

## Initial value problems (IVP)

$$\begin{cases} y'(x) = f(x, y(x)) \\ y(x_0) = y_0 \end{cases} \quad f: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$$

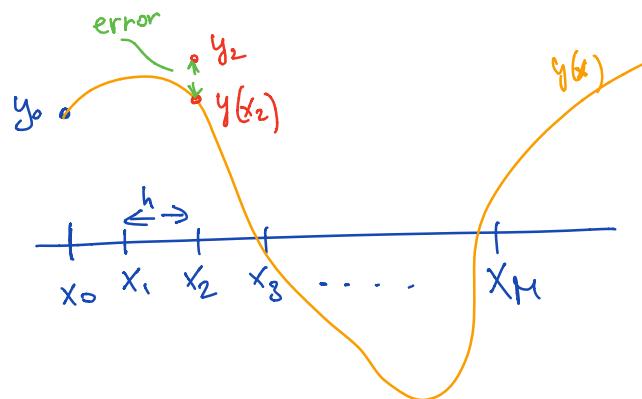
$y: [x_0, X_M] \rightarrow \mathbb{R}$ ,  $y = y(x)$  solution of the IVP

### Approximation:

points  $x_0, x_1, x_2, \dots, x_M$ ,

$$x_n = x_0 + nh, \quad h = \frac{x_M - x_0}{N}$$

$$y_k \approx y(x_k)$$



### One-step methods:

$y_{n+1}$  is computed just from  $y_n$

(different from k-step methods, where  $y_{n+1}$  is computed from  $y_n, y_{n-1}, \dots, y_{n-k+1}$ )

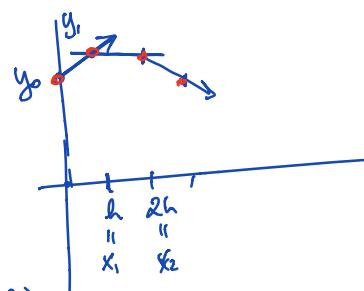
Simplest 1-step method is Euler's method

$$y_{n+1} = y_n + h f(x_n, y_n)$$

Where does this come from:

Taylor expansion of  $y(x_{n+1}) = y(x_n + h)$

$$y(x_{n+1}) = y(x_n) + h \underbrace{f(x_n, y(x_n))}_{f(x_n, y_n)} + \Theta(h^2)$$



One step method, general form:

$$y_{n+1} = y_n + h \phi(x_n, y_n; h) \quad n=0, 1, 2, \dots$$

$$e_n = y(x_n) - y_n \quad \text{error}$$

$$T_n = \frac{y(x_{n+1}) - y(x_n)}{h} - \phi(x_n, y(x_n); h) \quad \text{truncation error}$$

Theorem: Consider a one-step method, where

$$|\phi(x, u; h) - \phi(x, v; h)| \leq L_\phi |u - v|$$

Assuming  $|y_n - y_0| \leq C$  for  $n = 1, 2, \dots$

$$|e_n| \leq \frac{T}{L_\phi} \left( e^{L_\phi(x_n - x_0)} - 1 \right) \quad n=0, 1, 2, \dots$$

↑ larger for larger  $n$ ! (exponential growth of error bound)

$$T = \max_{0 \leq n \leq N-1} |T_n| \quad \text{maximum truncation error.}$$

truncation error for Euler's method:

$$T_n = \frac{y(x_{n+1}) - y(x_n)}{h} - f(x_n, y(x_n))$$

$$y(x) \in C^2 \quad y(x_{n+1}) = y(x_n + h) = y(x_n) + h y'(x_n) + \frac{h^2}{2!} y''(\xi_n)$$

$$\Rightarrow T_n = \frac{1}{2} h y''(\xi_n) \quad x_n \leq \xi_n \leq x_{n+1}$$

$$M_2 = \max_{x \in [x_0, x_N]} |y''(x)| \quad \Rightarrow |T_n| \leq T = \frac{1}{2} h M_2$$

Theorem  $\Rightarrow |e_n| \leq \frac{1}{2} M_2 \left[ \frac{e^{L(x_n - x_0)} - 1}{L} \right] h$  allows to make error small.

Example:  $y' = \tan^{-1}(y)$ ,  $y(0) = y_0$

Compute  $L$  and  $M_2$  explicitly

$$f(x,y) = \tan^{-1} y \implies |f(x,u) - f(x,v)| = \\ = \left| \frac{\partial f}{\partial y}(x,y)(u-v) \right| = \left| \frac{\partial f}{\partial y}(x,y) \right| |u-v| \quad y \in (u,v)$$

$$\left| \frac{\partial f}{\partial y}(x,y) \right| = \left| \frac{1}{1+y^2} \right| \leq 1 \implies L=1$$

$M_2$  depends on  $|y''|$  which we don't know - but we can still estimate it by differentiating  $y' = f(x,y) = \tan^{-1} y$

$$y'' = \frac{d}{dx} (\tan^{-1} y) = \frac{1}{1+y^2} \left( \frac{dy}{dx} \right) = \frac{1}{1+y^2} \tan^{-1} y$$

$\Downarrow y' = \tan^{-1} y$

$$\implies |y''| \leq M_2 = \frac{\pi}{2}$$

$$\implies |e_n| \leq \frac{1}{4} \pi (e^{x_n} - 1) h$$

I can use this to choose  $h$  such that  $|e_n| \leq \text{tol} (= 10^{-5})$ .

#### § 12.4 An implicit one-step method

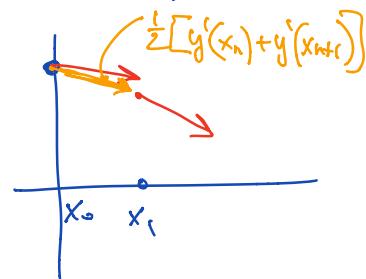
$$y_{n+1} = y_n + \frac{h}{2} [f(x_n, y_n) + f(x_{n+1}, y_{n+1})]$$

can be found from

$$y(x_{n+1}) - y(x_n) = \int_{x_n}^{x_{n+1}} y'(x) dx$$

approximate integral using trapezoidal

$$\text{rule, i.e. } \int \dots = \frac{h}{2} (y'(x_n) + y'(x_{n+1}))$$



Main difference: The right hand side depends on  $y_{n+1}$ !

So we need to solve a nonlinear equation

$$y_{n+1} - \frac{h}{2} f(x_{n+1}, y_{n+1}) = y_n + \frac{h}{2} f(x_n, y_n)$$

unknown