MATH-GA2120 Linear Algebra II Diagonalizable Linear Maps Inner Product on  $\mathbb{F}^n$ Inner Product on Abstract Vector Space Cauchy-Schwarz Inequality

#### Deane Yang

Courant Institute of Mathematical Sciences New York University

February 15, 2024

# **Diagonal Linear Transformation**

- Let dim V = n
- Let  $L: V \rightarrow V$  be a linear transformation
- Suppose L has n linearly independent eigenvectors e<sub>1</sub>,..., e<sub>n</sub> with eigenvalues λ<sub>1</sub>,..., λ<sub>n</sub>
- Then with respect to the basis  $E = (e_1, \ldots, e_n)$ ,

$$L(e_k) = e_k \lambda_k$$

Equivalently,

$$\begin{bmatrix} L(e_1) & \cdots & L(e_n) \end{bmatrix} = \begin{bmatrix} e_1 & \cdots & e_n \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix}$$

# **Diagonal Linear Transformation**

Conversely, suppose L : V → V is a linear transformation and E is a basis such that

$$L(E)=ED,$$

where D is a diagonal matrix

Then

$$L(e_k) = e_j D_k^j = e_k D_k^k$$

Therefore, L has eigenvalues D<sub>1</sub><sup>1</sup>,..., D<sub>n</sub><sup>n</sup> with eigenvectors e<sub>1</sub>,..., e<sub>n</sub> respectively

# Diagonalizable Linear Transformation

- Let  $L: V \rightarrow V$  be a diagonal linear transformation
- ▶ If *E* is a basis of eigenvectors, then

$$L(E)=ED,$$

where D is a diagonal matrix

▶ Given any basis *F*, there is an invertible matrix *M* such that

$$F = EM$$

and vice versa

There is a matrix A such that

$$L(F) = FA$$

► Therefore,

$$ED = L(E) = L(FM^{-1}) = L(F)M^{-1} = FAM^{-1} = EMAM^{-1}$$

▶ I.e., *M* and *D* are similar

Diagonalizable Linear Transformation and Matrix

- A linear transformation L : V → V is diagonalizable if any of the following equivalent conditions hold:
  - There exists a basis of V consisting of eigenvectors
  - There exists a basis E such that L(E) = ED, where D is a diagonal matrix
  - Given any basis F and matrix A such that

$$L(F) = FA,$$

A is similar to a diagonal matrix

A matrix A is diagonalizable if it is similar to a diagonal matrix

## Linear Transformation With Distinct Eigenvalues

• Let dim(V) = n and  $L: V \to V$  be a linear transformation with *n* distinct eigenvalues  $\lambda_1, \ldots, \lambda_n$ , i.e.,

$$j \neq k \implies \lambda_j \neq \lambda_k$$

Let  $v_1, \ldots, v_n$  be eigenvectors of  $\lambda_1, \ldots, \lambda_n$  respectively Suppose  $v_1, \ldots, v_{k-1}$  are linearly independent If  $a^1v_1 + \cdots + a^kv_kw = 0$ , then  $0 = (L - \lambda_k I)(a^1 v_1 + \dots + a^k v_k)$  $=a^{1}(Lv_{1})-\lambda_{k}v_{1})+\cdots+a^{k}(L(v_{k})-\lambda_{k}v_{k})$  $=a^{1}(\lambda_{1}-\lambda_{k})v_{1}+\cdots+a^{k}(\lambda_{k}-\lambda_{k})v_{k}$  $=a^{1}(\lambda_{1}-\lambda_{k})v_{1}+\cdots+a^{k-1}(\lambda_{k-1}-\lambda_{k})v_{k-1},$ • Therefore,  $a^1(\lambda_1 - \lambda_k) = \cdots = a^{k-1}(\lambda_{k-1} - \lambda_k) = 0$ 

# Linear Transformation With Distinct Eigenvalues

▶ Since  $v_1, \ldots, v_{k-1}$  are linearly independent, it follows that

$$a^1(\lambda_1 - \lambda_k) = \cdots = a^{k-1}(\lambda_{k-1} - \lambda_k) = 0$$

Since the eigenvalues are distinct, this implies that

$$a^1=\cdots=a^{k-1}=0$$

- By assumption,  $a^1v_1 + \cdots + a^kv_kw = 0$  and therefore  $a^k = 0$
- ▶ It follows by induction that  $v_1, \ldots, v_n$  form a basis of V
- ► Therefore, *L* is diagonalizable
- Conclusion: Any linear transformation with *n* distinct eigenvalues is diagonalizable

# Direct Sum of Subspaces

- Let  $V_1, \ldots, V_k$  be subspaces of V
- {V<sub>1</sub>,..., V<sub>k</sub>} is a **linearly independent** set of subspaces if for any nonzero vectors

$$v_1 \in V_1, v_2 \in V_2, \ldots, v_k \in V_k$$

are linearly independent

• Equivalently,  $\{V_1, \ldots, V_k\}$  is linearly independent if for any  $v_1 \in V_1, \ldots, v_k \in V_k$ ,

$$v_1 + v_2 + \cdots + v_k = 0 \implies v_1 = v_2 = \cdots = v_k$$

• Equivalently,  $\{V_1, \ldots, V_k\}$  is linearly independent if for any  $v_1, w_1 \in V_1, \ldots, v_k, w_k \in V_k$ ,

 $v_1+v_2+\cdots+v_k = w_1+w_2+\cdots+w_k \implies v_1 = w_1,\ldots,v_k = w_k$ 

If {V<sub>1</sub>, V<sub>2</sub>,..., V<sub>k</sub>} is linearly independent, then their direct sum is defined to be

$$V_1 \oplus V_2 \oplus \cdots \oplus V_k = \operatorname{span}(V_1 \cup V_2 \cup \cdots \cup V_k)$$

#### Examples

1

• 
$$\{S_1, S_2\}$$
, where  $S_1, S_2 \subset \mathbb{F}^3$  are given by $S_1 = ext{span}(e_1)$  $S_2 = ext{span}(e_2),$ 

is linearly independent

• If  $\{v_1, \ldots, v_k\}$  is linearly independent and

$$\forall 1 \leq j \leq k, \ V_j = \operatorname{span}(v_j),$$

then  $\{V_1, \ldots, V_k\}$  is a linearly independent set of subspaces If  $(e_1, e_2, e_3, e_4)$  is a basis of V and

$$S = \operatorname{span}(e_1, e_2, e_3), \ T = \operatorname{span}(e_4),$$

then  $V = S \oplus T$ 

# Eigenspaces of Distinct Eigenvalues are Linearly Independent (Part 1)

If λ<sub>1</sub>,..., λ<sub>k</sub> are distinct eigenvalues of L : V → V, then their eigenspaces E<sub>λ1</sub>,..., E<sub>λk</sub> are linearly independent

• Prove by induction that for any  $1 \le j \le k$ ,

$$v_1 + \cdots + v_j = 0 \implies v_1 = \cdots = v_j = 0$$

- This holds for j = 1
- ► Inductive step: Assume that it holds for 1 ≤ j < k and prove it holds for j + 1

Eigenspaces of Distinct Eigenvalues are Linearly Independent (Part 2)

• Suppose 
$$v_1 \in E_{\lambda_1}, \ldots, v_{j+1} \in E_{\lambda_{j+1}}$$
 satisfy  
 $v_1 + \cdots + v_{j+1} = 0$ 

It follows that

$$0 = (L - \lambda_{j+1}I)(v_1 + \dots + v_{j+1})$$
  
=  $(\lambda_1 - \lambda_{j+1})v_1 + \dots + (\lambda_j - \lambda_{j+1})v_j$ 

By the inductive assumption,

$$(\lambda_1 - \lambda_{j+1})v_1 = \cdots = (\lambda_j - \lambda_{j+1})v_j = 0$$

Since  $\lambda_i - \lambda_{j+1} \neq 0$  for each  $1 \leq i \leq j$ ,

$$v_1 = \cdots = v_j = 0$$

• By (1), it follows that  $v_{j+1} = 0$ 

11 / 28

(1)

Eigenspaces of Distinct Eigenvalues are Linearly Independent (Part 3)

► By induction,

$$v_1 + \cdots + v_k = 0 \implies v_1 = \cdots = v_k = 0$$

This implies that E<sub>λ1</sub>,..., E<sub>λk</sub> are linearly independent

Diagonalizability of a Linear Transformation (Part 1)

Let λ<sub>1</sub>,...,λ<sub>k</sub> be the eigenvalues of L : V → V
L is diagonalizable if and only if

 $\dim(E_{\lambda_1}) + \cdots + \dim(E_{\lambda_k}) = \dim V$ 

• Let  $n_0 = 0$  and, for  $1 \le j \le k$ , let

 $n_j = \dim(E_{\lambda_j})$  $N_j = n_1 + \cdots + n_j$ 

For each  $1 \le j \le k$ , let

 $(v_{N_{j-1}+1},\cdots,v_{N_j})$ 

be a basis of  $E_{\lambda_i}$ 

Diagonalizability of a Linear Transformation (Part 2)

Suppose

$$a^1v_1+\cdots+a^nv_n=0,$$

For each  $1 \le j \le k$ , let

$$w_j = a^{N_{j-1}+1}v_{N_{j-1}} + \cdots + a^{N_j}v_{N_j} \in E_{\lambda_j}$$

Since  $w_1 + \cdots + w_k = 0$ , it follows that

$$w_1 = \cdots = w_k = 0$$

For each  $1 \le j \le k$ ,

$$0 = w_j = a^{N_{j-1}+1} v_{N_{j-1}} + \dots + a^{N_j} v_{N_j},$$

which implies  $a^{N_{j-1}+1} = \cdots = a^{N_j} = 0$ 

- Therefore,  $(v_1, \ldots, v_n)$  is a basis of V
- L is diagonal with respect to this basis

#### Dot Product on $\mathbb{R}^n$

Recall that the dot product of

$$v = \begin{bmatrix} v^1 \\ \vdots \\ v^n \end{bmatrix}, \ w = \begin{bmatrix} w^1 \\ \vdots \\ w^n \end{bmatrix} \in \mathbb{R}^n$$

is defined to be

$$v \cdot w = v^1 w^1 + \dots + v^n w^n = v^T w = w^T v$$

• The **norm** or **magnitude** of  $v \in \mathbb{R}^n$  is defined to be

$$|v| = \|v\| = \sqrt{v \cdot v}$$

If v and w are nonzero and the angle at 0 from v to w is θ, then

$$\cos\theta = \frac{v \cdot w}{|v||w|}$$

15 / 28

#### Properties of Dot Product

The dot product is bilinear because for any a, b ∈ ℝ and u, v, w ∈ ℝ<sup>n</sup>,

$$(au + bv) \cdot w = a(u \cdot w) + b(v \cdot w)$$
$$u \cdot (av + bw) = a(u \cdot v) + b(u \cdot w)$$

▶ It is **symmetric**, because for any  $v, w \in \mathbb{R}^n$ ,

 $v \cdot w = w \cdot v$ 

lt is **positive definite**, because for any  $v \in \mathbb{R}^n$ ,

$$v \cdot v \ge 0$$

and

$$v \cdot v > 0 \iff v \neq 0$$

◆□ ▶ ◆□ ▶ ◆三 ▶ ◆三 ▶ ● ○ ○ ○ ○

## Inner Product on Real Vector Space

- Let V be an n-dimensional real vector space
- Consider a function

 $\alpha: V \times V \to \mathbb{R}$ 

▶ It is **bilinear** if for any  $a, b \in \mathbb{R}$  and  $u, v, w \in \mathbb{R}^n$ ,

$$\alpha(au + bv, w) = a\alpha(u, w) + b\alpha(v, w)$$
  
$$\alpha(u, av + bw) = a\alpha(u, v) + b\alpha(u, w)$$

• It is symmetric if for any  $v, w \in \mathbb{R}^n$ ,

$$\alpha(\mathbf{v},\mathbf{w}) = \alpha(\mathbf{w},\mathbf{v})$$

• It is **positive definite** if for any  $v \in \mathbb{R}^n$ ,

$$\alpha(\mathbf{v},\mathbf{v}) \geq \mathbf{0}$$

and

$$\alpha(\mathbf{v},\mathbf{v}) > \mathbf{0} \iff \mathbf{v} \neq \mathbf{0}$$

Any positive definite symmetric bilinear function on a real vector space V is called an inner product and the second state of the second state

## Hermitian Inner Product on $\mathbb{C}^n$

• Recall that if 
$$z = x + iy \in \mathbb{C}$$
, then

$$\bar{z} = x - iy$$
 and  $z\bar{z} = \bar{z}z = x^2 + y^2$ 

If A is a complex matrix, its Hermitian adjoint is defined to be

$$A^* = \bar{A}^*$$

• The Hermitian inner product on  $\mathbb{C}^n$  of

$$v = \begin{bmatrix} v^1 \\ \vdots \\ v^n \end{bmatrix}, \ w = \begin{bmatrix} w^1 \\ \vdots \\ w^n \end{bmatrix} \in \mathbb{C}^n$$

is defined to be

$$(v,w) = v^1 \overline{w}^1 + \cdots + v^n \overline{w}^n = v^T \overline{w} = \overline{w}^T v = w^* v \in \mathbb{C},$$

• The **norm** of  $v \in \mathbb{C}^n$  is defined to be

$$|v| = \|v\| = \sqrt{(v,v)}$$

No geometric interpretation of the Hermitian inner product and so a second s

18 / 28

#### Not a Real Inner Product

• Not bilinear, because if 
$$c \in \mathbb{C}$$
,

$$(v, cw) = \overline{c}(v, w)$$

Not symmetric, because

$$(w,v) = \overline{(v,w)}$$

▶ It is positive definite, because for any  $v \in \mathbb{C}^n$ ,  $(v, v) \in \mathbb{R}$ ,

$$(v,v) = v^1 \bar{v}^1 + \dots + v^n \bar{v}^n = |v^1|^2 + \dots + |v^n|^2 \ge 0,$$

and

$$(v,v) \neq 0 \iff v \neq 0$$

Properties of Hermitian Inner Product on  $\mathbb{C}^n$ 

It is a linear function of the first argument, because for any a, b ∈ C, u, v, w ∈ C<sup>n</sup>,

$$(au + bv, w) = a(u, w) + b(v, w)$$

It is Hermitian, which means

$$(v,w) = \overline{(w,v)}$$

▶ Therefore, for any  $a, b \in \mathbb{C}$  and  $u, v, w \in \mathbb{C}^n$ ,

$$(u, av + bw) = \overline{a}(u, v) + \overline{b}(a, w)$$

### Inner Product of a Vector Space Over ${\mathbb F}$

 $\blacktriangleright \text{ Assume } \mathbb{F} \text{ is } \mathbb{R} \text{ or } \mathbb{C}$ 

An inner product over a vector space V is a function

$$(\cdot, \cdot): V imes V o \mathbb{F}$$

with the following properties: For any  $a, b \in F$  and  $u, v, w \in V$ ,

$$(au + bv, w) = a(u, w) + b(v, w)$$
  
 $(w, v) = \overline{(v, w)}$   
 $(v, v) \ge 0$   
 $(v, v) \ne 0 \iff v \ne 0$ 

If 𝔽 = 𝖳, this is the same definition as before

▶ If  $\mathbb{F} = \mathbb{C}$ , this is the definition of a Hermitian inner product

# Examples

- For each  $v \in \mathbb{F}^n$ , denote  $v^* = \bar{v}^T$
- The standard inner product on  $\mathbb{F}^n$  is

$$(v,w)=w^*v,$$

which is the dot product on  $\mathbb{R}^n$  and the standard Hermitian inner product on  $\mathbb{C}^n$ 

An inner product on the space of polynomials of degree n or less and with coefficients in 𝔽 is

$$(f,g) = \int_{t=0}^{t=1} f(t)\overline{g(t)} dt$$

An inner product on the space of matrices with n rows and m columns is

$$(A,B)= ext{trace}(B^*A)=\sum_{1\leq k\leq m}\sum_{1\leq j\leq n}ar{B}^j_kA^j_k.$$

where  $B^* = \bar{B}^T$ 

#### Nondegeneracy Property

Fact: If a vector  $v \in V$  satisfies the following property:

$$\forall w \in V, \ (v, w) = 0,$$

then v = 0

• Proof: Setting w = v, it follows that

(v, v) = 0 and therefore v = 0

• Corollary: If  $v_1, v_2 \in V$  satisfy the property that

$$\forall w \in V, \ (v_1, w) = (v_2, w),$$

then  $v_1 = v_2$ 

▶ Corollary: If  $L_1, L_2 : V \to W$  are linear maps such that

$$\forall v \in V, w \in W, (L_1(v), w) = (L_2(v), w),$$

then  $L_1 = L_2$ 

Proof: Given  $v \in V$ ,

$$\forall w \in W, \ (L_1(v), w) = (L_2(v), w),$$

which implies  $L_1(v) = L_2(v)$ 

Since this holds for all  $v \in V$ , it follows that  $\ell_1 = \ell_2$ 

23 / 28

#### **Fundamental Inequalities**

**Cauchy-Schwarz inequality:** For any  $v, w \in V$ ,

 $|(v,w)| \leq |v||w|$ 

and

$$|(v,w)| = |v||w|$$

if and only if there exists  $s \in \mathbb{F}$  such that

v = sw or w = sv

• Triangle inequality: For any  $v, w \in V$ ,

 $|v+w| \le |v|+|w|$ 

and

$$|\mathbf{v} + \mathbf{w}| = |\mathbf{v}| + |\mathbf{w}|$$

if and only if  $v = \pm w$ 

24 / 28

#### Proof When $\mathbb{F} = \mathbb{R}$

$$f(t) = |v - tw|^{2}$$
  
=  $(v - tw, v - tw)$   
=  $|v|^{2} - 2t(v, w) + t^{2}|w|^{2}$   
=  $\left(t|w| - \frac{(v, w)}{|w|}\right)^{2} + |v|^{2} - \frac{(v, w)^{2}}{|w|^{2}}$ 

• *f* has a unique minimum when  $t = t_{min}$ , where

$$t_{\min} = rac{(v,w)}{|w|}$$
 and  $f(t_{\min}) = |v|^2 - rac{(v,w)^2}{|w|^2}$ 

25 / 28

▲□▶ ▲□▶ ▲目▶ ▲目▶ 目 のへで

# Proof of Cauchy-Schwarz (Part 1)

• If 
$$v = 0$$
 or  $w = 0$ , equality holds

▶ If  $w \neq 0$ , let  $f : \mathbb{F} \to \mathbb{R}$  be the function

$$\begin{split} f(t) &= |v - tw|^2 \\ &= (v - tw, v - tw) \\ &= |v|^2 - t(w, v) - \bar{t}(v, w) + |t|^2 |w|^2 \end{split}$$

▶ If f has a minimum at  $t_0 \in \mathbb{F}$ , then its directional derivative at  $t_0$  is zero in any direction  $\dot{t}$ 

$$0 = \frac{d}{ds} \Big|_{s=0} f(t_0 + s\dot{t})$$
  
=  $-\dot{t}(w, v) - \bar{t}(v, w) + (t_0\bar{t} + \bar{t}_0\dot{t})|w|^2$   
=  $\dot{t}(\bar{t}_0 - (w, v)) + \bar{t}(t_0|w|^2 - (v, w))$   
=  $\dot{t}(\overline{t_0 - (v, w)}) + \bar{t}(t_0|w|^2 - (v, w))$ 

26 / 28

Proof of Cauchy-Schwarz (Part 2)

ln particular, if 
$$\dot{t} = t_0 |w|^2 - (v, w),$$
 we get

$$|t_0|w|^2 - (v, w)|^2 = 0,$$

Therefore, the only critical point of f is

$$t_0 = \frac{(v, w)}{|w|^2}$$

Since f is always nonnegative, it follows that

$$0 \le f(t_0) = |v|^2 - \frac{|(v,w)|^2}{|w|^2}$$

which implies the Cauchy-Schwarz inequality

# Proof of Cauchy-Schwarz (Part 3)

• If 
$$w \neq 0$$
 and  $|(v, w)| = |v||w|$ , then  

$$0 = |v|^2 - \frac{|(v, w)|^2}{|w|^2} = f(t_0) = |v - t_0 w|^2,$$

which implies that

 $v = t_0 w$