

Frequentist

- ① Probability is consistent with long term relative frequency.
- ② Parameters are fixed unknown constants, not random quantities.
- ③ Statistical procedures should have well-defined long-run properties.

Bayesian

- ① Probability is a degree of belief that an event will occur.
- ② Can make probabilistic statements about parameters even though they are fixed constants.
- ③ Parameter inference is done by computing a probability distribution of  $\theta$ , point estimates are computed after the fact.

## Example of a Bayesian Method

Goal make a statement about some unknown parameter  $\theta$ .

① Choose a prior distribution  $f(\theta)$  which captures initial belief about  $\theta$ .

② Choose a statistical model  $f(\vec{x}|\theta)$  which captures beliefs about data  $\vec{x}$  given the parameter  $\theta$ : conditional distribution

Note: Write  $f(\vec{x}|\theta)$  instead of  $f(\vec{x};\theta)$ .

③ Observe  $X_1, \dots, X_n$ , update our belief about  $\theta$  in the form:  $f(\theta|\vec{x}) \leftarrow$  the posterior distribution

The posterior is just a conditional distribution:


$$f(\theta | \vec{x}) = \frac{f(\theta, \vec{x})}{f(\vec{x})} = \frac{f(\vec{x} | \theta) f(\theta)}{\int f(\theta, \vec{x}) d\theta}$$
$$= \frac{f(\vec{x} | \theta) f(\theta)}{\int f(\vec{x} | \theta) f(\theta) d\theta} \quad \left. \vphantom{\frac{f(\vec{x} | \theta) f(\theta)}{\int f(\vec{x} | \theta) f(\theta) d\theta}} \right\} \text{Bayes Theorem.}$$


In the case of  $n$  IID observations  $x_1, \dots, x_n$ ,

$$f(\vec{x} | \theta) = \prod_{i=1}^n f(x_i | \theta) = \mathcal{L}(\theta),$$

and therefore

$$f(\theta | \vec{x}) = \frac{f(\vec{x} | \theta) f(\theta)}{\int f(\vec{x} | \theta) f(\theta) d\theta} = \frac{\mathcal{L}(\theta) f(\theta)}{C}$$


  
function of  $\theta$

  
a constant  $C = C(\vec{x})$

The constant  $C$  is such that  $\int f(\theta | \vec{x}) d\theta = 1$   
 $= \int \frac{\mathcal{L}(\theta) f(\theta)}{C} d\theta.$


Often for this reason, we will write

$$f(\theta | \vec{x}) \propto \mathcal{L}(\theta) f(\theta).$$

  
posterior                  model                  prior

To generate a point estimate compute a functional of the posterior  $f(\theta | \vec{x})$ :

$$\bar{\theta} = \mathbb{E}(\theta | \vec{x}) = \int \theta f(\theta | \vec{x}) d\theta = \frac{\int \theta \mathcal{L}(\theta) f(\theta) d\theta}{\int \mathcal{L}(\theta) f(\theta) d\theta}$$

  
Bayesian estimator

Posterior  $\alpha$  interval (not a confidence interval)

Find  $a, b$  such that

$$P(\theta | \vec{x} \in (a, b)) = 1 - \alpha = \int_a^b f(\theta | \vec{x}) d\theta.$$

Example  $X_1, \dots, X_n \sim \text{Bernoulli}(p)$  random variables

$$\begin{aligned} \text{Our model: } f(\vec{x} | p) &= \mathcal{L}(p) \\ &= \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i} \end{aligned}$$

$$\begin{aligned} \text{prior: } p &\sim \text{Uniform}(0, 1) \\ f(p) &= 1 \text{ on } (0, 1). \end{aligned}$$

$$\begin{aligned} \text{posterior } f(p | \vec{x}) &\propto \mathcal{L}(p) f(p) \\ &= \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i} \\ &= p^s (1-p)^{n-s} \quad s = \sum_{i=1}^n x_i. \end{aligned}$$

think of this as a function of  $p$ , not  
the data  $x_i$  anymore

$$= p^{(s+1)-1} (1-p)^{(n-s+1)-1}$$

Now identify which family of probability distribution  
 $\mathcal{L}(p) f(p)$  belongs to.

Recall: Beta( $\alpha, \beta$ ) density:  $f(p; \alpha, \beta) = \frac{\Gamma(\alpha, \beta)}{\Gamma(\alpha) \Gamma(\beta)} p^{\alpha-1} (1-p)^{\beta-1}$

$$\Rightarrow f(p | \vec{x}) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha) \Gamma(\beta)} p^{\alpha-1} (1-p)^{\beta-1} \quad \text{with } \begin{aligned} \alpha &= 1 + \sum x_i \\ \beta &= 1 + n - \sum x_i \end{aligned}$$

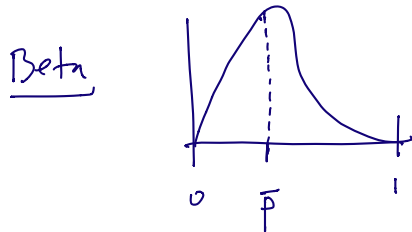
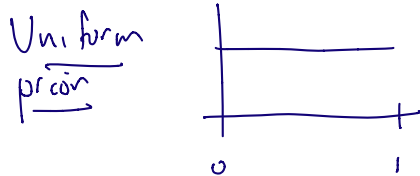
$$\Rightarrow p | \vec{x} \sim \text{Beta}(\alpha, \beta).$$

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Bayes estimator:

$$\bar{p} = E(p|\bar{x}) = \frac{s+1}{n+2} \text{ mean of } \beta(\alpha, \beta) = \frac{\alpha}{\alpha+\beta}.$$

Graphically



Part 2 If we use the prior  $p \sim \text{Beta}(\alpha, \beta)$ , then repeating the calculation gives

$$p|\bar{x} \sim \text{Beta}(\alpha+s, \beta+n-s).$$

(Note: that  $p \sim \text{Unif}(0,1)$  is just  $p \sim \text{Beta}(1,1)$ )

This is a case when the prior family equals the posterior family.

We say that "the prior is conjugate with respect to the model".

$$f(p|\bar{x}) \propto \overset{\text{model}}{f(\bar{x}|p)} f(p)$$

same family

## Functions of parameters

- Recall from MLE that if  $\hat{p}$  is the MLE estimate for  $p$ , then the MLE estimate for  $\tau = g(p)$  was just  $\hat{\tau} = g(\hat{p})$ .
- Furthermore if  $Y = g(X)$ , then
$$F(y) = \mathbb{P}(Y \leq y) = \mathbb{P}(g(X) \leq y) = \int_{g(x) \leq y} f(x) dx$$
and  $f(y) = F'(y)$ .

We can use these ideas for Bayesian inference as well.  
Let  $\tau = g(\theta)$ .

Bayes says:  $f(\theta | \vec{x}) \propto L(\theta) f(\theta)$ .

$$\begin{aligned} \text{Posterior CDF for } \tau = g(\theta) | \vec{x} &= H(\tau | \vec{x}) \\ &= \mathbb{P}(g(\theta) \leq \tau | \vec{x}) \\ &= \int_{g(\theta) \leq \tau} f(\theta | \vec{x}) d\theta \end{aligned}$$

Then the posterior  $h(\tau | \vec{x}) = \frac{d}{d\tau} H(\tau | \vec{x})$ .

Example  $X_i \sim \text{Bernoulli}(p)$ , prior  $f(p) = 1$ .

$$\Rightarrow p | \vec{x} \sim \text{Beta}(s+1, n-s+1). \quad \text{Let } \psi = \log\left(\frac{p}{1-p}\right).$$

$p \in (0, 1) \Rightarrow \psi \in (-\infty, \infty)$ .

$$\begin{aligned} \Rightarrow H(\psi | \vec{x}) &= \mathbb{P}\left(\log \frac{p}{1-p} \leq \psi | \vec{x}\right) \\ &= \mathbb{P}\left(p \leq \frac{e^\psi}{1+e^\psi} | \vec{x}\right) \end{aligned}$$

$$= \int_0^{e^\gamma / (1+e^\gamma)} f(p | \vec{x}) dp$$

$$= \int_0^{e^\gamma / (1+e^\gamma)} \frac{\Gamma(n+2)}{\Gamma(s+1)\Gamma(n-s+1)} p^s (1-p)^{n-s} dp$$

To compute  $h(\gamma | \vec{x})$ , compute  $\frac{d}{d\gamma} H(\gamma | \vec{x})$ :


$$h(\gamma | \vec{x}) = \frac{d}{d\gamma} H(\gamma | \vec{x})$$


$$= \frac{d}{d\gamma} \left( \int_0^{e^\gamma / (1+e^\gamma)} \frac{\Gamma(n+2)}{\Gamma(s+1)\Gamma(n-s+1)} p^s (1-p)^{n-s} dp \right)$$

$$= \frac{\Gamma(n+2)}{\Gamma(s+1)\Gamma(n-s+1)} e^\gamma \left( \frac{e^\gamma}{1+e^\gamma} \right)^s \left( \frac{1}{1+e^\gamma} \right)^{n-s}$$

## Types of Priors

The big question in Bayesian analysis is where does the prior come from in a general problem.

Subjective prior  
e.g.  , normal distribution

vs. Non-informative prior  
e.g.  , flat, uniform pdf

Improper prior: Let  $x | \mu \sim N(\mu, \sigma^2)$ ,  $\sigma^2$  is known.

Set a flat prior on  $\mu$ :  $f(\mu) = c > 0$ .

$$\Rightarrow \int_{-\infty}^{\infty} f(\mu) d\mu = \infty \leftarrow \text{not a prob. density. } \boxed{6}$$

This is known as an improper prior, but Bayes can formally be carried out:

$$\begin{aligned}
 f(\mu|x) &= \frac{\mathcal{L}(\mu) \cdot f(\mu)}{\int \mathcal{L}(\mu) \cdot f(\mu) d\mu} \\
 &= \frac{\mathcal{L}(\mu) \cdot \cancel{c}}{\int \mathcal{L}(\mu) \cdot \cancel{c} d\mu} = \frac{\mathcal{L}(\mu)}{\int \mathcal{L}(\mu) d\mu} \\
 &\quad \searrow \int_{-\infty}^{\infty} \frac{e^{-(x-\mu)^2/2\sigma^2}}{\sqrt{2\pi}\sigma} d\mu = 1 \\
 \Rightarrow \mu|x &\sim N(x, \sigma^2)
 \end{aligned}$$

In general, improper priors are not a problem so long as  $f(x|\theta)$  decays fast enough as a function of  $\theta$ .

Flat priors are not transformation invariant

Logically, if we know nothing about a parameter  $p$ , then we should also know nothing about  $\psi = \log\left(\frac{p}{1-p}\right)$ , but  $f(p)=1 \Rightarrow f(\psi) \neq 1$ . Contradiction?

My interpretation: flat priors do not mean non-informative.

## Jeffrey's Prior

$$\text{Set } f(\theta) \propto \sqrt{I(\theta)}$$

↖ Fisher information

The Jeffrey's Prior is transformation invariant.

If  $\tau = g(\theta)$ , then what does the prior for  $\tau$  look like?

$$I(\theta) = -\mathbb{E} \left( \frac{\partial^2}{\partial \theta^2} \log f(\bar{x}; \theta) \right)$$

↘ statistical model.

$$= -\mathbb{E} \left( \left( \frac{d\tau}{d\theta} \right)^2 \frac{\partial^2}{\partial \tau^2} \log f(\bar{x}; \tau) \right)$$

$$= - \left( \frac{d\tau}{d\theta} \right)^2 \mathbb{E} \left( \frac{\partial^2}{\partial \tau^2} \log f(\bar{x}; \tau) \right)$$

$$= \left( \frac{d\tau}{d\theta} \right)^2 I(\tau)$$

$$\Rightarrow \sqrt{I(\theta)} = \sqrt{I(\tau)} \left| \frac{d\tau}{d\theta} \right|$$

This is the usual change of variables formula.