

Q: How do props of each hyp space carry over to $K \leq 0 / K < 0$?

Today: Rauch Comparison thm, geometric implications.

Recall 2VF: If δ is a geod, $w_1, w_2 \in \mathcal{V}(\delta)$ $w_i(0) = w_i(1) = 0$, then

$$\frac{1}{2} H(E)(w_1, w_2) = -\int_a^b \langle w_2, \Delta_+ D_+ w_1 \rangle - \int_a^b \langle w_2, D_+^2 w_1 - R(V, w_1) V \rangle dt$$

Problem: Not ~~well-def~~ if w_i do not vanish at endpoints. So we define ~~symmetric~~ ~~Hessian~~ ~~not~~ ~~well-def~~.

index form: $I(w_1, w_2) = \int_a^b \langle D_+ V, D_+ w_2 \rangle + \langle R(V, w_1) V, w_2 \rangle dt$

Prop: I is well-def, ~~red~~, symmetric, bilinear, and if $w_i(0) = w_i(1) = 0$, then $I(w_1, w_2) = \frac{1}{2} H(E)(w_1, w_2)$.

Pf: ETS: $\int_a^b \langle w_2, D_+^2 w_1 \rangle = -\int_a^b \langle w_2, \Delta_+ D_+ w_1 \rangle - \int_a^b \langle D_+ V, D_+ w_2 \rangle dt$

If w_1, w_2 smooth on $[a, b]$, then

$$\int_a^b \langle w_2, D_+^2 w_1 \rangle = \langle w_2, D_+ w_1 \rangle \Big|_a^b - \int_a^b \langle D_+ w_1, D_+ w_2 \rangle dt$$

$$= \langle w_2(b), w_1'(b^-) \rangle - \langle w_2(a), w_1'(a^+) \rangle - \int_a^b \langle D_+ w_1, D_+ w_2 \rangle dt$$

If w_1, w_2 piecewise smooth on $a = a_1 < \dots < a_n = b$, then

$$\int_a^b \langle w_2, D_+^2 w_1 \rangle = \sum_{i=1}^n \langle w_2(a_i), w_1'(a_i^-) \rangle - \sum_{i=1}^n \langle w_2(a_i), w_1'(a_i^+) \rangle - \int_a^b \langle w_1', w_2' \rangle dt$$

$$= \langle w_2(b), w_1'(b^-) \rangle - \langle w_2(a), w_1'(a^+) \rangle - \int_a^b \langle w_1', w_2' \rangle dt$$

If w_i vanish at endpoints ~~these terms vanish~~ ^{boundary}.

Further, this satisfies:

First Index Lemma: If $\delta: [0, 1] \rightarrow M$ be a geodesic with no conj. pts and $w \in \mathcal{V}(\delta)$ is a v-field with $w(0) = 0$, ~~then~~ let J be the Jacobi field st. $J(0) = 0, J(1) = w(1)$. Then

$$I(J, J) \leq I(w, w), \text{ with equality iff } J = w$$

Pf (Note: Usually this is a lemma used to prove Morse Index — but since we already proved Morse Index, it'll just follow as a consequence.)

Let ~~δ~~ extend δ to a geodesic $\bar{\delta}: [0, 1+\epsilon] \rightarrow M$, and extend w, \bar{w} to $\bar{\delta}$ by a Jacobi field ~~so that~~ ~~$\bar{w}|_{[1, 1+\epsilon]} = w$~~ ^{so that} $\bar{J}|_{[1, 1+\epsilon]} = \bar{w}$

$$\text{Then: } I(\bar{J}, \bar{J}) = I(J, J) + I(\bar{J}|_{[1, 1+\epsilon]}, \bar{J}|_{[1, 1+\epsilon]})$$

$$I(\bar{w}, \bar{w}) = I(w, w) + C$$

ETS: $H(E)(\bar{w}, \bar{w}) \geq H(E)(\bar{J}, \bar{J})$ ~~let~~ $w_0 = \bar{w} - \bar{J}$

Then $H(E)(\bar{J}, w_0) = 0$ (because $w_0 = 0$ outside $[0, 1]$ and \bar{J} is Jacobi on $[0, 1]$)

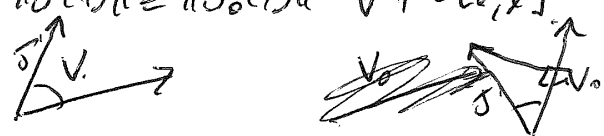
so $H(E)(\bar{w}, \bar{w}) = H(E)(\bar{J}, \bar{J}) + H(E)(w_0, w_0)$

By Morse Index, $H(E)$ is positive definite $\Rightarrow H(E)(\bar{w}, \bar{w}) \geq H(E)(\bar{J}, \bar{J})$

Rauch Comparison Theorem:

Let M, M_0 be Riemannian manifolds with $\dim M_0 \geq \dim M$,
 $\gamma, \gamma_0: [0, l] \rightarrow M, M_0$ unit-speed geodesics with $V = \gamma', V_0 = \gamma_0'$.
 Suppose that $\forall t \in [0, l], \forall X \in T_{\gamma(t)} M, X_0 \in T_{\gamma_0(t)} M_0$,
 $K(X, V) \leq K(X_0, V_0)$. Suppose no conjugate pts along γ_0 .

Then, if J, J_0 are ~~normal~~ Jacobi fields on γ, γ_0 with $J_0(0) = J(0) = 0$,
 $\langle V_0 J_0'(0) \rangle = \langle V_0(0), J_0'(0) \rangle, \|J'(0)\| = \|J_0'(0)\|$, then
 $\|J(t)\| \geq \|J_0(t)\| \forall t \in [0, l]$ (i.e., angle magnitude of J'
 angle with V ~~are the same~~
 are equal)



Pf: First: Recall that $J(t) = J^\perp(t) + \langle V(0), J'(0) \rangle \cdot V(t)$
 where J^\perp is a normal Jacobi field. So
 $\|J(t)\|^2 = \|J^\perp(t)\|^2 + t^2 \langle V(0), J'(0) \rangle^2$
 and its enough to consider the case that $J = J^\perp, J_0 = J_0^\perp$.

So: Let $f(t) = \frac{\|J(t)\|^2}{\|J_0(t)\|^2}$. — claim that $f'(t) \geq 0, \lim_{t \rightarrow 0} f(t) = 1$.

First is easy: by L'H, $\lim_{t \rightarrow 0} f(t) = \lim_{t \rightarrow 0} \frac{\langle J'(t), J'(t) \rangle}{\langle J_0'(t), J_0'(t) \rangle} = 1$.

2: $f'(t) \geq 0 \Leftrightarrow \frac{\langle J'(t), J(t) \rangle}{\langle J(t), J(t) \rangle} \geq \frac{\langle J_0'(t), J_0(t) \rangle}{\langle J_0(t), J_0(t) \rangle}$.

Let $\tau \in [0, l]$. Normalize by letting $W(t) = \frac{J(t)}{\|J(t)\|}, W_0(t) = \frac{J_0(t)}{\|J_0(t)\|}$
 ETS: $\langle W'(\tau), W(\tau) \rangle \geq \langle W_0'(\tau), W_0(\tau) \rangle$

Let E_1, \dots, E_n be ~~a field~~ fields on the frame on $\gamma, E_1 = V, E_2(\tau) = W(E)$
 E_1^0, \dots, E_n^0 " " $\gamma_0, E_1^0 = V_0, E_2^0(\tau) = W_0(\tau)$.

We can use these to translate W to γ_0 :

let $W(t) = \sum w_i(t) E_i, \bar{W}_0(t) = \sum w_i(t) E_i^0$

(we lose structure - probably not Jacobi, but that's exactly what we want)

- $\langle W_0, V_0 \rangle = 0$ - $\|W_0\|^2 = \|\bar{W}_0\|^2 = \sum w_i^2$

- $\bar{W}_0'(\tau) = W_0'(\tau)$ - $\langle W_0, W_0' \rangle = \langle W, W' \rangle$

So: $\langle V(\tau), W_0'(\tau) \rangle = \int_0^\tau \langle W_0', W_0' \rangle + \langle V_0, W_0'' \rangle dt$
 $= \int_0^\tau \langle W_0', W_0' \rangle + \langle R(V, W_0)V, W_0 \rangle dt$ (Jacobi)
 $= \int_0^\tau \langle W_0', W_0' \rangle + I(W_0, W_0) dt$

$$\begin{aligned}
 \text{OTOH: } \langle W(\tau), W'(\tau) \rangle &= \int_0^\tau \langle \dot{W}_0, \dot{W}' \rangle + \langle W_0, W_0'' \rangle \\
 &= \int_0^\tau \langle W', W' \rangle + \langle K(V, W) V, W \rangle dt + K(V, W) \|W\|^2 \\
 &\geq \int_0^\tau \langle W', W' \rangle + K(V, W_0) \|W_0\|^2 dt \\
 &= I(W_0, W_0) \geq I(W_0, W_0) //
 \end{aligned}$$

(break). (Did you do the exercise?)

Corollary. If ~~...~~

Note: we only assume that δ_0 has no conjugate pts. So —

Cor: If $K(X, Y) \leq K \leq K_M \forall X, Y \in TM$ ($K_M \leq K$), then $\forall x \in M$, $\exp_x|_{B(\frac{r}{\sqrt{K}})}$ is nonsingular

(Compare with Myers Thm from before, which said that if $Ric_M \leq \kappa(m-1)$, then every geod of length $< \frac{r}{\sqrt{\kappa}}$ has conjugate pts)

Cor: Let M, M_0 be s.t. $K_M \leq K_{M_0}$ ~~...~~ ^{simply connected} ~~...~~ ^{let $M_0 = \mathbb{R}^n$} and let $i: T_{x_0} M_0 \rightarrow T_x M$ be a norm-preserving map. ~~...~~ Suppose that $r > 0$ is s.t. $\exp_x|_B$ is a diffeo (in particular $r < \frac{r}{\sqrt{K}}$ if $K > 0$).

Let $m_0 \in M_0$ and let $i: T_{m_0} M_0 \rightarrow T_m M$ be an isometry. Then let $f: B_r(m_0) \rightarrow B_r(m)$

$f(x) = \exp_m \circ i \circ \exp_{m_0}^{-1}(x)$ Then for all paths λ in $B_r(m_0)$, $L(f(\lambda)) \geq L(\lambda)$.

Pf: Let $\tilde{\lambda}(t) = \exp_{m_0}^{-1}(\lambda(t))$, let $\alpha_0(u, v) = \exp_{m_0}(v \tilde{\lambda}(u)) \in M_0$. Then $J_0 = \frac{\partial \alpha_0}{\partial u} \Big|_{v=\tau}$ is a Jacobi field on $\gamma_0(t) = \exp_{m_0}(t \tilde{\lambda}(t))$ with $J_0(0) = 0$, $J_0(1) = \tilde{\lambda}'(1)$, $J_0'(0) = \tilde{\lambda}'(0)$.

Likewise, if $\alpha(u, v) = \exp_m(i(v \tilde{\lambda}(u)))$ then $J = \frac{\partial \alpha}{\partial u} \Big|_{v=\tau}$ is Jacobi with $J(0) = 0$, $J(1) = (f \circ \lambda)'(1)$, $J'(0) = i(\tilde{\lambda}'(0))$.

— so Rauch applies and $\|J(u)\| \geq \|J_0(u)\|$
 $\|(f \circ \lambda)'(1)\| \geq \|\tilde{\lambda}'(1)\|$

$L(f \circ \lambda) \geq L(\lambda)$

So, if $K_M \leq 0$, then ~~there is a length-increasing map from $\mathbb{R}^n \rightarrow M$ around each~~

~~This is cumbersome to use, but there is a beautiful condition that~~

~~Use this to prove the CAT(0) - condition~~

Seems a bit cumbersome, but will use this to prove that if $K_M \leq 0$, then M satisfies CAT(0) condition.

Def: A geodesic triangle is a loop composed of three geodesic segments — we'll write $\Delta[p, q]$ for the segments, $\Delta(p, q, r)$ for the triangle.


If Δ is a geodesic triangle, the comparison triangle $\bar{\Delta} = \bar{\Delta}(p, q, r)$ is the triangle in \mathbb{R}^2 with side lengths $d(p, q), d(q, r), d(p, r)$.

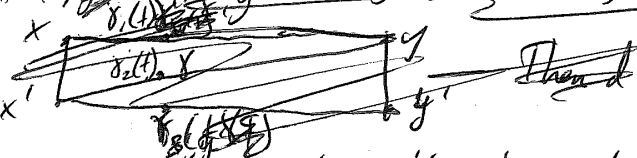
~~Then~~ If X is a geodesic metric space, we say X is CAT(0) if \forall geod. tris. $\Delta, \forall x, y \in \Delta, d(x, y) \leq d(\bar{x}, \bar{y})$.

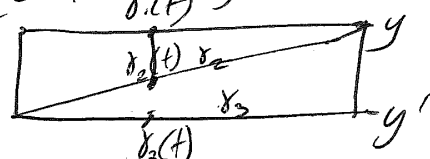
- every measurement of the triangle is bounded by the corresp measurement in \mathbb{R}^2

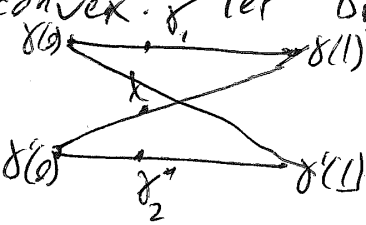
Note: No ~~convex~~ requirement that X is a manifold!
In fact, trees are CAT(0) - check this.

Properties: $\forall x, y \in X$,
- there is a unique geodesic from x to y

pf: Suppose not.
Suppose p, q is a geod. triangle, γ, γ' geods from p to q .
 So ...

~~if γ varies continuously with its end pts~~


γ_{xy} varies continuously with its end pts. In fact,


In fact, let's prove that $d: X \times X \rightarrow \mathbb{R}$ the distance function is convex: let γ_1, γ_2 be geodesics, let $f \in [0, 1]$.
 let γ_3 be the geod from $\gamma_1(0)$ to $\gamma_2(1)$.

Claim: $\forall t \in [0, 1]$
 $d(\gamma_1(t), \gamma_2(t)) \leq (1-t)d(\gamma_1(0), \gamma_2(0)) + td(\gamma_1(1), \gamma_2(1))$

pf: let λ be the geod from $\gamma_2(0)$ to $\gamma_2(1)$.
Then $\Delta(\gamma_1(0), \gamma_1(1), \gamma_2(0))$ is a comparison triangle by similar tris, $d(\gamma_1(t), \lambda(t)) \leq (1-t)d(\gamma_1(0), \gamma_2(0))$.
Likewise, $d(\lambda(t), \gamma_2(t)) \leq t d(\gamma_1(1), \gamma_2(1))$.

- Balls are convex.
- Approximate midpoints close to midpoints.
- Contractible.

Last time, Rauch and corollary:

If M, M_0 mfd's, $K_M \leq K_{M_0}$, and $m_0 \in M_0$, $r > 0$ s.t. $\exp_{m_0} |_{B_r(0)}$ is a diffeomorphism, and $i: \mathbb{R}^n \rightarrow T_{m_0} M$ is an isometry. Then f is length-increasing \forall curves γ in $B_r(m_0)$, $L(f(\gamma)) \geq L(\gamma)$.

Today, apply this: The CAT(0) condition

Def: A geodesic triangle is a loop made of three geodesic segments

Write $[p, q]$ for the edges, $\Delta(p, q, r)$ for the triangle.

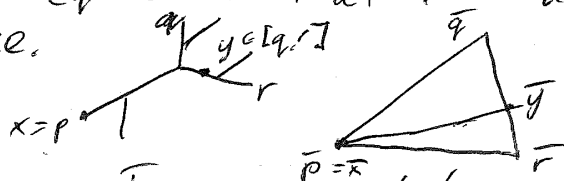
If Δ is a geod. triangle, the comparison triangle $\bar{\Delta} = \bar{\Delta}(\bar{p}, \bar{q}, \bar{r})$ is a triangle in \mathbb{R}^2 with the same side lengths

If $x \in [p, q]$, the comparison point $\bar{x} \in [\bar{p}, \bar{q}]$ is the point s.t. $d(x, p) = d(\bar{x}, \bar{p})$

If X is a geodesic metric space, we say that X is CAT(0) if \forall geodesic triangles Δ , $\forall x, y \in \Delta$, $d(x, y) \leq d(\bar{x}, \bar{y})$
 - every measurement is bounded by the corresponding measurement in \mathbb{R}^2 .

Note: No requirement that X is a manifold!

Ex: tree.



(but note that in general, we compare pts on edges too)

In general, checking CAT(0) is cumbersome, but:

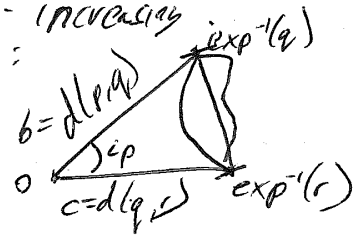
Thm: TFAE:

- X is CAT(0)
 - $\forall \Delta(p, q, r), \forall x \in [q, r], d(p, x) \leq d(\bar{p}, \bar{x})$
 - $\forall \Delta(p, q, r), \angle p \leq \angle \bar{p}$ if p, q, r distinct, then $\angle p \leq \angle \bar{p}$
- Pf omitted.

Then: If M is a complete, simply-connected manifold and $K_M \leq 0$, then M is CAT(0).

Pf: By the corollary, if $m \in M$, then \exp_m is a diffeo. By the corollary, \exp_m is length-increasing.

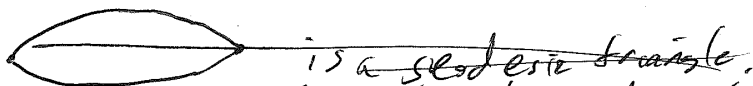
Consider $\exp_p^{-1}(\Delta)$:



$$\begin{aligned} \text{So } \sqrt{b^2 + c^2 - 2bc \cos L_p} &\leq d(q, r) \\ &= \sqrt{b^2 + c^2 - 2bc \cos L_{\bar{p}}} \\ &\Rightarrow L_p \leq L_{\bar{p}} \quad // \end{aligned}$$

Properties: If X is CAT(0), then:

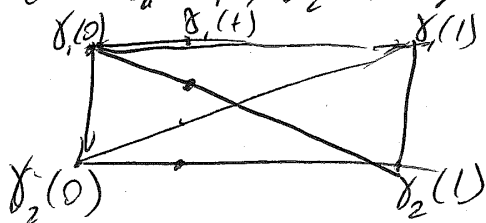
~~$\forall x, y, \exists!$ geodesic $\gamma_{x,y}$ from x to y .~~



~~$\gamma_{x,y}$ varies continuously with its endpoints.~~

In fact, $d: X \times X \rightarrow \mathbb{R}$ is convex: $\exists!$ from p_i to q_i

Let γ_1, γ_2 be geodesics. Then $\forall t \in [0, 1]$
 Let λ be a geodesic from $\gamma_1(t) + \gamma_2(t)$



Then
 $d(\gamma_1(t), \lambda(t)) \leq d(\gamma_1(1), \gamma_2(1))t$
 $d(\gamma_2(t), \lambda(t)) \leq d(\gamma_1(0), \gamma_2(0))(1-t)$

by similar triangle argument. So
 $d(\gamma_1(t), \gamma_2(t)) \leq (1-t)d(\gamma_1(0), \gamma_2(0)) + td(\gamma_1(1), \gamma_2(1))$

Cor: $\forall x, y \in X, \exists!$ $\gamma_{x,y}$ from x to y , which varies smoothly.

Pf: If γ_1, γ_2 are geodesics, and $d(\gamma_1, \gamma_2)$ are as above, then

$$d(\gamma_1(t), \gamma_2(t)) \leq \max\{d(p_1, p_2), d(q_1, q_2)\}$$

So if $p_1 = p_2, q_1 = q_2$, then $\gamma_1 = \gamma_2$.

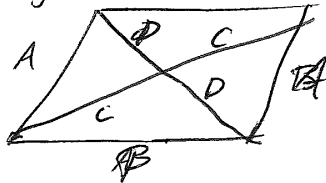
Likevise, if $d(p_1, p_2), d(q_1, q_2) < \epsilon$ then $d(\gamma_1, \gamma_2) < \epsilon$.

Every metric ball is convex (easy)

Every metric ball is strictly convex:

$\forall x \in X, \forall r, \epsilon > 0, \exists \delta$ s.t. if $y, z \in B_x(r)$ and $d(y, z) > \epsilon$,
 where m is midpoint of y, z .

Pf: Parallelogram law.



$$A^2 + B^2 = 2(C^2 + D^2)$$

$$\Rightarrow \text{if } A, B \leq r, D > \epsilon, \text{ then}$$

$$2C^2 + 2\epsilon^2 \leq 2r^2$$

$$\Rightarrow C \leq \sqrt{r^2 - \epsilon^2}$$

In fact, $d(x, m) < \frac{\sqrt{d(x, y)^2 + d(x, z)^2}}{2} = \frac{d(y, z)}{2} = r - \frac{\epsilon^2}{2r}$

This lets us define Not true, e.g. in S^2 , or in L^1 -metric on \mathbb{R}^2 .

will let us prove some nice things: X is complete (by much) standard X CAT(0) con

Thm: Suppose that $C \subset X$ is convex (if $x, y \in C$, then $\gamma_{x,y} \subset C$)

Then $\forall x \in C, \exists!$ $\tilde{r}(x) \in C$ s.t. $d(x, \tilde{r}(x)) = d(x, C)$

Further:

- $\forall x \notin C, y \in C, \tilde{r}(y) \neq \tilde{r}(x)$ then $\angle_{\tilde{r}(x)}(x, y) \geq \pi/2$.
- The map $x \mapsto \tilde{r}(x)$ is distance-decreasing.

Pf: Suppose that $y_1, \dots, y_n \in C$, and $\lim_{n \rightarrow \infty} d(x, y_n) = d(x, C) = r$.

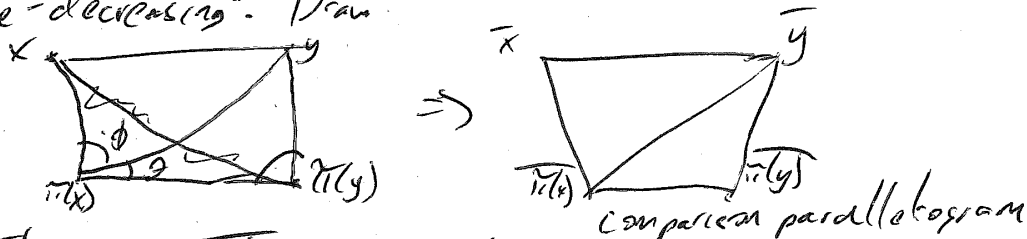
Claim: (y_i) is Cauchy. Suppose $y_i, y_j \in C$, $d(x, y_i) < r + \epsilon$
 $d(x, y_j) < r + \epsilon$.

Then Let m be the midpoint of y_i, y_j . Then $m \in C$, so
 $r \leq d(x, m) < r + \epsilon - \Omega\left(\frac{d(y_i, y_j)}{r}\right) \Rightarrow d(y_i, y_j) = O(\sqrt{\epsilon})$.

$\Rightarrow (y_i)$ is Cauchy. Further, the limit is ~~well~~ well-defined -
 if (y'_i) is another such sequence, then $y_i, y'_i, y_2, y'_2, \dots$
 is still also Cauchy, so $\lim y_i = \lim y'_i$.

Angles: If $y \in C$, then $[y, \pi(x)] \subset C$. If $\angle \pi(x)(x, y) < \pi/2$,
 then $d(x, [y, \pi(x)]) < d(x, \pi(x)) = d(x, C)$.

Ret. Distance-decreasing. Draw



Then $\angle \pi(y) \geq \angle \pi(x) \geq \pi/2$
 $\angle \pi(x) \geq \theta + \phi \geq \angle \pi(x) \geq \pi/2$.

$\Rightarrow d(x, y) \geq d(\pi(x), \pi(y))$.

(and we'll see examples of convex sets in omega)

Another application of this ~~conv~~

Thm (Carathéodory): If $F \in \mathcal{P} X$ is complete, $\text{AT}(\emptyset)$, and $F \in \mathcal{I}(\text{set } K)$
 is an ~~isometry~~ h_t with a bounded orbit, then F fixes a point.

Pf:

Def: The radius of a set Y is the infimal radius of a ball containing Y -

$$r_Y = \inf \{ r \mid \exists x \in X, Y \subset B_r(x) \}$$

Prop: If X is complete, $\text{CAT}(\theta)$, $Y \subset X$ is a bounded set, then $\exists x \in X$

s.t. $Y \subset B_r(x)$. (circumcenter)

Pf: Let $x_1, \dots, x_n \in X$ be s.t. $Y \subset B_{r_i}(x_i)$, $r_1, \dots, r_n > 0$ be s.t.
 $\lim_{n \rightarrow \infty} r_i = r_Y$.

Claim: (x_i) is Cauchy.

- Same argument: if x, x' are s.t. $Y \subset B_{r+\epsilon}(x)$
 $Y \subset B_{r+\epsilon}(x')$.

then $\forall y, d(x, y) \leq r + \epsilon, d(x', y) \leq r + \epsilon$, so
 $d(x, x') \leq r + \epsilon - \Omega\left(\frac{d(x, x')}{r}\right)$

So, if X is complete Γ has a bounded orbit
 let $y = \Gamma x$, $c = c_y$. Then Γ fixes y , so it fixes c_y .
 by uniqueness. //

More generally, we can classify isoms of CAT(0) spaces similarly to those of \mathbb{H}^n space.

Classification of isometries.

If $f: X \rightarrow X$ is an isometry, let $d_f: X \rightarrow \mathbb{R}$ be the displacement function $d_f(x) = d(x, f(x))$.

Let $|f| = \inf d_f =$ translation length of f .

Let $\text{Min}(f) = d_f^{-1}(|f|)$.

Then:

- $\text{Min}(f)$ is invariant under f .
- $\forall \alpha \in \text{Isom}(X)$, $|f| = |\alpha \circ f \circ \alpha^{-1}|$, $\text{Min}(\alpha \circ f \circ \alpha^{-1}) = \alpha \text{Min}(f)$
- d_f is convex, so $\text{Min}(f)$ is closed, convex.

We say that either

- f is elliptic if f has a fixed pt ($|f| = 0$, $\text{Min}(f) \neq \emptyset$)
- f is hyperbolic if $|f| > 0$, $\text{Min}(f) \neq \emptyset$
- f is parabolic if $\text{Min}(f) = \emptyset$.

Ex: $X = \mathbb{R}^n$. $f(x) = Ax + b$. If f fixes a pt, then f is elliptic.

If f is not elliptic, then $x = Ax + b$ has no solutions \Rightarrow

$(A - I)$ is singular. Let $V = \text{Null}(A - I)$.

If $V = \mathbb{R}^n$, then f is a translation.

Otherwise, write $\mathbb{R}^n = V \oplus V^\perp$. A fixes V , V^\perp , so

$f(v_1, v_2) = (v_1 + b_1, A_2 v_2 + b_2)$

Further, $A_2 - I$ is nonsingular, so $f_2(v_2) = A_2 v_2 + b_2$

has a unique fixed pt.

Clearly,

Then $d_f(x, v_2) \geq \|b\|$, with equality iff $f_2(v_2) = v_2$.

$\Rightarrow |f| = \|b\|$, $\text{Min}(f)$ is a plane parallel to V .

f acts by translation on $\text{Min}(f)$

(in particular, no parabolic isometries)

Ex: $X = \mathbb{H}^n$: elliptic; d_f depends on distance to fixed pt.

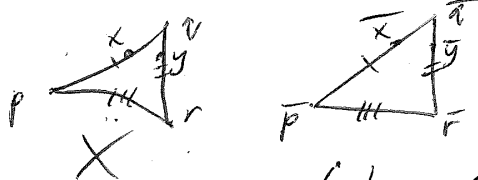
- min achieved at fixed pt

hyp: ~~always an axis~~

- $\text{min}(f) =$ axis - d_f depends on distance to axis, angle

- Next time, see why there's always a unique axis.

Last time: CAT(0) condition:



$\forall x, y, d(x, y) \leq d(\bar{x}, \bar{y})$
 $\forall p, q, r, y \in [q, r], d(p, y) \leq d(\bar{p}, \bar{y})$

(where $\angle_p(x, y) = \limsup_{t \rightarrow 0} \frac{1}{t} \angle(x(t), y(t))$ - for manifolds, this limit always exists.)

Today symmetries, but first, a ~~lemma~~ demonstration how powerful this cond is:
~~some~~ Flat subspaces of CAT(0) spaces

Standing assumption: X is a CAT(0) space.

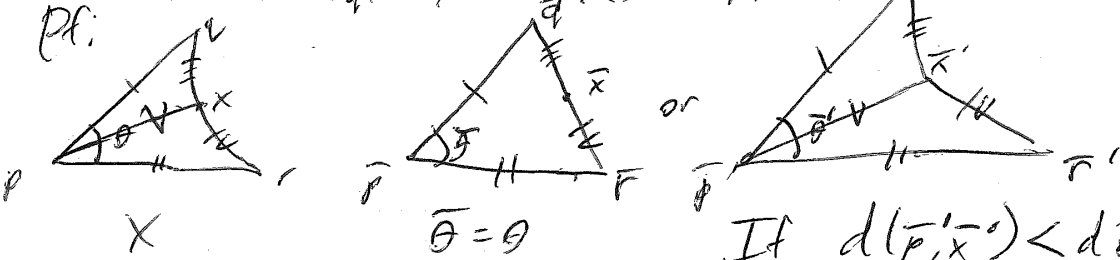
Flat Triangle Lemma: If $\Delta = \Delta(p, q, r)$ and $\bar{\Delta} = \Delta(\bar{p}, \bar{q}, \bar{r})$ is a comparison triangle, then and $\angle_p = \angle_{\bar{p}}$ or if $\exists x, y \in \Delta$ s.t. $d(x, y) = d(\bar{x}, \bar{y})$ (and x, y not on same edge), then the convex hulls $C(\Delta)$ and $C(\bar{\Delta})$ are isometric (i.e., solid triangles)

Note: $C(S)$ = minimal convex set containing S .
 - in general, the convex hull of a triangle need not be 2-dimensional.

Pf: Suppose $\angle_p = \angle_{\bar{p}}$

1. If $x \in [q, r]$, then $d(p, x) = d(\bar{p}, \bar{x})$

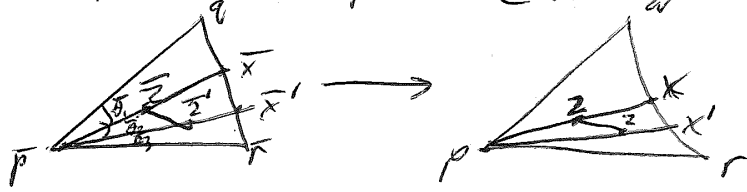
Pf:



If $d(\bar{p}, \bar{x}') < d(\bar{p}, \bar{x})$, then $\bar{\theta}' < \bar{\theta}$ (by law of cosines).
 So $d(\bar{p}, \bar{x}) = d(\bar{p}', \bar{x}') = d(p, x)$

But then $\theta \leq \theta' < \bar{\theta} = \theta$ *

Now, define a map $t: C(\bar{\Delta}) \rightarrow X$ by sending $[\bar{p}, \bar{x}]$ to $[p, x]$ and $\forall \bar{r} \in [\bar{q}, \bar{r}]$.



Claim: Isometry. Suppose $z, z' \in \bar{\Delta}$ Claim: $d(z, z') = d(\bar{z}, \bar{z}')$

But all these lengths are equal, so $\bar{A}, \bar{B}, \bar{C}$ are comparison triangles for A, B, C . Then $\bar{\theta}_1 \geq \theta_1 \Rightarrow \bar{\theta}_1 = \theta_1$. Important as is $\theta_2 = \theta_2$.
 If $d(z, z') < d(\bar{z}, \bar{z}')$, then $\Delta(p, \bar{z}, \bar{z}')$ has an angle smaller than $\theta_2 \Rightarrow \theta_2 < \theta_2$ *

Ex: Show that if $d(x, y) = d(\bar{x}, \bar{y})$ nontrivially, then $\angle_p = \angle_{\bar{p}}$:

Similarly: Flat Quadrilateral Theorem: if p, q, r, s form a quadrilateral and $\alpha + \beta + \gamma + \delta$ the sum of the angles is $\geq 2\pi$, then in fact, $C(p, q, r, s)$ is isometric to a Euclidean quad.

How does this affect the geometry?

Def: We say that geodesics γ, γ' are parallel if $d(\gamma(t), \gamma'(t))$ is constant.

Flat Strip Theorem: Suppose $\gamma: \mathbb{R} \rightarrow X, \gamma': \mathbb{R} \rightarrow X$ are geodesics s.t. $d(\gamma(t), \gamma'(t))$ is bounded. Then γ, γ' are parallel and $C(\gamma(\mathbb{R}), \gamma'(\mathbb{R})) \cong I \times \mathbb{R}$.

Pf: - γ, γ' are parameterized with same speed.

Let $\pi: X \rightarrow \gamma$ be closest-point projection, parameterize so $\pi(\gamma(0)) = \gamma(0)$.

Then $f(t) = d(\gamma(t), \gamma'(t))$ is convex, bdd \Rightarrow constant.

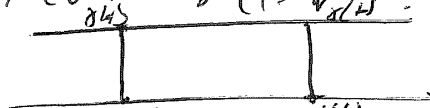
In fact, $f_a(t) = d(\gamma(t), \gamma'(t+a)) \Rightarrow$ constant,

and $f_a(0)$ is minimized when $a=0$.

So $\pi(\gamma'(t)) = \gamma(t) \forall t$. Likewise,

if $\pi': X \rightarrow \gamma'$, then $\pi'(\gamma(t)) = \gamma'(t) \forall t$.

So $\forall a, b \in \mathbb{R}$, draw:



All angles are $\geq \frac{\pi}{2}$, so this is a Euclidean rectangle.

So the map $I \times \mathbb{R} \rightarrow X$

Product Decomposition $\rightarrow I \times \mathbb{R} \rightarrow [\gamma(t), \gamma'(t)]$ is an isom //

Thm: If γ is a geod, let

$X_\gamma = \cup \{ \gamma'(\mathbb{R}) \mid \gamma' \text{ is parallel to } \gamma \}$.

Then X_γ is convex, and $X_\gamma \cong X_\gamma^0 \times \mathbb{R}$, where X_γ^0 is a CAT(0)-space.

Pf: Exercise

Isometries: Recall: If $f \in \text{Isom}(X)$.

- $d_f(x) = d(x, f(x))$ — displacement function

- $|f| = \inf d_f$ — translation length

- $\text{Min}(f) = d_f^{-1}(|f|)$.

Def: f is elliptic $\Leftrightarrow |f| = 0, \text{Min}(f) \neq \emptyset$

f is hyperbolic $\Leftrightarrow |f| > 0, \text{Min}(f) \neq \emptyset$

f is parabolic $\Leftrightarrow \text{Min}(f) = \emptyset$.

Ex: In H^n this case is the same as the previous def:

elliptic: fix a point $\Rightarrow \text{Min}(f)$ is totally geodesic

hyperbolic: fix exactly two points in $\partial_\infty H^n \Rightarrow |f| > 0, \text{Min}(f) = \text{geodesic axes}$

parabolic: fix exactly one point in $\partial_\infty H^n \Rightarrow |f| = 0, \text{Min}(f) = \emptyset$.

Exercise: All isoms of \mathbb{R}^n are elliptic or hyperbolic. $\text{Min}(f)$

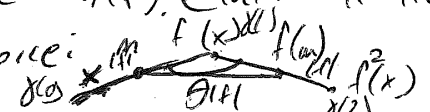
If f is hyperbolic, there is a decomp $\mathbb{R}^n = V \oplus V^\perp$

where f acts on V by translation, V^\perp by rotation/reflection, $\text{Min}(f) = V$.

Generally: If $f \in \text{Isom}(X)$, an axis of f is a geodesic γ s.t. $\forall t, f(\gamma(t)) = \gamma(t+a)$.
 Lemma: Any axis is contained in $\text{Min}(f)$ by projection & translation by f .

Then: If $f \in \text{Isom}(X)$, an axis of f is a geodesic γ s.t. $\forall t, f(\gamma(t)) = \gamma(t+a)$.
 If $f \in \text{Isom}(X)$ is hyperbolic, then f has an axis. In fact,
 - $\text{Min}(f) = \cup$ axes of f and all axes are parallel.
 - $\text{Min}(f) \cong Y \times \mathbb{R}$, where Y is $\text{CAT}(0)$, and $f(y, t) = (y, t+a)$.
 - If g commutes with f , then $g(y, t) = (g(y), t+b)$, where $b \in \mathbb{R}$, $g \in \text{Isom}(Y)$.

Pf: Recall: $\text{Min}(f)$ is convex, $f(\text{Min}(f)) = \text{Min}(f)$, if $[f, g] = \text{id}$, then $g(\text{Min}(f)) = \text{Min}(f)$, more generally,

Suppose $x \in \text{Min}(f)$. Claim: x lies on an axis.
 Natural choice: γ connecting $f^{-1}(x), x, f(x), \dots$.


Claim: γ is a geodesic. ~~Let $m = \text{mid}(x, f(x))$. Then $d(m, f(m)) = |a|$, so $d(m, f(m)) = |a|$. So the broken geodesic γ is a geodesic.~~
 But γ is a path of length $|a|$ from m to $f(m) \Rightarrow \gamma$ is a geodesic.
 ~~γ is a geodesic from m to $f(m)$.~~
 ~~$[m, f(m)] \in \gamma \Rightarrow \gamma$ is a geodesic.~~
 ~~$[m, f(m)] \in \gamma \Rightarrow \gamma$ is a local geodesic.~~

Ex: Every local geodesic in a $\text{CAT}(0)$ space is a geodesic. (induction)
 Claim: γ is a geodesic.

- All axes are parallel; contained in a minset .
 Suppose γ, γ' are axes. Then $d(\gamma(t), \gamma'(t)) = d(f(\gamma(t)), f(\gamma'(t))) = d(\gamma(t+a), \gamma'(t+a)) = d(\gamma(t), \gamma'(t))$.
 Parameterize so $f(\gamma(t)) = \gamma(t+a)$. So $g(t)$ is periodic, convex \Rightarrow constant. $\Rightarrow \gamma, \gamma'$ are parallel.

(ant f translates both by same distance).
 - $\text{Min}(f) \cong Y \times \mathbb{R}$: Let γ be an axis, $M = \text{Min}(f)$.
 Then M is convex $\Rightarrow M$ is $\text{CAT}(0)$. We know $M = \cup$ axes, and M is a $\text{CAT}(0)$ space. So $M \cong Y \times \mathbb{R}$.

Further, f translates each axis by $|a|$, so $f(y, t) = (y, t+|a|)$.
 If γ is a geodesic, let λ be an axis. Then $\gamma \parallel \lambda$.
 Let γ' be the axis through $\gamma(0)$. Then $\gamma \parallel \gamma' \Rightarrow \gamma' \parallel \lambda \Rightarrow \gamma' = \lambda$.
 So M is a $\text{CAT}(0)$ space that's the union of parallel geodesics.
 Product Decomposition Theorem $\Rightarrow M \cong Y \times \mathbb{R}$.

- If g commutes with f , then ~~$g(M) = M$~~ Then $g(M) = M$

- Suppose g commutes with f , γ an axis of f .
Then:

- $f(\gamma(t)) = \gamma(t + |f|) \Rightarrow$ so

$f(g(\gamma(t))) = g \circ f(\gamma(t)) = g(\gamma(t + |f|))$

So $g \circ \gamma$ is an axis

$\Rightarrow g(M) = M$, g sends axes to axes.

$\Rightarrow g(y, t) = (g(y), t + b)$

(g action sets axes by an isom, g acts on each axis by an isom)

Preview of next time: And this is a powerful result:

One of the key questions: If M is a compact manifold, does it have a metric with $K_n \leq 0$?

If M compact, $K_n \leq 0$, then $X = \tilde{M}$ is $(\text{Ad}(0))$ and $\pi = \pi_1(M)$ acts on X by isometries

In fact, hyperbolic isometries. This is a strong condition.

We can prove a splitting theorem. We can use the axes to prove a splitting theorem.

Thm: If Γ is finitely generated, acts on X , and if $a \in \mathbb{Z}(\Gamma)$ acts as a hyperbolic isometry, then \exists a finite-index $G \subset \Gamma$ s.t. $G \cong \langle a \rangle \times H$

By theorem, Pf: $M_n(a) \cong Y \times \mathbb{R}$. If $g \in \Gamma$, then g acts on $M_n(a)$.

Let $\beta: \Gamma \rightarrow \mathbb{R}$, $g(y, t) = (g(y), t + \beta(g))$

$\beta(g) = b_g$. Then $\beta(a) \neq 0$, and since Γ is f.g., $\beta(\Gamma) \cong \mathbb{Z}^n$

$\exists \rho: \mathbb{Z}^n \rightarrow \mathbb{Z}$ s.t. $\rho(\beta(a)) \neq 0$. Let $\phi = \rho \circ \beta: \Gamma \rightarrow \mathbb{Z}$

Let $G = \phi^{-1}(\phi(a)\mathbb{Z})$
 $H = \ker \phi$.

Then $H \langle a \rangle = G$,
 $H \cap \langle a \rangle = \{0\}$,
and $a \in \mathbb{Z}(H)$, so
 $G \cong \langle a \rangle \times H$.