

LU decomposition without pivoting: $A = LU$

$$A \in \mathbb{R}^{n \times n}$$

$L \in \mathbb{R}^{n \times n}$ unit lower triangular

$U \in \mathbb{R}^{n \times n}$ upper triangular

Theorem $A \in \mathbb{R}^{n \times n}$, then \exists permutation matrix $P \in \mathbb{R}^{n \times n}$, $L, U \in \mathbb{R}^{n \times n}$:

$$PA = LU$$

Proof: (Sketch)

By induction over size n :

$n=2$ $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$

Case 1: $a \neq 0 \rightarrow$ Theorem on dominant submatrices
 $\Rightarrow A = LU, P = I \quad \checkmark$

Case 2: $a = 0, c \neq 0, P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$
 $PA = \begin{bmatrix} c & d \\ 0 & b \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}}_L \underbrace{\begin{bmatrix} c & d \\ 0 & b \end{bmatrix}}_U$

Case 3: $a = c = 0, P = I$
 $PA = \begin{bmatrix} 0 & b \\ 0 & d \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}}_L \underbrace{\begin{bmatrix} 0 & b \\ 0 & d \end{bmatrix}}_U$

Induction step: Choose permutation matrix P^{in} such that $P^{in}A$ has the element with largest absolute value amongst all elements in the 1st column on $(l,1)$ spot.
... assume a block LU-decomposition and show that it is well-defined

$$P^T A = \begin{bmatrix} \alpha & w^T \\ p & B \end{bmatrix} \text{ and use induction assumption on } B \quad \checkmark$$

and if all entries in 1st column are zero, using the assumption for smaller matrices $\rightarrow \checkmark$ (□)

Recall: to solve linear system $Ax=b$

1) LU decomposition $PA=LU$

2) Forward substitution $Ly= Pb$

3) Backward \leftarrow $Ux=y$

then x solves $Ax=b$.

$$Ax=b \iff$$

$$PAx=Pb \iff$$

$$LUx=Pb \iff$$

$$\begin{aligned} y &= Ux \\ Ly &= Pb \end{aligned}$$

§2.6 Computational cost

We count the number of elementary operations (+, -, /, \cdot) as a measure of the cost of algorithms, ("flops")

Consider LU without permutations (for simplicity)

$$l_{ij} = \frac{1}{u_{jj}} \left\{ a_{ij} - \sum_{k=1}^{j-1} l_{ik} u_{kj} \right\} \quad \begin{array}{l} i=2,3,\dots,n \\ j=1,\dots,i-1 \end{array} \quad \begin{array}{l} j-1 \text{ mult} \\ j-1 \text{ add/sub} \\ +1 \text{ division} \end{array}$$

$$u_{ij} = a_{ij} - \sum_{k=1}^{i-1} l_{ik} u_{kj} \quad \begin{array}{l} i=1,\dots,n \\ j=i,\dots,n \end{array} \quad \begin{array}{l} i-1 \text{ mult} \\ i-1 \text{ add/subst.} \end{array}$$

$$\sum_{i=2}^n \sum_{j=1}^{i-1} 2j-1 + \sum_{i=1}^n \sum_{j=i}^n 2i-2 = \frac{1}{6} n(n-1)(4n+1) \sim \frac{2}{3} n^3 - \frac{1}{2} n^2$$

Forward/backward substitution:

$$\text{fwd: } Ly = Pb$$

$$y_i = (Pb)_i - \sum_{j=1}^{i-1} l_{ij} y_j \quad i=2, 3, \dots, n \quad \begin{array}{l} i-1 \text{ mult.} \\ i-1 \text{ subst.} \end{array}$$

$$\sum_{i=2}^n 2i-2 = 2 \frac{n(n-1)}{2} = n(n-1) \sim n^2$$

backward: $\sim n^2$

overall cost: $\sim \frac{2}{3} n^3 + \frac{3}{2} n^2$

Let us assume we want to solve a system with k different right hand sides, i.e.:

$$Ax_i = b_i \quad i=1, \dots, k$$

cost: $\frac{2}{3} n^3 - \frac{1}{2} n^2 + 2kn^2$

LU factorization k fwd/backw subst.

Is it better to compute A^{-1} and then $A^{-1} b_i \quad i=1, \dots, k$?

cost of computing A^{-1} : $AA^{-1} = I$, i.e. to get a column of A^{-1} , solve a system with rhs vector $e_i = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix}$

cost: $\frac{2}{3} n^3 - \frac{1}{2} n^2 + 2n^2 m$

one LU fact m fwd/backw.

$$\sim \frac{8}{3} n^3 \quad [\text{can be reduced to } 2n^3]$$

cost of applying $A^{-1} b_i$: $2n^2$ operations, is the same as for fwd/backw substitution

overall cost for $A^{-1} b_i \quad i=1, \dots, k$:

$$\underbrace{2n^3}_{\text{invert } A^{-1}} + \underbrace{2kn^2}_{\text{apply } A^{-1}}$$

always slower than using forward/backward substitution!