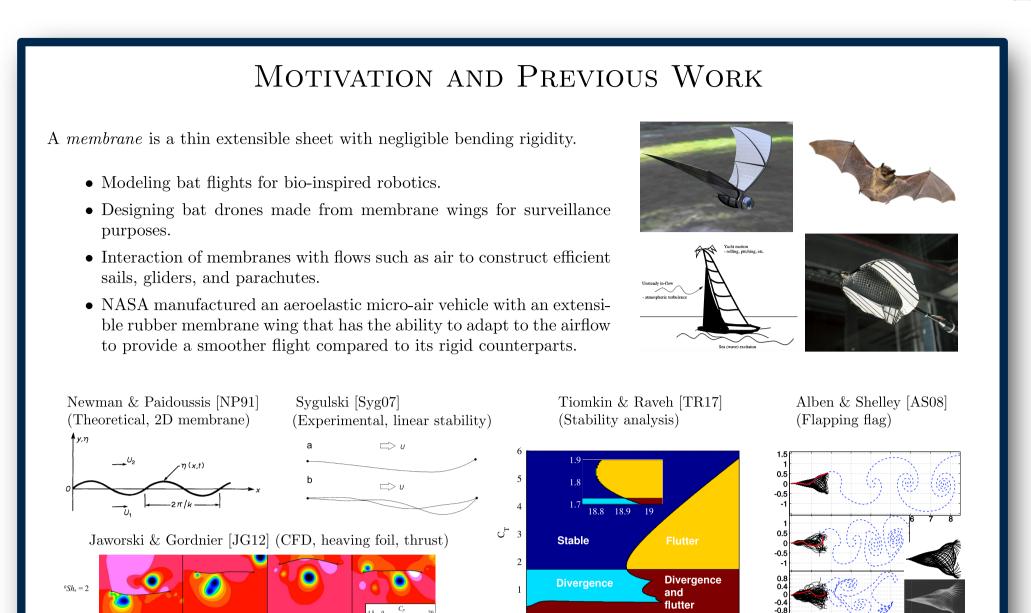


SIMULATING LARGE-AMPLITUDE MEMBRANE

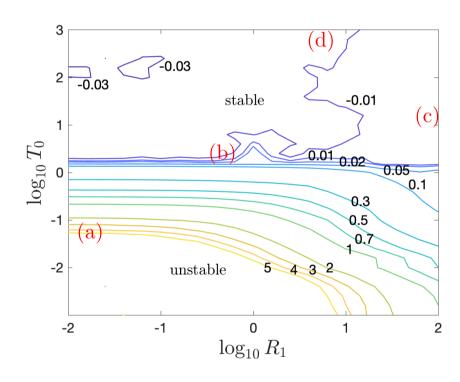
Motions in Inviscid Flow

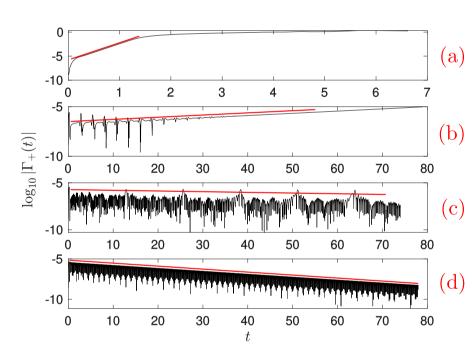
Christiana Mavroyiakoumou Silas Alben



STABILITY DIAGRAM (FIXED-FIXED)

We focus on the fixed-fixed membrane and show the stability diagram in the pretension (T_0) versus mass (R_1) parameter space. For large pretension, the membrane is stable whereas for small pretension it is unstable. The subplots show examples of the computed rates, ranging from exponential growth to exponential decay. We observe two distinct types of motion: either stable or simply divergence.



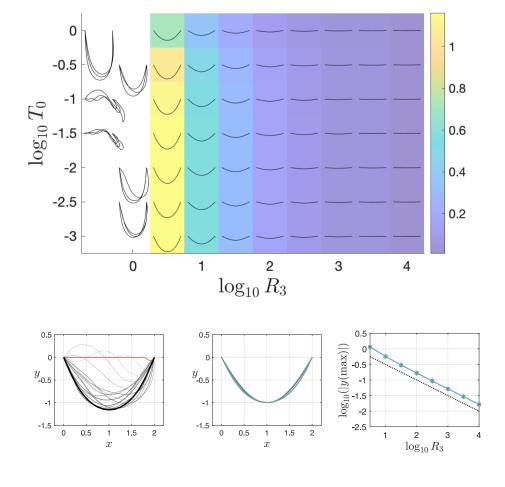


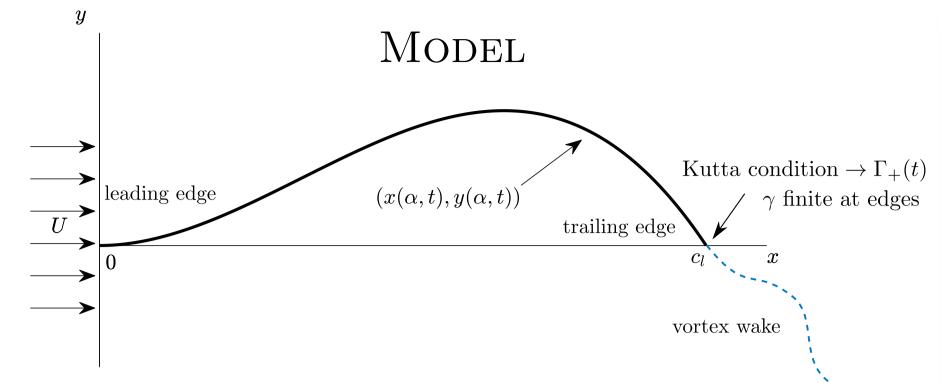
TIME-AVERAGED AMPLITUDE

The surface plot colors correspond to the time-averaged amplitude of each membrane. We superpose mode shapes at the last time step while keeping the membrane mass fixed.

From left to right, the subplots show:

- For a specific membrane choice, how the mode shapes converge to the steady shape. In particular, we illustrate a sequence of time snapshots ranging from gray in early time to black in current time.
- All the membranes plotted on top of each other, but normalized, to emphasize that the steady shape is almost identical and it is only the amplitude that changes.
- Scaling law between time-averaged amplitude and stretching rigidity (R_3) . From the governing equations, it can be shown that $y(\max) \propto 1/\sqrt{R_3}$. The different colors correspond to different pretension values T_0 but with fixed mass $R_1 = 10^{-0.5}$.





Membrane: $\zeta(\alpha, t) = x(\alpha, t) + iy(\alpha, t)$

Extensible membrane: $R_1 \partial_{tt} \zeta + \underbrace{R_2 \partial_s (\partial_s \kappa(s,t) \hat{n})}_{\text{bending resistance}} - \partial_{\alpha} ((T_0 + R_3(\partial_{\alpha} s - 1)) \hat{s}) = -[p] \hat{n}$

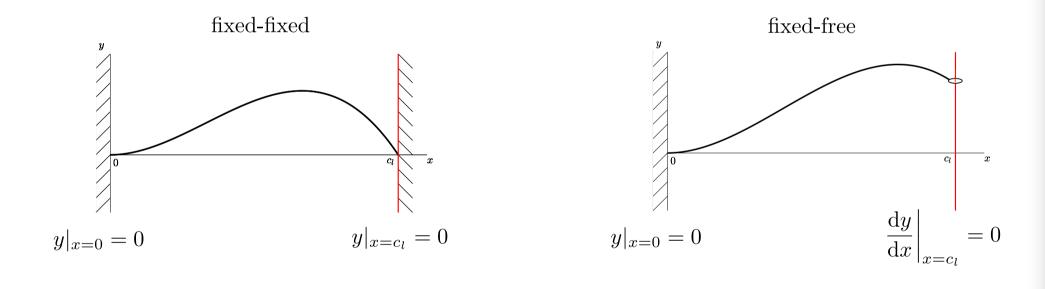
Pressure jump: $\partial_{\alpha} s \partial_t \gamma + \gamma (\partial_{\alpha} \tau - \nu \kappa \partial_{\alpha} s) + \partial_{\alpha} (\gamma (\mu - \tau)) = \partial_{\alpha} [p]$

Birkhoff-Rott:
$$\partial_t \overline{\zeta}(\Gamma, t) = \frac{1}{2\pi i} \int_{-1}^1 \frac{\gamma(\alpha', t) \partial_{\alpha} s(\alpha')}{\zeta(\Gamma, t) - \zeta(\alpha', t)} d\alpha' - \frac{1}{2\pi i} \int_0^{\Gamma_+} \frac{\overline{\zeta}(\Gamma, t) - \zeta(\Lambda', t)}{|\zeta(\Gamma, t) - \zeta(\Lambda', t)|^2 + \delta(\Gamma, t)^2} d\Lambda'$$

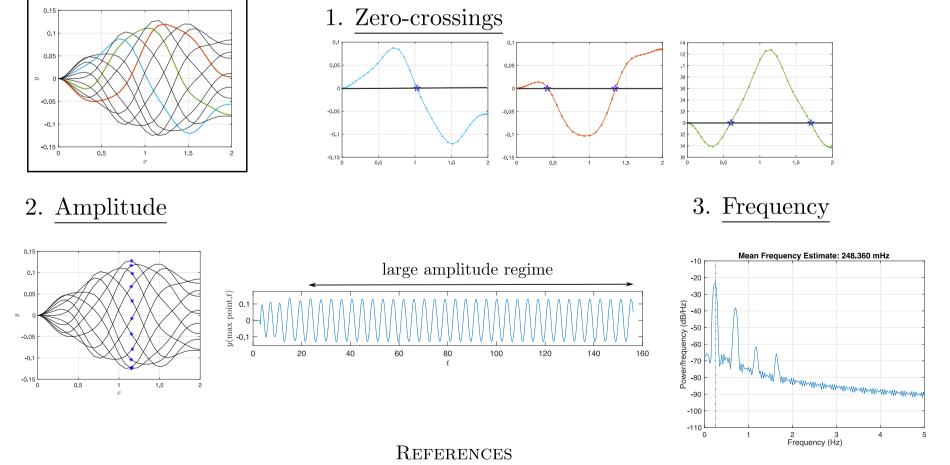
We study how the dynamics depend on three parameters:

(a) Membrane mass:
$$R_1 = \frac{\rho_s h}{0.5c_l\rho_f}$$
, (b) stretching rigidity: $R_3 = \frac{Eh}{0.5c_l\rho_f U^2}$, (c) pretension: $T_0 = \frac{\overline{T}}{0.5c_l\rho_f U^2 W}$.

BOUNDARY CONDITIONS



Important Quantities

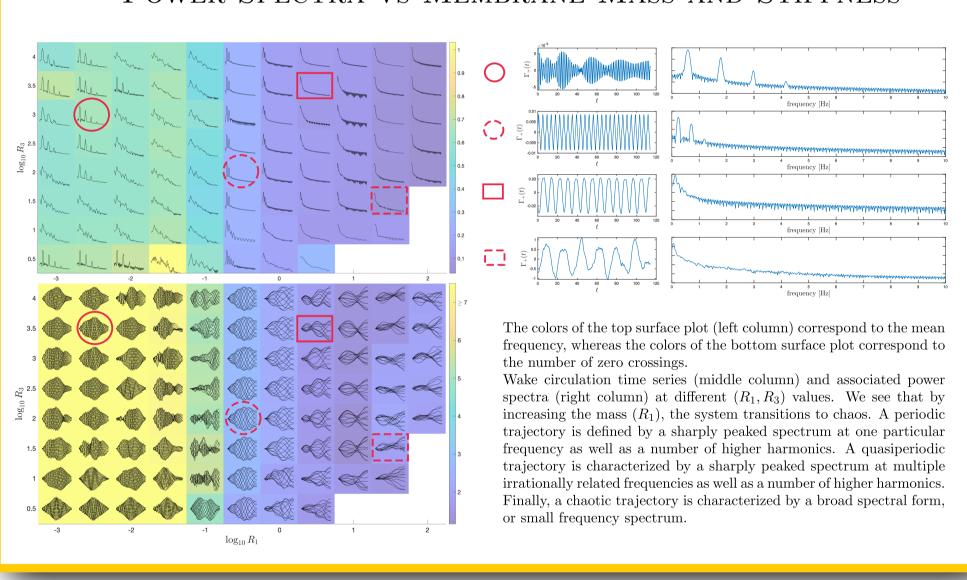


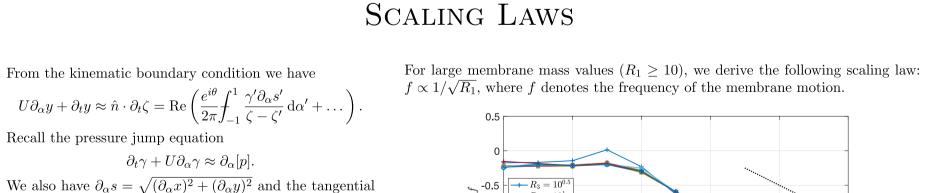
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Poster design adapted from A. Horawa's design.







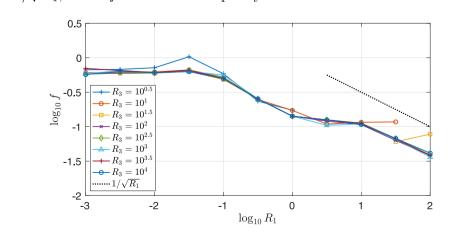
unit vector $\hat{s} = (\partial_{\alpha} x, \partial_{\alpha} y) / \sqrt{(\partial_{\alpha} x)^2 + (\partial_{\alpha} y)^2}$. Balancing

 $R_1 \partial_{tt} \zeta - \partial_{\alpha} ((T_0 + R_3(\partial_{\alpha} s - 1))\hat{s}) = -[p]\hat{n},$

 $R_1 = 10^{-1.6}$ $R_1 = 10^{-1.6}$ $R_1 = 10^{-1}$ $R_1 = 10^{-1}$ $R_1 = 10^{-0.6}$ $R_1 = 10^{0.5}$ $R_1 = 10^{0.5}$

terms in the extensible membrane equation

yields $R_3 \propto 1/\text{deflection}^2$.



From the vortex wakes, we observe the onset of chaos for the membrane motions as the mass (R_1) increases. Furthermore, we confirm using these time snapshots, that as the stretching rigidity (R_3) increases, the amplitude of the membrane decreases.

