

# Fast Reactive Brownian Dynamics

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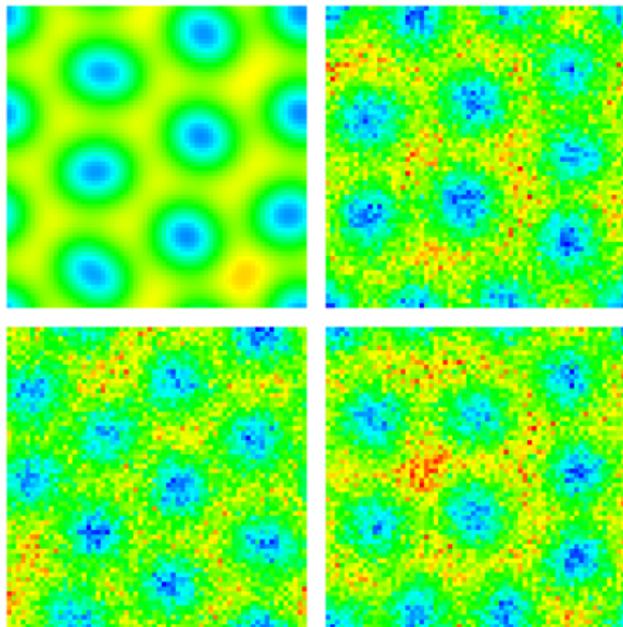
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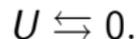
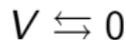
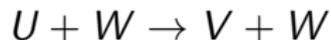
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# Example: Turing-Like Patterns



We want to understand the role fluctuations play in the formation of the Turing pattern.

- Consider a Petri dish with solution of three “chemical” species  $U$ ,  $V$  and  $W$  that can **diffuse and react** via:



- We use parameters giving a limit cycle together with  $D_V = D_W = D_U/10$  to get a **Turing-like pattern**.

# Chemical Reactions in Solution

- Many chemical reactions occur in a viscous solvent and are **affected by diffusion**, making a mean-field or “well-mixed” deterministic reaction-diffusion PDE approximation inappropriate.
- Classical examples where the **Law of Mass Action (LMA)** reaction-diffusion equations **fails spectacularly** is annihilation  
 $A + B \rightarrow 0$   
But even in  $A + B \rightleftharpoons C$  there are power-law tail signatures in the dynamics even at chemical equilibrium.
- **Spatial fluctuations play a key role** and spatial diffusion must be accounted for; this is different from (in addition to) fluctuations coming from there being **very few reactants** of certain species.
- Primarily interested in the case when **fluctuations are weak**, i.e., lots of molecules are involved, but fluctuations still make a difference.

# Grid-Based Methods

- The traditional approach to simulation of reaction-diffusion problems is to solve the **Reaction-Diffusion Master Equation** (RDME), which has the following issues:
  - Diffusion events/hops dominate when cells are “well-mixed” (they must be!) making solving the RDME exactly **expensive** (but one can do **multinomial diffusion** and/or **tau leaping** to speed things up).
  - Diffusion is modeled by a jump process instead of the more physical continuous random walk leading to a **fluctuating Fick’s law** (fluctuating hydrodynamics [1]).
  - LMA is postulated instead of following from the model; this requires **effective macroscopic rates** instead of microscopic ones. LMA is **missing a length scale (reactive distance)**.
  - The results depend strongly on the cell size and are thus **not grid-independent**: **binary reactions lost as cell size shrinks** [2] See Sam Isaacson’s **Convergent RDME** (CRDME) [3] for one *grid-based* fix (reactions between neighboring cells).

# Particle-Based Methods

- Particles are modeled as species-labeled spheres that diffuse as **independent Brownian walkers** (but note importance of **hydrodynamic interactions**) and react based on a microscopic reaction rule.
- Particle methods are **grid-free** and **closure-free** (they take reactive length scale as input).
- Key problem is **lack of efficiency**. This is what I address in this talk.
- To handle reactions two models are commonly used:
  - In the **surface-reactivity / Smoluchowski model** particles react **upon touching**.  
This automatically includes **steric repulsion** but lacks a mechanism to control reaction rate (but one can introduce unbinding).
  - In the **volume-reactivity / Doi model** particles react with a certain Poisson reaction rate **while they overlap**.  
This allows to separately and independently control the reactive distance and the effective reaction rate [2].

# Particle Algorithms

- The Smoluchowski model can be simulated **exactly** by the event-driven **First Passage Kinetic Monte Carlo** method (FPKMC) [4], called **eGFRD** in the biochemical community.
- FPKMC becomes **inefficient** at larger densities, it is **hard to generalize**, and it is **quite complicated** to implement.
- Approximate **reactive Brownian Dynamics** exist (e.g., Smoldyn) but they make **uncontrolled approximations** in diffusion and reactions.
- The Doi model is much simpler and more flexible so we use it here. Consider  $A + B \rightarrow \dots$ 

Particles are spheres of a given reactive radius  $R_A$  and  $R_B$ . They diffuse as independent Brownian walkers, and **while two particles overlap** ( $r_{AB} \leq R_A + R_B$ ) they react as a Poisson process with a given rate  $\lambda$ . Only binary reactions are allowed.
- Use our **Split Reactive Brownian Dynamics (SRBD)** to simulate Doi model efficiently with controlled accuracy!

# Time Splitting

SRBD is a combination of ideas taken from the **Isotropic Direct Simulation Monte Carlo** (IDSMC) algorithm (used for simulating binary collisions in low-density gases) and the **next subvolume method** for solving the RDME:

- Strang **time splitting** is used to separate diffusion from reaction ( $\mathbf{D}/2+\mathbf{R}+\mathbf{D}/2$ ). This is the only error introduced so **error is controlled** by reducing the time step size  $\Delta t$ .
- Simulating the diffusion exactly without reactions is trivial and inexpensive for independent Brownian walkers:

$$\mathbf{q}_k(t + \Delta t) = \mathbf{q}_k(t) + \sqrt{2D_k\Delta t}\mathcal{N}(0, 1)$$

One can include hydrodynamic interactions (expensive!).

- The difficult part is to **simulate reactions exactly** while particles are stationary (fixed). This is our key contribution.

It is possible to make some approximations and speed this up greatly but we want to control the error by a single parameter  $\Delta t$ .

# Selecting Reactions

- An obvious but very slow method is to first make a list of all overlapping pairs of particles, and then use a Gillespie-like / SSA / KMC algorithm to select pairs to react in sequence.
- The key idea is to accomplish the same (in law) without making a list of all overlapping pairs, by using an **event-driven algorithm** not on particle pairs but on grid cells!
- Introduce back a **computational grid which is not part of model** (think of neighbor search in MD) with spacing larger than all potential reactive distances:  
**Particles can only overlap/react with a particle in their own cell or neighboring cells.**
- **For each cell  $i$ , schedule the next potential binary reaction** between a particle in cell  $i$  and a particle in the neighborhood of cell  $i$  (9 cells in 2D or 27 cells in 3D).
- Make an **event queue** (heap) of all cells, and then process reactions by choosing the next cell (next subvolume) in which to try a reaction.

# Basic Time Stepping Algorithm

- 1 Diffuse for half a time step

$$\mathbf{q}_k^{n+\frac{1}{2}} = \mathbf{q}_k^n + \sqrt{D_k \Delta t} \mathcal{N}(0, 1)$$

- 2 Prepare: Build **linked-list cells** (LLCs) and schedule next reaction for each cell (if before time  $\Delta t$ ) and **build an event queue**.
- 3 Event Loop: Until the event queue is empty, do:
  - 1 Select cell  $i$  on top of queue with time stamp  $t^n \leq t \leq t^n + \Delta t$ .
  - 2 Select next reaction to happen in cell  $i$  using usual KMC/SSA method.
  - 3 Process the reaction (if particles overlap for binary), creating/destroying/updating particles+LLCs as necessary.
  - 4 For each cell  $i$  (potentially) affected by reaction, compute the total reaction rate  $\alpha$ , sample an exponentially-distributed  $\delta t$  with mean  $\alpha^{-1}$ . If  $t_i = t + \delta t < t + \Delta t$  schedule next event at time  $t_i$  and update event queue, otherwise delete cell  $i$  from queue.
- 4 Diffuse remaining/new particles for half a time step

$$\mathbf{q}_k^{n+1} = \mathbf{q}_k^{n+\frac{1}{2}} + \sqrt{D_k \Delta t} \mathcal{N}(0, 1)$$

# Scheduling Reactions

- For reactions with different reactants  $A + B \rightarrow \dots$  with rate  $\lambda$ , we schedule separately  $A + B \rightarrow \dots$  and  $B + A \rightarrow \dots$ 
  - For binary reaction  $r$  of form  $A + B \rightarrow \dots$  (order matters!), the propensity function (rate) for cell  $i$  is

$$\alpha_r = \frac{\lambda}{2} N_A N'_B$$

where  $N_A$  is the number of  $A$  particles in cell  $i$ , and  $N'_B$  is the total number of  $B$  particles in the neighborhood of  $i$ .

- For  $A + A \rightarrow 0$ , the rate is  $\alpha_r = \frac{\lambda}{2} N_A N'_A$  since pairs are counted twice (we reject self-reactions later).
- We add all the rates in each cell,  $\alpha = \sum_{r=1}^{N_r} \alpha_r$  (as in ordinary SSA).
- Note that this over-estimates the actual rate since it does not account for whether the particles actually overlap; we correct for this using rejection: **If a pair is selected to react does not overlap (or the same particle  $A$  is selected twice) we reject the pair.**

# Processing Reactions

Once we select the next cell  $i$  to *potentially* have a reaction using the event queue, we need to:

- Select a particle at random from cell  $i$  of the first reactant species, and another particle of the second reactant species from the neighborhood of  $i$  (can be the same particle twice!).
- Test if the two particles are within their reactive distance, and if not, do nothing.
- Otherwise, process the reaction by deleting and adding particles (see next slide) depending on the reaction.
- While doing this, keep track of whether any event is processed that changes the population of cell  $i$  (number of particles of each species), and also whether the population of a neighboring cell  $j$  changes.
- Recompute reaction rates and schedule a new event for cell  $i$ .
- If population of  $i$  changed, update the event prediction for all neighbor cells of  $i$ , and, if population of  $j$  changed, update the event prediction for all cell neighbors of  $j$  that are not neighbors of  $i$ .

# Reversible Reaction Rules

We have made a set of rules that obey **microscopic reversibility** (detailed balance) that dictate how reactions are processed, e.g.,

- 1 **Annihilation:**  $A + B \rightarrow \emptyset$  if within distance  $R_{AB} = R_A + R_B$ .
- 2 **Birth:**  $\emptyset \rightarrow A + B$ . The  $A$  is born uniformly in the system, and  $B$  is born with position uniformly chosen within a reactive sphere of radius  $R_{AB}$  around the  $A$ .
- 3 **Merge:**  $A + A \rightarrow B$  or  $A + B \rightarrow C$ . One of the reactants changes species and the others disappears.
- 4 **Replication:**  $A \rightarrow B + C$ , where  $B/C$  can be equal to  $A$ :  
 $A$  becomes a  $B$  or a  $C$  or remains as is, and another particle is born uniformly in a sphere centered at the  $A$  with radius  $R_{BC}$ .
- 5 **Transform:**  $A + B \rightarrow C + D$  or  $A + B \rightarrow A + C$  (catalysis):  
 No particle changes position or new particles are created, only species are changed (e.g.,  $B$  becomes a  $C$  or  $D$ ).

# From microscopic to macroscopic rates

- For a single reaction  $A + B \rightarrow \dots$ , Erban and Chapman [2] derive that in **3D** the **macroscopic reaction rate**  $k$  (units  $m^3/s$ ) is related to the **microscopic rate**  $\lambda$  (units  $s^{-1}$ ),

$$k = 4\pi D_{AB} R_{AB} \left[ 1 - \sqrt{\frac{D_{AB}}{\lambda R_{AB}^2}} \tanh \left( \sqrt{\frac{\lambda R_{AB}^2}{D_{AB}}} \right) \right], \quad (1)$$

where  $D_{AB} = D_A + D_B$  is the mutual diffusion coefficient and  $R_{AB} = R_A + R_B$  is the reactive radius.

- For  $A + A \rightarrow$  one just divides the rate by two, and using  $D_{AA} = 2D_A$  gives

$$k_{AA} = 4\pi D_A R_{AA} \left[ 1 - \sqrt{\frac{2D_A}{\lambda R_{AA}^2}} \tanh \left( \sqrt{\frac{\lambda R_{AA}^2}{2D_A}} \right) \right], \quad (2)$$

# Diffusion-Limited vs Reaction-Limited?

- This shows that the important parameter is the dimensionless number

$$r = \frac{\lambda R_{AB}^2}{D_{AB}} \quad \text{and} \quad k < 4\pi D_{AB} R_{AB}.$$

- If  $r \gg 1$  (**diffusion-limited**), then  $k \rightarrow 4\pi D_{AB} R_{AB}$ , which is the **Smoluchowski rate**, i.e., particles react upon first touching.
- For  $r \ll 1$  (**reaction-limited**), then we get the result expected if the particle positions are uncorrelated, i.e., the system is “uniformly mixed” at microscopic scales:

$$k \approx \frac{4\pi}{3} R_{AB}^3 \lambda \quad \text{for } A+B$$

$$k \approx \frac{2\pi}{3} R_{AB}^3 \lambda \quad \text{for } A+A$$

# Diffusion-Limited RDME

- Similarly, **for RDME** in 3D for  $A + B \rightarrow \dots$ , the effective macroscopic rate is related to input (microscopic) rate  $k_{RDME}$  via [2, 5]

$$\frac{1}{k} = \frac{1}{k_{RDME}} + \frac{\beta = 0.25273}{hD},$$

where  $D = D_{AB}$  for  $A + B$  and  $D = D_A$  for  $A + A$ .

- This explains the **loss of bimolecular reactions** as  $h \rightarrow 0$  (more precisely, in 3D, when  $h \ll k/D_{AB}$ ).
- **Renormalization** theory suggests that for  $A + A \rightarrow A$  the **law of mass action at finite densities is non-analytic** [5]

$$\frac{k}{k_0} = 1 + \alpha \left( \frac{k_0}{D_A} \right)^{\frac{3}{2}} n_A^{\frac{1}{2}} = 1 + \beta f^{3/2} \phi^{\frac{1}{2}},$$

where  $k_0 = \lim_{\phi \rightarrow 0} k$ ,  $f = k_0 / (4\pi D_A R_{AA})$ ,  $\phi = n_A \cdot (4\pi R_{AA}^3 / 3)$  for Doi or  $\phi = n_A h^3$  for RDME, and for RDME  $\alpha = 1/2\pi\sqrt{2}$  [5].

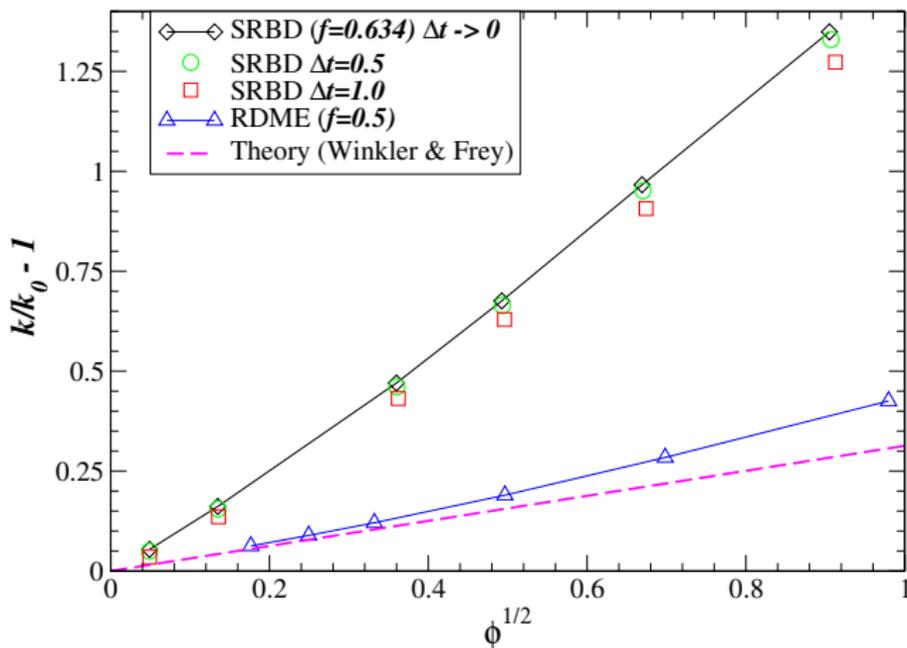
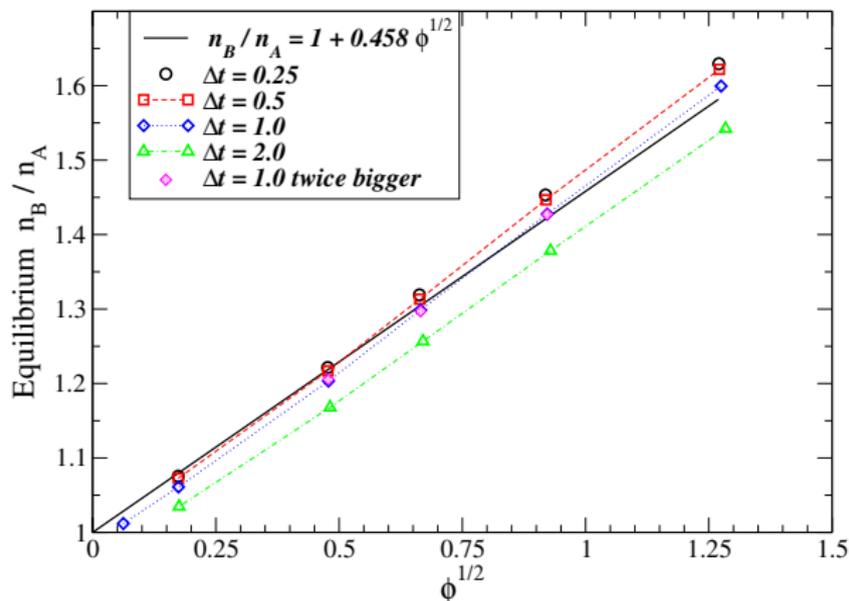
Many-Body Effects (3D):  $A + A \rightarrow A$ Coagulation  $A + A \rightarrow A$ ,  $0 \rightarrow A$ .

Figure: Here  $k_0 = 0.634 \cdot (2\pi D_{AA} R_{AA})$  is computed from (2), and  $\phi = n_A \cdot (4\pi R_{AA}^3/3)$  is the packing density.

# Many-Body Effects (3D): $A + B \rightarrow B$

We find that (1) holds **only for very dilute many-body systems** with  $A + B \rightarrow B$ ,  $0 \rightarrow A$  ( $B$  is conserved).

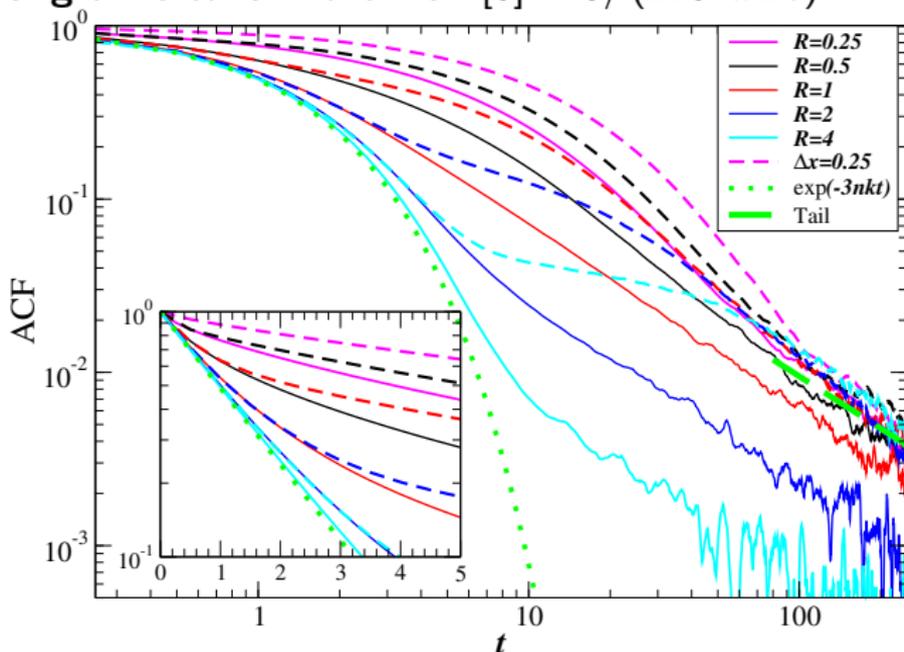


**Figure:** If (1) is correct, then  $k = (1/2) \cdot 4\pi D_{AB} R_{AB}$  and  $\langle n_A \rangle = n_B$  at equilibrium. Here  $R_A = R_B$ ,  $D_A = D_B$ , and  $\phi = (n_A + n_B) \cdot (4\pi R_{AB}^3/3)$ .

# Long-Time Tail for $A + B \leftrightarrow C$ (2D)

**Obeys detailed balance:  $k = \pi R_{AB}^2 \lambda$  (2D) independent of kinetics!**

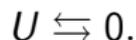
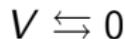
There are **long-time tails** in the ACF [6]  $\approx 5 / (216n\pi Dt)$ .



**Figure:** Here  $n_{A/B/C}^{\text{eq}} = n$ ,  $D_{A/B/C} = D$ ,  $k = 1$ , solid=SRBD, dashed=RDME,  $\Delta x = R_{AB} = R$ . **Numerical  $D_{\text{eff}} = D + 0.13knR_{AB}^2$ .**

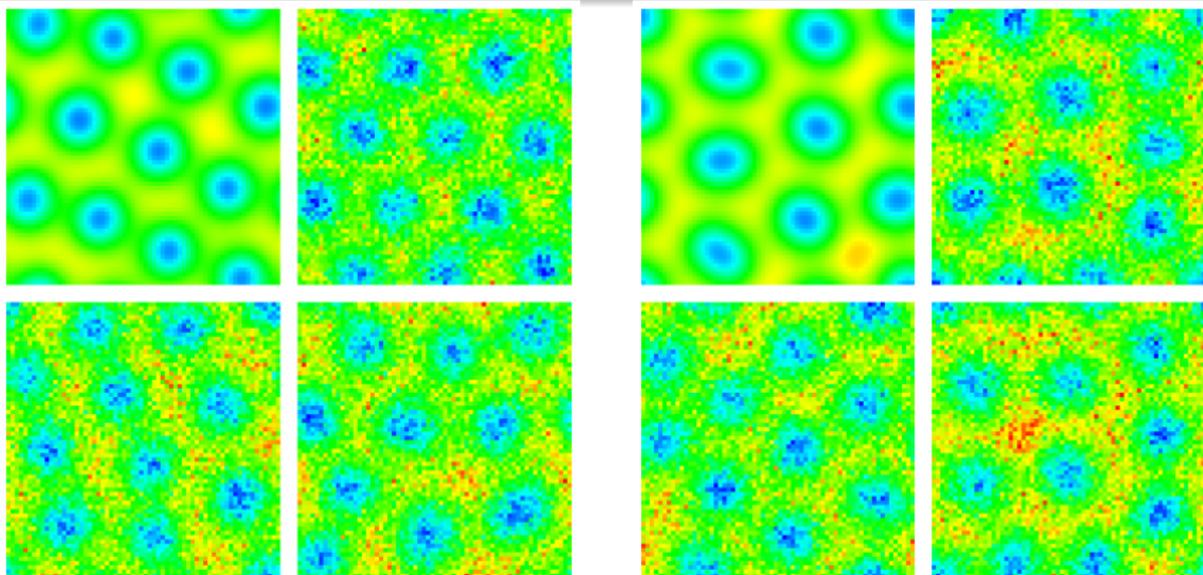
# BPM Model

- We have studied the Baras-Pearson-Mansour (BPM) reaction network (3 species, 7 reactions):



- This system has only binary reactions but can exhibit bimodal states (**bistability**) and also **limit cycles**.
- We use parameters giving a limit cycle together with  $D_V = D_W = D_U/10$  to get a **Turing-like pattern**.
- We want to understand the role fluctuations play in the formation of the Turing pattern.
- We do simulations in 2D to make them more feasible and to simplify visualization, but the code works in 3D as well.

# Turing-like Patterns



Top (grid only): (Left) Deterministic reaction-diffusion.

(Right) RDME using multinomial diffusion [7] + SSA.

Bottom (particle+grid): (Left) **S-BD-RME** [8]. (Right) **SRBD**

Periodic  $256 \times 256$  grid in all cases coarsened to  $64 \times 64$

$R_U = R_V = R_W = h/2$  for SRBD

# Diffusion-Limited or Reaction-Limited?

- Define the **chemical penetration depth**, related to the typical distance a molecule travels between successive reactions,

$$L = \sqrt{\frac{D_{AB}}{kn_{AB}}}, \quad \text{where } n_{AB} = n_A + n_B.$$

- Define also the **packing fraction**

$$\phi = \frac{4\pi}{3} n_{AB} R_{AB}^3 \gtrsim 0.1.$$

If  $\phi \ll 1$  use FPKMC-style algorithms and *not* SRBD!

- Let the number of molecules in a penetration volume be  $N_L = n_{AB} L^3 \gg 1$  (if this were not true then fluctuations would be too large to see a Turing pattern).

# Order-of-Magnitude Estimates

- Then for SRDB we have

$$\frac{k}{R_{AB}D_{AB}} = \frac{1}{N_L} \left( \frac{L}{R_{AB}} \right) = \left( \frac{4\pi}{3\phi N_L^2} \right)^{\frac{1}{3}} \ll 1 \quad \Rightarrow$$

$$r = \frac{3}{4\pi} \frac{k}{R_{AB}D_{AB}} \ll 1$$

- And for RDME we would have  $k \approx k_{RDME}$  since

$$\frac{k}{hD_{AB}} \ll \frac{k}{R_{AB}D_{AB}} \ll 1 \text{ for RDME since } h > R_{AB}.$$

# From (macroscopic) RDME to (microscopic) SRBD rates

- We conclude that we must be in the **reaction-limited case**, so

$$k \approx \frac{4\pi}{3} R_{AB}^3 \lambda \quad \text{for } A+B$$

$$k \approx \frac{2\pi}{3} R_{AB}^3 \lambda \quad \text{for } A+A$$

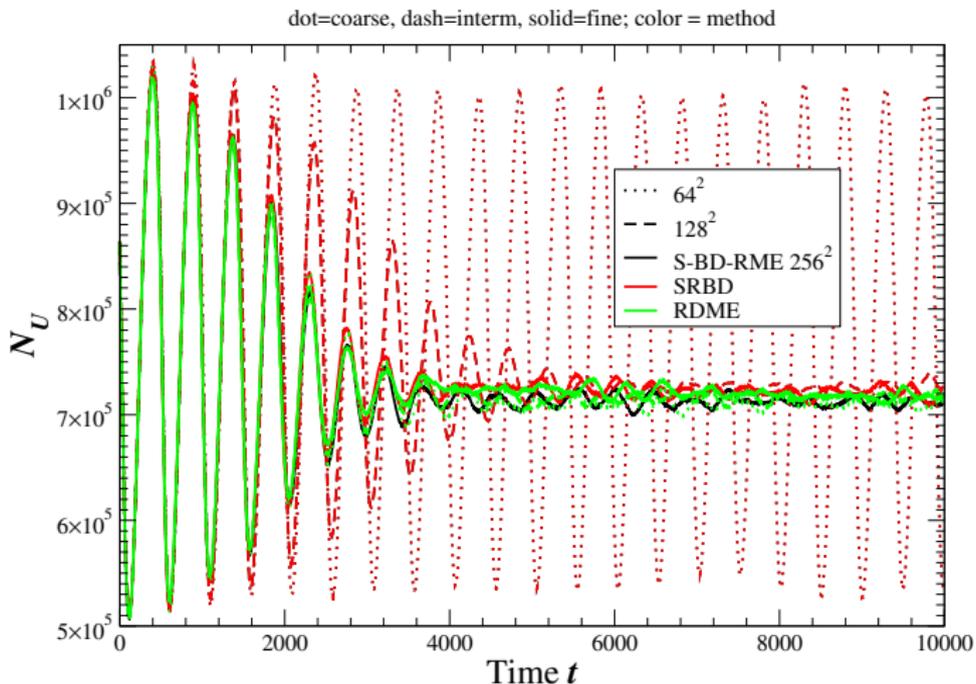
has an obvious generalization in 1D and 2D as well and we will use it to determine  $\lambda$  given  $k$  in order to compare different methods.

- Note that for our Turing test to see any corrections from diffusion-limited effects we would need grids larger than  $1024 \times 1024$ , so assuming  $r \ll 1$  is well justified.
- We have studied grids  $64^2$ ,  $128^2$  and  $256^2$ , keeping the physical parameters (diffusion, macroscopic reaction rates, domain size) fixed.
- For coarser grids, the **added diffusion due to reversible reactions** in SRBD and S-BD-RME will be non-negligible!

# Comparison of methods

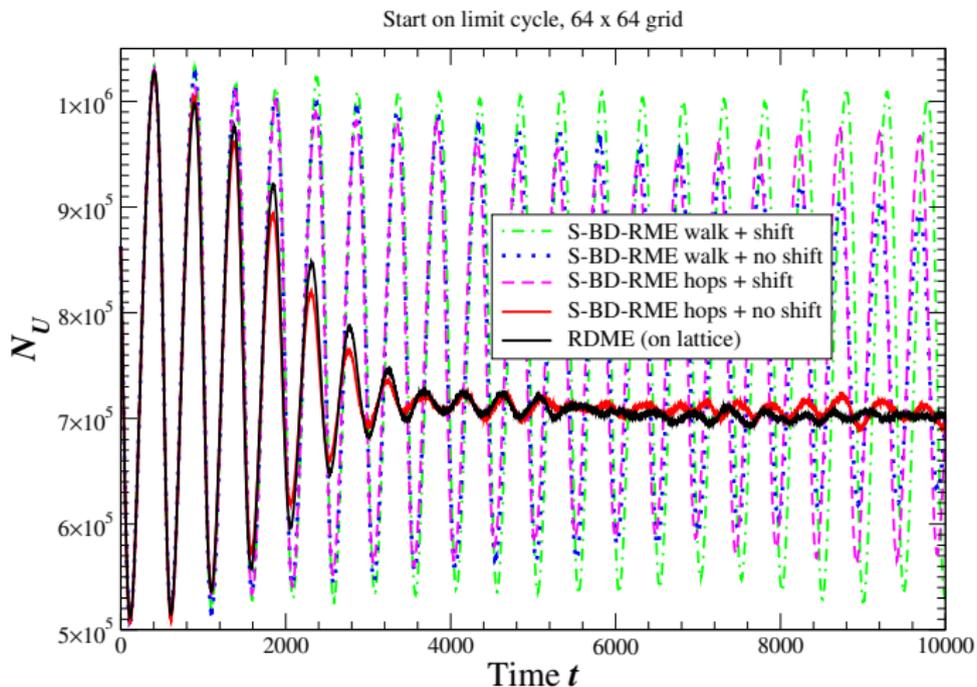
- We compare to a **deterministic/fluctuating hydrodynamics solver** developed with the group of Bell/Garcia at LBNL [1].
- We implement **RDME** using splitting with **multinomial diffusion** (Tartakovsky [7]) + SSA for reactions – much simpler and much more efficient than next-reaction method.
- We also implement a particle algorithm that we call **Split-Brownian Dynamics-Reaction Master Equation (S-BD-RME)** where diffusion is done using a continuum Brownian walk as in SRBD but reactions are done on a grid using SSA (see Tartakovsky [8]).
- Before carrying out SSA in S-BD-RME, **we randomly shift the reaction grid to improve Galilean invariance.**
- In SRBD we use  $R_U = R_V = R_W = h/2$  where  $h$  is the grid spacing used in the RME-based methods.
- Time step in *all* methods is **limited by fast diffusion**; we set Courant number  $D_U \Delta t / h^2 \approx 0.3$ .

# Changing Resolution



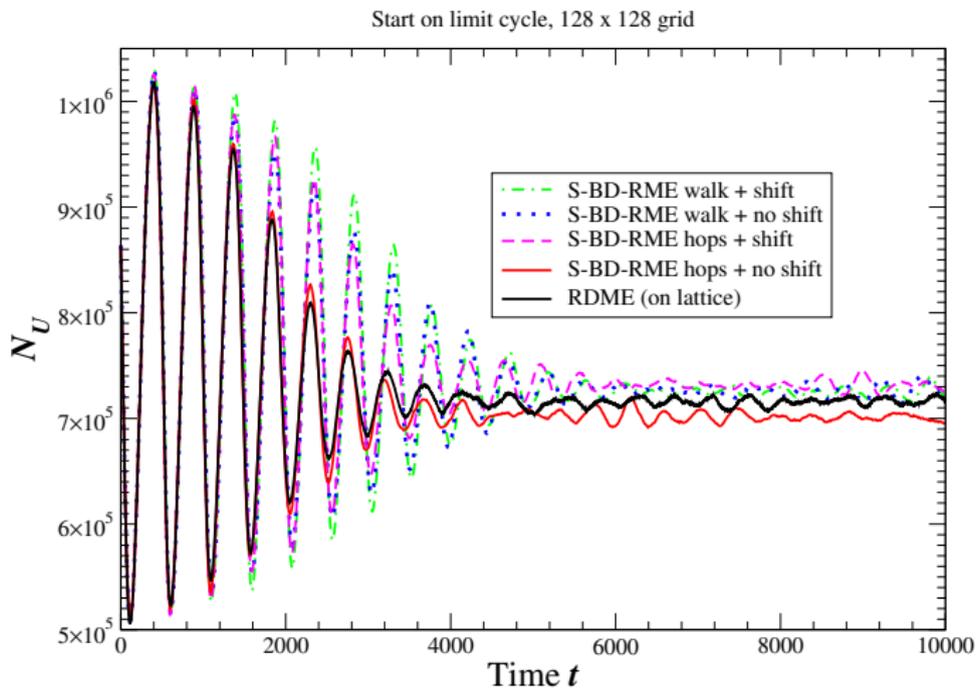
**Figure:** For  $256^2$  resolution, total running time is 4.5h for RDME, 12h for S-BD-RME, and 19h for SRBD. For  $512^2$  resolution, 54h for S-BD-RME and 48h for SRBD (but 43h for  $256^2$  reaction grid).

## Walk versus Hops (coarse grid)



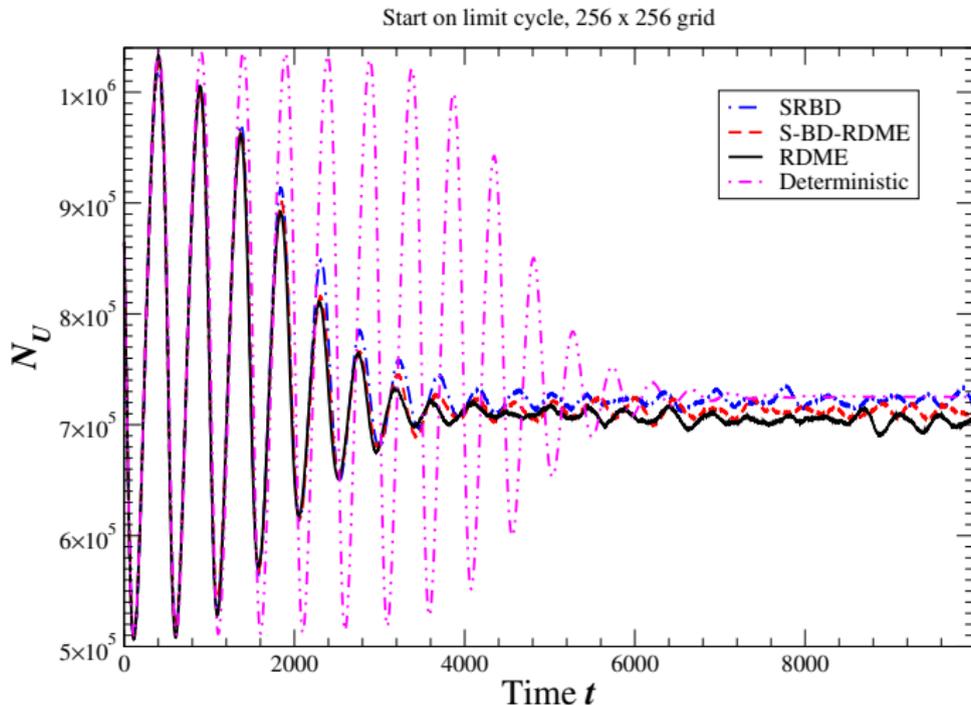
**Figure:** Importance of microscopic details of diffusion (**hops versus continuum walk**) and reactions (especially **enhanced diffusion**) for **under-resolved simulations** (cells not uniformly mixed).

# Walk versus Hops (finer grid)



**Figure:** Importance of microscopic details of diffusion (**hops versus continuum walk**) and reactions (especially **enhanced diffusion**) for **marginally-resolved simulations** (cells not uniformly mixed).

# Fine Resolutions (Resolved)



**Figure:** If the resolution is sufficiently high (resolved) we get matching between the fluctuating methods (including **fluctuating hydrodynamics**, not shown).

## Quantitative Comparison

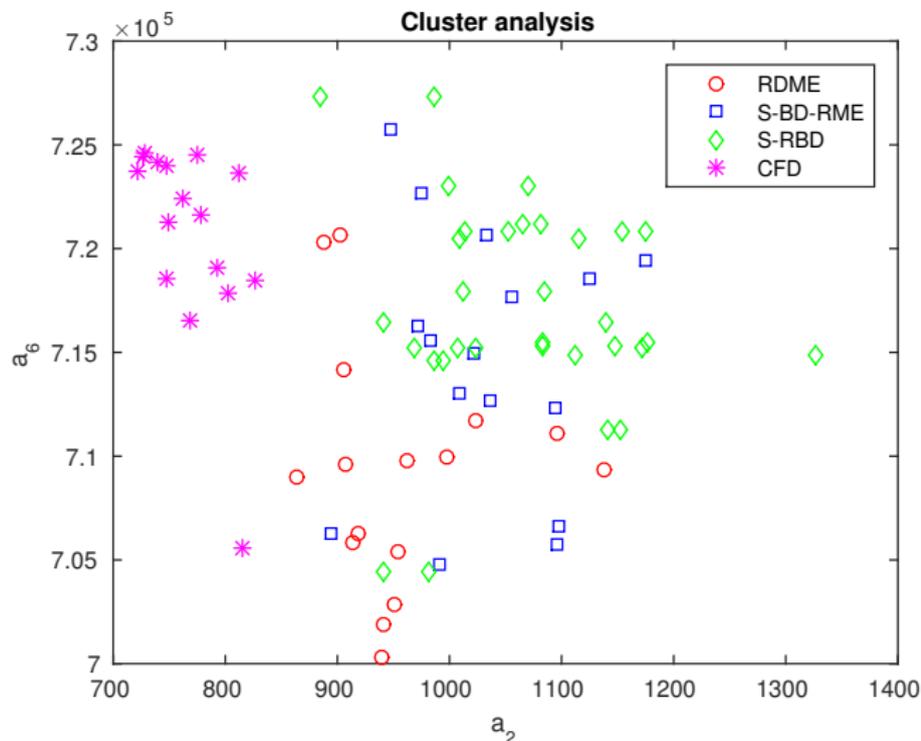


Figure: Fit  $N_U(t) = (1 - \tanh((t - a_0)/a_2))(a_1 \sin(a_3x + a_4) + a_5) + a_6$ .

# Conclusions

- Our **Split Reactive Brownian Dynamics** (SRBD) introduces a **time splitting error** but handles diffusion and reaction exactly.
- Efficiency was gained by never computing neighbor lists for particles, instead, **scheduling potential reactions** and only looking for neighbors when a reaction actually happens.
- The algorithm is best at higher densities and slow reactions (otherwise use FPKMC).
- How one handles diffusion (hops vs walk) and reactions (fixed grids, shifting grids, grid-free) microscopically affects the macroscopic behavior strongly if the cells are not sufficiently well-mixed (i.e., much smaller than chemical penetration depth).
- For resolved simulations we were able to match the macroscopic behavior between RDME, S-BD-RME, SRBD and FHD.
- Under what conditions can one use coarse-grained models like RDME/FHD and avoid tracking particles? Do the rates need to be renormalized and how?

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