= \nabla \cdot \left[\overset{\leftrightarrow}{\eta} \overset{\leftarrow}{\nabla} \left(\frac{\partial H}{\partial \vec{j}} \right) \right] = \nabla \cdot (\overset{\leftrightarrow}{\eta} \overset{\leftarrow}{\nabla} \overset{\leftrightarrow}{\varphi})$$

rank four viscosity tensor $\succcurlyeq 0$

For isotropic fluids (simple Newtonian liquids and gases), it can be shown by symmetry arguments that

$$\overleftrightarrow{\eta}(\overleftrightarrow{\nabla}\overleftrightarrow{\varphi}) = \underbrace{\eta}_{\text{shear viscosity}} \left(\overleftrightarrow{\nabla}\overleftrightarrow{\varphi} + \overleftrightarrow{\nabla}^T\overleftrightarrow{\varphi} \right) + \underbrace{K}_{\text{bulk viscosity}} (\overleftrightarrow{\nabla} \cdot \overleftrightarrow{\varphi}) \mathbf{I}$$

$$M = \frac{1}{2} (N + N^*) = - \frac{\partial}{\partial r} \cdot \overleftrightarrow{\eta} \frac{\partial}{\partial r} = B B^*$$

$$\Rightarrow B = \frac{\partial}{\partial r} \cdot \overleftrightarrow{\eta}^{1/2}$$

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This means that the fluctuating or stochastic stress tensor $\tilde{\sigma}$ is

$$(2k_B T)^{1/2} B \cdot W(t) = \nabla \cdot (\tilde{\sigma})$$

$$\tilde{\sigma} = (2k_B T \overset{\leftrightarrow}{\eta})^{1/2} \overset{\uparrow}{\text{white noise}} W(r, t)$$

giving the equations of fluctuating hydrodynamics

$$\rho (\partial_t \mathcal{U} + \mathcal{U} \cdot \nabla \mathcal{U}) = -\nabla P + \nabla \cdot [\overset{\leftrightarrow}{\eta} \nabla \mathcal{U} +$$

$$\text{or } \rho (D_t \mathcal{U}) \leftarrow \text{material derivative} \quad (2k_B T \overset{\leftrightarrow}{\eta})^{1/2} W(r, t)]$$

$$D_t \rho = -\rho (\nabla \cdot \mathcal{U}) = 0 \text{ if } \underline{\text{incompressible}}$$

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These equations revert to the usual compressible isothermal Navier-Stokes equations when fluctuations are neglected. The stochastic terms ensure that the Gibbs distribution (canonical ensemble) is preserved

$$P_{eq} = Z^{-1} \exp \left[-\frac{1}{k_B T} \int \left(\frac{\rho \psi^2}{2} + \mathcal{E}(\rho) \right) dr \right]$$

Consider fluctuations at equilibrium

$$(\rho, \psi) = (\rho_0 + \delta \rho, \delta \psi)$$

and linearize to leading order in the fluctuations

$$H = \int \left[\frac{\rho_0 v^2}{2} + \epsilon(\rho) \right] dr \approx \int \left[\frac{\rho_0 (\delta v)^2}{2} + \frac{\epsilon''(\rho_0) (\delta \rho)^2}{2} \right] dr$$

$$\Rightarrow P_{eq} \sim \exp \int dr \left[\frac{(\delta v)^2}{2 (k_B T / \rho_0)} + \frac{(\delta \rho)^2}{2 (k_B T / \epsilon''(\rho_0))} \right]$$

This means (see earlier lecture) that at equilibrium both the density and the velocity are spatially-white and uncorrelated

$$\begin{aligned} \langle v(r) v(r') \rangle &= \frac{k_B T}{\rho_0} \mathbf{I}_d \cdot \delta(r-r') \\ \langle \rho(r) \rho(r') \rangle &= k_B T / \epsilon''(\rho_0) \delta(r-r') \end{aligned}$$

In terms of physical parameters

$$\epsilon''(\rho_0) = \frac{1}{\rho} \frac{dP(\rho)}{d\rho} = \frac{c^2}{\rho}$$

where c is the isothermal speed of sound, the density fluctuations are

$$\langle (\delta \rho_{\Delta V})^2 \rangle = \frac{(k_B T) \rho_0}{(\Delta V) c^2} \rightarrow 0 \text{ if } c \rightarrow \infty \text{ (incompressible fluid)}$$

For an ideal gas $c^2 = \frac{k_B T}{m} \Rightarrow$

$$\langle (\delta \rho_{\Delta V})^2 \rangle = \frac{\rho_0 m}{\Delta V} = \frac{\langle \delta N_{\Delta V}^2 \rangle m^2}{\Delta V^2} = \frac{m^2 N_{\Delta V}}{\Delta V^2}$$

$$\Rightarrow \langle (\delta N_{\Delta V})^2 \rangle = N_{\Delta V} \leftarrow \begin{array}{l} \text{number of} \\ \text{molecules in} \\ \text{volume } \Delta V \end{array}$$

↑
Poisson process

Note that these are the same sort of fluctuations that arise for diffusive dynamics but here there is no diffusion of mass (only momentum).

The fluctuating hydrodynamics formalism and equations obtained here can be extended to many other cases (non-isothermal, fluid mixtures, etc.).