

S 2.1 Solving linear systems

We are interested in solving the linear system

$$Ax = b, \quad A \in \mathbb{R}^{n \times n}, \quad x, b \in \mathbb{R}^n$$

i.e:

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & & \vdots & \\ \vdots & & \vdots & \\ a_{n1} & \dots & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

Recall: $A^{-1} \in \mathbb{R}^{n \times n}$, $AA^{-1} = A^{-1}A = I = \begin{bmatrix} 1 & & & \\ & \ddots & & \\ 0 & & \ddots & \\ & & & 1 \end{bmatrix} \in \mathbb{R}^{n \times n}$

inverse exists if $\det(A) \neq 0$,

we call these matrices "non-singular", "regular",
"invertible".

Cramer's rule:

$$x_i = \frac{\det(A_i^b)}{\det(A)}$$

A_i^b ... matrix A
with i -th column
replaced by b

requires $n+1$ determinant computations to find $x \in \mathbb{R}^n$.

each determinant computation is expensive/computationally intensive, e.g. for $n=4$

$$\begin{aligned} \det \begin{bmatrix} a_{11} & \dots & a_{14} \\ \vdots & & \vdots \\ a_{41} & \dots & a_{44} \end{bmatrix} &= a_{11}(-1)^{1+1} \det \begin{bmatrix} a_{22} & a_{23} & a_{24} \\ a_{32} & \vdots & \\ a_{42} & \dots & a_{44} \end{bmatrix} + \\ &+ a_{21}(-1)^{2+1} \det \begin{bmatrix} a_{12} & a_{13} & a_{14} \\ a_{32} & a_{33} & a_{34} \\ a_{42} & a_{43} & a_{44} \end{bmatrix} + \dots \end{aligned}$$

it's possible to show that

computing a determinant of an $n \times n$ -matrix requires
 $\sim n!$ operations (additions, summations), "flop"
floating point operations

Sol.2 Gaussian elimination

Example $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 4 & 2 \\ -1 & 5 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6 \\ 16 \\ -3 \end{bmatrix}$

Generate triangular form by adding multiples of rows to other rows [solution remains the same!]

add $[-2]$ first row
 $\xrightarrow{\text{do 2nd row}}$
 $\xrightarrow{\text{add first row to 3rd}}$ $\begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 0 \\ 0 & 6 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \\ 3 \end{bmatrix}$

identical to multiplication of system with

$$L_1 = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \text{ then by } L_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$= I + \mu_{21} E^{21}$$

$$= I + \mu_{31} E^{31}$$

$$E^{21} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Continue...

$\xrightarrow{(-3) \times 2\text{nd row}}$
 $\xrightarrow{\text{add to 3rd row}}$ $\begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \\ -9 \end{bmatrix} \quad (*)$

$$L_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -3 & 1 \end{bmatrix}$$

is an upper triangular matrix

(*) can be solved easily by "backward substitution"

$$\rightarrow x = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}.$$

Def: $L \in \mathbb{R}^{n \times n}$ is lower triangular if $l_{ij} = 0$ for all

$1 \leq i < j \leq n$:

$$\begin{bmatrix} l_{11} & & & \\ \vdots & \ddots & & 0 \\ & & \ddots & \\ l_{nn} & \cdots & l_{nn} & \end{bmatrix}$$

and unit lower triangular

if $l_{11} = l_{22} = \dots = l_{nn} = 1$

Analog definitions hold for upper triangular.

Thm (Properties of lower triangular systems — identical results hold for upper triangular systems)

(i) products of lower triangular matrices are lower triangular

(ii) $\|$ unit $\|$ $\|$ unit $\|$

(iii) non-singular if $l_{11} \neq 0, l_{22} \neq 0, \dots$
lower triangular matrices that are invertible have lower triangular inverses

(iv) $\|$ $\|$ for unit lower triangular matrices

Proof of iv: Induction over matrix size,

$$\xrightarrow{n=2} L = \begin{pmatrix} a & 0 \\ b & c \end{pmatrix} \quad L^{-1} = \begin{pmatrix} d & e \\ f & g \end{pmatrix}$$

$$LL^{-1} = I \Rightarrow ac = 0, \Rightarrow c = 0 \quad \text{since } a \neq 0$$

$n \mapsto n+1$

$$L = \left[\begin{array}{c|c} L_1 & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \\ \hline -r^T & \alpha \end{array} \right] \in \mathbb{R}^{(n+1) \times (n+1)} \quad L^{-1} = \left[\begin{array}{c|c} L_1' & \begin{matrix} 1 \\ c \\ \vdots \\ 1 \end{matrix} \\ \hline r^T & \mu \end{array} \right]$$

$$\text{Since } LL^{-1} = I \xrightarrow{\text{induction}}$$

$$L_1 L_1' = I \in \mathbb{R}^{n \times n}, \quad L_1 c = 0, \quad r^T L_1' = 0, \quad r^T c + \alpha \mu = 1$$

$\Rightarrow L_1' = L_1^{-1}$ is lower triangular by induction assumption for n .

$L_1 c = 0 \Rightarrow c = 0 \Rightarrow L^{-1}$ is lower triangular \square .

Elimination process:

$$L_N \cdots L_2 L_1 A = U$$

\nwarrow upper triangular system

$N = \frac{n(n-1)}{2}$

$$L_j = I + \mu_{rs} E^{rs}$$

\nwarrow $\begin{bmatrix} 0 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 0 \end{bmatrix}$

$$\Rightarrow A = \underbrace{L_1^{-1} L_2^{-1} \cdots L_N^{-1}}_L \cdot U$$

\nwarrow unit lower triangular

$$A = L U$$

LU-decomposition
of A.