

§ 2.1 Solving linear systems

We are interested in solving the linear system

$$Ax = b, \quad A \in \mathbb{R}^{n \times n}, \quad x, b \in \mathbb{R}^n$$

i.e.:

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & \dots & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

Recall: $A^{-1} \in \mathbb{R}^{n \times n}$, $AA^{-1} = A^{-1}A = I = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix} \in \mathbb{R}^{n \times n}$

inverse exists if $\det(A) \neq 0$,
we call these matrices "non-singular", "regular",
"invertible".

Cramer's rule:

$$x_i = \frac{\det(A_i^b)}{\det(A)}$$

A_i^b ... matrix A
with i -th column
replaced by b

requires $n+1$ determinant computations to find $x \in \mathbb{R}^n$.

each determinant computation is expensive/computationally intensive, e.g. for $n=4$

$$\det \begin{bmatrix} a_{11} & \dots & a_{14} \\ \vdots & \ddots & \vdots \\ a_{41} & \dots & a_{44} \end{bmatrix} = a_{11} (-1)^{1+1} \det \begin{bmatrix} a_{22} & a_{23} & a_{24} \\ a_{32} & & \vdots \\ a_{42} & \dots & a_{44} \end{bmatrix} +$$
$$+ a_{21} (-1)^{2+1} \det \begin{bmatrix} a_{12} & a_{13} & a_{14} \\ a_{32} & a_{33} & a_{34} \\ a_{42} & a_{43} & a_{44} \end{bmatrix} + \dots$$

it's possible to show that
computing a determinant of an $n \times n$ -matrix requires
 $\sim n!$ operations (additions, summations), "flop"

floating point operations

Ex 2.2 Gaussian elimination

Example
$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 4 & 2 \\ -1 & 5 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6 \\ 16 \\ -3 \end{bmatrix}$$

Generate triangular form by adding multiples of rows to other rows [solution remains the same!]

add (-2) first row
to 2nd row
add first row to 3rd

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 0 \\ 0 & 6 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \\ 3 \end{bmatrix}$$

identical to multiplication of system with

$$L_1 = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \text{ then by } L_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$
$$= I + \mu_{21} E^{21} \qquad = I + \mu_{31} E^{31}$$

$$E^{21} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Continue...

$(-3) \times$ 2nd row
add to 3rd row

$$L_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -3 & 1 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \\ -9 \end{bmatrix} \quad (*)$$

is an upper triangular matrix

(*) can be solved easily by "backward substitution"

$$\rightarrow x = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}.$$

Elimination process:

$$L_N \dots L_2 L_1 A = U \quad \leftarrow \text{upper triangular system}$$

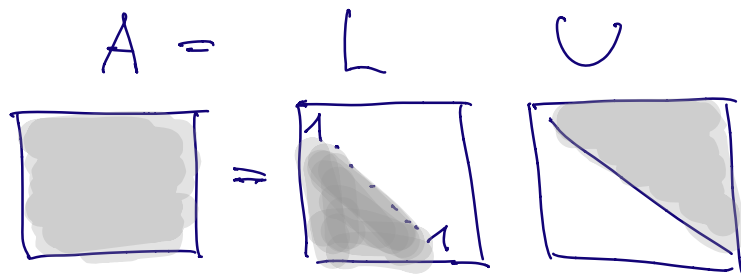
$$N = \frac{n(n-1)}{2}$$

$$L_j = I + \mu_{rs} E^{rs}$$

$$E^{rs} = \begin{bmatrix} 0 & & & 0 \\ & \ddots & & \\ & & 1 & \\ & & & \ddots & \\ & & & & 0 \end{bmatrix}$$

$$\Rightarrow A = \underbrace{L_1^{-1} L_2^{-1} \dots L_N^{-1}}_L \cdot U$$

L unit lower triangular



LU-decomposition
of A.