

DIVERGENCE

Definition. $\vec{F}(x, y, z)$ is a vector field defined in a neighbourhood of $(x_0, y_0, z_0) \in \mathbb{R}^3$, V is a solid with (x_0, y_0, z_0) in its interior, $\partial V = \vec{S}$ is outward oriented. Define the divergence of $\vec{F}(x, y, z)$ at (x_0, y_0, z_0) to be:

$$\operatorname{div} \vec{F}(x_0, y_0, z_0) = \lim_{V \rightarrow 0} \frac{1}{V} \oiint_S \vec{F} \cdot d\vec{S}$$

So as (x_0, y_0, z_0) varies around, we obtain a scalar function $\operatorname{div} \vec{F}$.

Proposition. (i) If λ and μ are constants, \vec{F} and \vec{G} are vector fields, then

$$\operatorname{div}(\lambda \vec{F} + \mu \vec{G}) = \lambda \operatorname{div}(\vec{F}) + \mu \operatorname{div}(\vec{G})$$

(ii) If f is a scalar function and \vec{u} is a constant vector, then

$$\operatorname{div}(f\vec{u}) = \vec{u} \cdot \nabla f$$

Proof. (i) Follows directly from the distributive law of dot product.

$$(ii) \operatorname{div}(f\vec{u}) = \lim_{V \rightarrow 0} \frac{1}{V} \oiint_S (f\vec{u}) \cdot d\vec{S} = \lim_{V \rightarrow 0} \frac{1}{V} \vec{u} \cdot \oiint_S f d\vec{S}$$

$$= \vec{u} \cdot \lim_{V \rightarrow 0} \frac{1}{V} \oiint_S f d\vec{S}$$

$$= \vec{u} \cdot \nabla f$$

Proposition. If $\vec{F}(x, y, z) = (P(x, y, z), Q(x, y, z), R(x, y, z))$ is a vector field, then $\text{div} \vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$

So formally we write $\text{div} \vec{F} = \vec{\nabla} \cdot \vec{F}$.

Proof $\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k}$.

$$\begin{aligned} \text{div} \vec{F} &= \text{div}(P\hat{i} + Q\hat{j} + R\hat{k}) \\ &= \text{div}(P\hat{i}) + \text{div}(Q\hat{j}) + \text{div}(R\hat{k}) \\ &= \nabla P \cdot \hat{i} + \nabla Q \cdot \hat{j} + \nabla R \cdot \hat{k} \\ &= \left(\frac{\partial P}{\partial x}, \frac{\partial P}{\partial y}, \frac{\partial P}{\partial z}\right) \cdot (1, 0, 0) + \left(\frac{\partial Q}{\partial x}, \frac{\partial Q}{\partial y}, \frac{\partial Q}{\partial z}\right) \cdot (0, 1, 0) \\ &\quad + \left(\frac{\partial R}{\partial x}, \frac{\partial R}{\partial y}, \frac{\partial R}{\partial z}\right) \cdot (0, 0, 1) \\ &= \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \end{aligned}$$

Proposition. $\text{div}(\text{curl} \vec{F}) = 0$

Proof. $\text{div}(\text{curl} \vec{F}) = \text{div}(R_y - Q_z, P_z - R_x, Q_x - P_y)$

$$\begin{aligned} &= R_{yx} - Q_{zx} + P_{zy} - R_{xy} + Q_{xz} - P_{yz} \\ &= 0 \end{aligned}$$

Definition. If f is a scalar function, define the Laplacian of f to be $\Delta f = \vec{\nabla} \cdot (\vec{\nabla} f) = \text{div}(\nabla f)$

$$= \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

Exercise. Show that $\Delta(fg) = f\Delta g + g\Delta f + 2\nabla f \cdot \nabla g$

GAUSS' THEOREM (DIVERGENCE THEOREM)

Theorem: V is a solid with boundary $\partial V = \vec{S}$ outward oriented.
 \vec{F} is a vector field defined on a region containing V .
 Then:

$$\iiint_V \operatorname{div} \vec{F} dV = \oiint_S \vec{F} \cdot d\vec{S}$$

Proof. By the definition of $\operatorname{div} \vec{F} = \lim_{V \rightarrow 0} \frac{1}{V} \oiint_S \vec{F} \cdot d\vec{S}$

$$\text{For each } (x_0, y_0, z_0), \operatorname{div} \vec{F}(x_0, y_0, z_0) = \frac{1}{V} \oiint_S \vec{F} \cdot d\vec{S} + \epsilon(V)$$

and $\epsilon(V) \rightarrow 0$ as $V \rightarrow 0$.

$$\text{so } \operatorname{div} \vec{F}(x, y, z) V = \oiint_S \vec{F} \cdot d\vec{S} + V \epsilon(V)$$

$$\begin{aligned} \iiint_V \operatorname{div} \vec{F} dV &= \lim_{\max \Delta V_i \rightarrow 0} \sum \operatorname{div} \vec{F}(x_i^*, y_i^*, z_i^*) \Delta V_i \\ &= \lim_{\max \Delta V_i \rightarrow 0} \sum \frac{\oiint_{\Delta V_i} \vec{F} \cdot d\vec{S}}{\Delta V_i} + \Delta V_i \epsilon(\Delta V_i) \end{aligned}$$

$$\begin{aligned} (*) \quad &\downarrow \\ &= \sum_{\Delta V_i} \oiint_{\Delta V_i} \vec{F} \cdot d\vec{S} \\ &= \oiint_S \vec{F} \cdot d\vec{S} \end{aligned}$$

$$\begin{aligned} (*) \text{ is because } \left| \sum_{\Delta V_i} \Delta V_i \cdot \epsilon(\Delta V_i) \right| &\leq \left| \max \epsilon(\Delta V_i) \right| \sum_{\Delta V_i} \Delta V_i \\ &= \left| \max \epsilon(\Delta V_i) \right| V \rightarrow 0 \end{aligned}$$

Corollary. $\iiint_V \nabla f \, dV = \oint_{\partial V} f \, d\vec{S}$. for a solid V .

Proof. For any constant vector \vec{u} , apply Gauss theorem to $f\vec{u}$.

$$\iiint_V \operatorname{div}(f\vec{u}) \, dV = \oint_{\partial V} (f\vec{u}) \cdot d\vec{S}$$

$$\iiint_V \vec{u} \cdot \nabla f \, dV = \oint_{\partial V} \vec{u} \cdot (f\hat{n}) \, dS$$

$$\vec{u} \cdot \iiint_V \nabla f \, dV = \vec{u} \cdot \oint_{\partial V} f \, d\vec{S}$$

Since this holds for all $\vec{u} \in \mathbb{R}^3$, we conclude

$$\iiint_V \nabla f \, dV = \oint_{\partial V} f \, d\vec{S}$$

Corollary. If \vec{S} is a closed surface, $\oint_S 1 \, d\vec{S} = \vec{0}$

Corollary. If \vec{S} is a closed surface, $\oint_S \operatorname{curl} \vec{F} \cdot d\vec{S} = 0$ for any vector field \vec{F} .

Proof. $\oint_S \operatorname{curl} \vec{F} \cdot d\vec{S} = \iiint_V \operatorname{div}(\operatorname{curl} \vec{F}) \, dV = \iiint_V 0 \, dV = 0$

Example. Evaluate $\oint_S (3x, 2y, z) \cdot d\vec{S}$ where \vec{S} is the unit sphere with centre $(0, 0, 0)$.

$$\begin{aligned} \oint_S (3x, 2y, z) \cdot d\vec{S} &= \iiint_B \frac{\partial(3x)}{\partial x} + \frac{\partial(2y)}{\partial y} + \frac{\partial(z)}{\partial z} dV \\ &= \iiint_B 6 dV \\ &= 6 \iiint_B 1 dV \\ &= 6 \cdot \frac{4}{3}\pi \\ &= 8\pi \end{aligned}$$

Remark. The Green's Theorem can also be viewed as a special case of Gauss' Theorem:

If we parameterize a simple closed curve C on \mathbb{R}^2 by $\vec{r}(t) = (x(t), y(t))$, then let $\hat{n}(t) = \frac{1}{|\vec{r}'(t)|} \cdot (y'(t), -x'(t))$, $\hat{n}(t)$ is the unit normal vector of C at $\vec{r}(t)$ pointing outward.

$S = s(t) = \int_a^t |\vec{r}'(\tau)| d\tau$ is the arclength, then the Green's Theorem implies:

$$\begin{aligned} \oint_C \vec{F} \cdot \hat{n} ds &= \int_a^b \vec{F}(\vec{r}(t)) \cdot \hat{n}(t) |\vec{r}'(t)| dt \\ &= \int_a^b \frac{1}{|\vec{r}'(t)|} \cdot (P(\vec{r}(t))y'(t) - Q(\vec{r}(t))x'(t)) \cdot |\vec{r}'(t)| dt \\ &= \oint_C P dy - Q dx \\ &= \oint_C (-Q, P) \cdot d\vec{r} = \iint_D P_x + Q_y dA = \iint_D \operatorname{div} \vec{F} dA \end{aligned}$$