

1 **The rain is askew: Two idealized models relating vertical velocity and**
2 **precipitation distributions in a warming world**

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ABSTRACT

12 As the planet warms, climate models predict that rain will become heavier
13 but less frequent, and that the circulation will weaken. Here, two heuristic
14 models relating moisture, vertical velocity, and rainfall distributions are de-
15 veloped, one in which the distribution of vertical velocity is prescribed and
16 another in which it is predicted. These models are used to explore the re-
17 sponse to warming and moistening, changes in the circulation, atmospheric
18 energy budget, and stability. Some key assumptions of the models include that
19 relative humidity is fixed within and between climate states and that stability
20 is constant within each climate state. The first model shows that an increase
21 in skewness of the vertical velocity distribution is crucial for capturing salient
22 characteristics of the changing distribution of rain, including the muted rate of
23 mean precipitation increase relative to extremes and the decrease in the total
24 number or area of rain events. The second model suggests that this increase
25 in the skewness of the vertical velocity arises from the asymmetric impact of
26 latent heating on vertical motion.

27 **1. Introduction**

28 Changes in rain are inexorably tied to changes in atmospheric circulation. In response to global
29 warming, climate model projections show an increase in global-mean precipitation, the rate of
30 which is in balance with the change in atmospheric radiative cooling (O’Gorman et al. 2012;
31 Pendergrass and Hartmann 2014a). This rate of increase, 1-3% per degree of warming across
32 climate models, is smaller than the rate of increase of moisture in the atmosphere, which roughly
33 follows saturation vapor pressure at $\sim 7\%K^{-1}$ (Held and Soden 2006). The difference between the
34 rates of increase of moisture and precipitation with warming imply a slowing of the atmospheric
35 overturning circulation (Betts 1998). The weakening circulation in climate model projections
36 manifests as a decrease in spatial variance of convective mass flux (Held and Soden 2006) and the
37 Walker circulation (the anti-symmetric component of variance of 500 hPa vertical velocity in the
38 tropics, Vecchi and Soden 2007).

39 Along with changes in circulation, climate models project substantial changes in the distribution
40 of rainfall, as shown in Fig. 1. The rain frequency distribution (Fig. 1a) shows how often it rains at
41 any particular rain rate. It is displayed on a logarithmic rain-rate scale in order to accommodate the
42 full range of rain rates that can be encountered, which encompasses orders of magnitude. The rain
43 amount distribution (Fig. 1b) shows how much rain falls at a particular rain rate. These calculations
44 are based on the mean of the Coupled Model Intercomparison Project version 5 (CMIP5, Taylor
45 et al. 2012) models and are described in more detail in Pendergrass and Hartmann (2014b). Figures
46 1c,d show the multi-model mean changes in the rain frequency and rain amount distributions
47 in response to a doubling of carbon dioxide in a scenario where carbon dioxide concentrations
48 increase by 1% each year. The rain frequency response to warming (Fig. 1c) is an increase in days
49 with heavy rain, a larger decrease in days with moderate rain, a small (statistically insignificant)

50 increase in days with light rain, and a small (statistically significant) increase in the number of dry
51 days (noted at the top left of the panel). The rain amount response (Fig. 1d) is an increase in rain
52 falling at heavy rain rates and a smaller decrease in rain falling at moderate rain rates, comprising
53 an increase in the total amount of precipitation.

54 Pendergrass and Hartmann (2014c) found that these changes in the distribution of rainfall in
55 response to warming (as well as those arising in response to El Niño and La Nina phases of
56 ENSO) in models can be well described by two empirically-derived patterns, denoted the “shift”
57 and “increase” modes, which are illustrated in Fig. 2. Each mode describes a simple adjustment
58 to the climatological distribution of rain. A combination of the shift and increase modes (chosen
59 with an algorithm to optimize the fit to the change in rain amount distribution) captures most of
60 the response in most climate model simulations of global warming, and the entire change in some
61 models.

62 The “increase” mode (Fig. 2a,b) characterizes an increase in the frequency of rain by the same
63 fraction at all rain rates. The bell shape of this mode simply follows the climatological distribution
64 of rain frequency. While the change in rain amount is characterized by a similar bell-shaped
65 pattern, it occurs at higher rain rates (Fig. 2b). The total amount of rain is the product of the rain
66 frequency and rain rate, such that an increase in rain frequency at higher rain rates has a larger
67 impact on the total precipitation than it does at lower rain rates. An increase in rain frequency
68 implies a reduction in the number of dry days. In the global mean, it rains about half of the time,
69 such that a one percent increase at all rain rates is associated with a one-half percent reduction in
70 dry days.

71 The “shift” mode (Fig. 2c,d) characterizes a movement of the distribution of rain to higher rain
72 rates, but with no net increase in the total rain amount. It is defined as a shift of the rain amount
73 distribution (Fig. 2d); the corresponding change in the rain frequency distribution can also be

74 obtained (Fig. 2c). A larger decrease in the frequency of light rain events is needed to offset the
75 smaller increase in the frequency of strong rain events on total precipitation, hence the shift mode
76 is associated with an increase in the number of dry days. For a one percent increase in the shift
77 mode, the total number of dry days increases by about one-half of a percent.

78 Pendergrass and Hartmann (2014b) determined that the shift and increase mode magnitudes that
79 optimally capture the change in the multi-model mean rain amount distribution in Fig. 1d is a shift
80 mode of $3.3 \%K^{-1}$ along with an increase mode of $0.9 \%K^{-1}$. Figure 2e,f show the change in
81 rain frequency and amount distributions for this combination of shift and increase modes. The
82 response of the shift mode is larger than the increase mode, such that there is a modest increase in
83 the frequency of dry days.

84 Not all of the change in the distribution of rain in climate models is captured by the shift and
85 increase modes. Pendergrass and Hartmann (2014c) identified two additional aspects of the chang-
86 ing distribution of rain common to many models: the light rain mode and the extreme mode. The
87 light rain mode is the small increase in rain frequency just below 1 mm d^{-1} visible in Fig. 1c, also
88 evident in Lau et al. (2013). The extreme mode represents additional increases in rain at the heav-
89 iest rain rates, beyond what is captured by the shift and increase modes. It is crucial for capturing
90 the response of extreme precipitation to warming.

91 Changes in moisture, circulation, and the distribution of rain in response to warming are related.
92 Indeed, the changes in the intensity of extreme rain events in climate model projections of global
93 warming can be linearly related to changes in moisture and vertical velocity in most models and
94 regions (Emori and Brown 2005; O’Gorman and Schneider 2009; Chou et al. 2012). This moti-
95 vates us to consider whether we can understand the changing distribution of rain in terms of the
96 changes in moisture and vertical velocity distributions, constituting a physically based, rather than
97 empirically derived, approach.

98 One might assume that changes in the distribution of rain are complex. The distribution of rain
99 (particularly the global distribution) is generated by a number of different types of precipitating
100 systems, each of which is driven by somewhat different mechanisms and might respond differently
101 to external forcing. For example, it would not be surprising if midlatitude cyclones and tropical
102 convection responded differently to global warming. On the other hand, we expect many aspects of
103 the response to warming to be fairly straightforward: warming along with moistening at a relative
104 humidity that stays constant on surfaces of constant temperature (Romps 2014).

105 In this study, we approach the relationships among changes in moisture, vertical velocity, and
106 rain by examining the response to straightforward changes of simple statistical distributions. We
107 develop two heuristic models that predict the distribution of rain from moisture and vertical veloc-
108 ity distributions. We will see that despite the potential for complexity among these relationships,
109 we can recover many aspects of the changes in rainfall and vertical velocity we see in climate
110 models in an idealized setting.

111 In Section 2, we introduce the first model, in which distributions of moisture and vertical velocity
112 are prescribed. We use the model to explore how the distribution of rain responds to warming and
113 moistening, and to changes in the strength and asymmetry (or skewness) of the vertical velocity
114 distribution. Then, in Section 3, we introduce a second model that predicts the vertical velocity
115 distribution in order to understand its changes in concert with those of the distribution of rain.
116 In Section 4, we show that climate model simulations also have increasing skewness of vertical
117 velocity with warming. Finally, we consider the implications of the increasing skewness of vertical
118 velocity on convective area in Section 5 and conclude our study in Section 6.

119 **2. The first model: Prescribed vertical velocity**

120 We know rain is a result of very complex processes, many of which are parameterized rather than
121 explicitly modeled in climate models. At the most basic level, rain is regulated by two processes:
122 (1) the moisture content, which is tied to the temperature structure, assuming constant relative
123 humidity, and (2) the magnitude of upward vertical velocity. Instead of considering variability
124 in space, consider a distribution that captures the structure of all regions globally. Furthermore,
125 neglect concerns about the vertical structure of the motion or the structure of the atmosphere, and
126 consider only the vertical flux of moisture through the cloud base.

127 The key – and gross – simplification of this model is that we will assume that the vertical velocity
128 is *independent* of the temperature and moisture content, so we can model these as two independent
129 distributions. We know this is not the case – upward velocity is often driven by convection, which
130 occurs where surface temperature is warm – but for now we will see what insight can be gleaned
131 with this assumption.

132 *a. Model description*

133 Our first model is driven by two prescribed, independent, Gaussian (normal) distributions: one
134 for temperature, $N(\bar{T}, \sigma_T)$, where \bar{T} is the mean temperature and σ_T is width of the temperature
135 distribution, and another for vertical velocity, $N(\bar{w}, \sigma_w)$, where \bar{w} is the mean vertical velocity
136 (equal to zero when mass is conserved) and σ_w is the width of the w distribution. The tempera-
137 ture distribution, with the assumption of constant relative humidity, in turn gives us the moisture
138 distribution. We calculate moisture q ,

$$q(T) = q_0 e^{0.07T}, \quad (1)$$

139 where q_0 is chosen so that $q(T)$ is equal to its Clausius-Clapeyron value at $T = 287$ K. This
 140 equation is very similar to Clausius-Clapeyron, except that here $dq/dT = 7 \text{ \%K}^{-1}$ exactly. The
 141 implied relative humidity is fixed at 100%. The choice of 100% relative humidity is arbitrary, but
 142 any non-zero choice that is held constant will result in the same behavior.

143 We suppose that it rains whenever vertical velocity w is positive (upward), with a rain rate equal
 144 to the product of the moisture, vertical velocity, and air density ρ_a (held constant at 1.225 kg m^{-3} ,
 145 its value at sea level and 15°C),

$$r(q, w) = \begin{cases} \rho_a w q, & w > 0 \\ 0, & w \leq 0. \end{cases} \quad (2)$$

146 This is analogous to saying that the rain rate is equal to the flux of moisture across the cloud base.
 147 While this is a gross simplification, it would hold if the column were saturated and the temperature
 148 structure fixed, and the air was lifted to a level where the saturation specific humidity is effectively
 149 zero. In this limit, any moisture advected upward will lead to supersaturation and rain from above.
 150 Neglecting the impact of condensation on the temperature is a similarly coarse approximation as
 151 our assumption that the temperature and vertical velocity are independent.

152 The rain frequency distribution is obtained by integrating across the distributions of T (which
 153 determines q by Eqn. 1) and w ,

$$p(r) = \int_0^\infty \int_{-\infty}^\infty \int_{-\infty}^\infty \delta(r - \rho_a w q) p(T) p(w) dT dw dr, \quad (3)$$

154 where $p(T)$ and $p(w)$ are Gaussian probability density functions and δ is a Dirac delta function.
155 The rain amount distribution is then,

$$P(r) = r p(r). \quad (4)$$

156 In practice, $p(r)$ and $P(r)$ are computed over a discrete set of bins. Because the rain rate varies over
157 several orders of magnitude, the bins are spaced evenly on a logarithmic scale for proper sampling;
158 the bin width defined in logarithmic space is $\Delta \ln r = \Delta r_i / r_i$, where r_i is the rain rate and Δr_i is the
159 linear bin width for the i th bin. We then work with the frequency of rain events corresponding to
160 each bin, $p(r_i)\Delta r_i$. To maintain the property that the area under the displayed distribution curves
161 accurately represents the contribution of each rain rate to the total integral when displayed on a
162 logarithmic scale, our plots show $r_i p(r_i) = p(r_i)\Delta r_i / \Delta \ln r$.

163 Lastly, we must specify the parameters governing the temperature and vertical velocity distribu-
164 tions, which are listed in Table 1 for reference. For temperature (shown in Fig. 3a) we take \bar{T} to
165 be 287 K and its standard deviation $\sigma_T = 16$ K, both chosen to match the surface air temperature
166 distribution in a climate model. The vertical velocity distribution (shown in Fig. 3b) must have
167 a mean $\bar{w} = 0$ if mass is to be conserved. Given the temperature distribution above, the standard
168 deviation of w will ultimately set the total precipitation. Thus we sought to constrain its value so as
169 to capture the total precipitation in climate models and observational datasets (see Pendergrass and
170 Hartmann 2014c), while at the same time being consistent with the vertical velocity distribution
171 in climate models. Studies such as Emori and Brown (2005) show that rain frequency changes are
172 linearly related to changes in moisture and 500 hPa vertical velocity in many climate models for
173 most regions. While vertical velocity at cloud base rather than 500 hPa would be more closely
174 physically related to our conceptual model, it is not archived for these climate model integrations.

175 The rain frequency distribution (shown in Fig. 3c) is calculated numerically following the de-
176 scription in Appendix A. It is dry exactly 50% of the time, since the vertical velocity distribution
177 is symmetric about zero. The peak of the rain frequency distribution occurs at just under 10 mm
178 d^{-1} . The rain amount distribution (Fig. 3d) shows how much rain falls in each rain rate bin. The
179 peak of the rain amount distribution occurs at a rain rate about an order of magnitude larger than
180 for the rain frequency distribution.

181 These distributions resemble those in observational datasets and climate models to the correct
182 order of magnitude – compare to Fig. 1a,b and Pendergrass and Hartmann (2014c) – despite the
183 crude assumptions of our model. The main deficiency of our model compared to climate models
184 is a lack of precipitation at light rain rates, and a corresponding overestimation of dry-day fre-
185 quency. However, climate models underestimate the dry-day frequency by about a factor of two
186 compared to GPCP 1DD and TRMM 3B42 merged satellite-gauge gridded daily observational
187 datasets (Pendergrass and Hartmann 2014c). The implications of this discrepancy on the rain
188 amount distribution are nonetheless small because light rain contributes less than heavy rain does
189 to the total precipitation, so that distribution of rain amount appears better than rain frequency
190 qualitatively (compare Figs. 1b and 3d).

191 The goal in developing this toy model is to explore what happens in response to perturbations:
192 warming and moistening, weakening of the circulation, and introducing skewness to the vertical
193 velocity distribution. We consider these next.

194 *b. Response to warming and moistening*

195 We approximate warming by simply shifting the mean of the temperature distribution \bar{T} 1 K
196 higher. We keep σ_T constant, assuming no change in the variance of temperature. The moisture
197 distribution adjusts accordingly. We maintain the same w distribution and calculate the distribution

198 of rain in the warmed climate. The difference between the distributions of rain frequency and
199 amount in the warmed and initial climates are shown in Fig. 4a-c. There is no change in the total
200 frequency of rain, and the total amount of rainfall increases by $7 \%K^{-1}$, exactly following the
201 change in moisture.

202 The rainfall distribution response to warming is equivalent to moving the rain frequency distri-
203 bution to the right by exactly $7 \%K^{-1}$, or having equal shift and increase modes of $7 \%K^{-1}$ (the
204 fitted shift and increase modes are listed in Table 2), as in Fig. 2g,h. In contrast to this warm-
205 ing experiment, in climate model simulations of global warming the shift mode response is larger
206 than that of the increase mode, and total precipitation increases more slowly than moisture. This
207 exposes a flaw: circulation also adjusts to changes in climate, which is not captured by this first
208 experiment. In climate model projections, circulation adjusts to satisfy the energetic constraints
209 of the climate system, including the constraint that precipitation (in the global mean) can only
210 increase as much as atmospheric radiative cooling and sensible heat flux allow (e.g. Allen and
211 Ingram 2002).

212 *c. Response to weakening circulation*

213 A weakening of the atmospheric overturning circulation can be effected in our model by reduc-
214 ing the width of the vertical velocity distribution, σ_w . For our second experiment, we decrease
215 the standard deviation of w by 4%, using the initial (not warmed) distribution of temperature and
216 moisture. The change in the distribution of rain is shown in Fig. 4d-f.

217 Again, there is no change in the dry frequency, and the total amount of rainfall decreases by 4%,
218 the same amount that we weakened the width of the vertical velocity distribution by. Decreasing
219 the width of the vertical velocity distribution results in a shift of the rain frequency distribution to
220 lower rain rates. In fact, narrowing the w distribution by 7% would exactly cancel the effect of

221 warming by 1 K. We can understand this by considering Eqn. 2 or 3: warming by 1 K increases q
222 by 7%, whereas widening the vertical velocity distribution increases w by 7%. The effect of either
223 change on r is the same.

224 We have just seen that neither warming nor changing the strength of the circulation affects the
225 dry frequency, or the symmetry between the rates of change of mean and extreme rainfall. Changes
226 analogous to those we see in climate model simulations thus cannot result from either warming
227 at constant relative humidity or weakening circulation alone. But what if the circulation becomes
228 more asymmetric?

229 *d. Response to changing skewness of vertical velocity*

230 The first moment of the vertical velocity distribution, its mean, must be fixed at zero to maintain
231 mass conservation. We have just seen that changing the second moment (standard deviation or
232 variance) does not cause the changes in the distribution of rain that we see in climate models.
233 We now turn to the third moment, skewness, which measures the asymmetry of a distribution.
234 Skewness, a key quantity, is attended to more widely in the parts of atmospheric sciences dealing
235 with turbulence, like boundary layer meteorology. It has also received some limited attention
236 in climate recently. Monahan (2004) discusses skewness of low-level wind speed arising from
237 surface drag. Luxford and Woollings (2012) discuss how skewness arises in geopotential height
238 from kinematic fluctuations of the jet stream. Sardeshmukh et al. (2015) incorporate skewness
239 into a non-linear model for atmospheric fields including precipitation. In particular, they highlight
240 the skewness in the vertical velocity field.

241 Skewness can arise in vertical motion from the asymmetric effect of latent heating. To visualize
242 this effect, picture a developing thunderstorm. The cumulus cloud grows because an updraft is
243 heated when water vapor condenses, sustaining or even strengthening the updraft and eventually

244 resulting in rainfall. Over the life of the thunderstorm, some of this rainfall will re-evaporate, but
245 there will be a net latent heating of the atmosphere due to the formation of this thunderstorm equal
246 to the amount of rainfall that reaches the ground. There is no corresponding effect of latent heating
247 on subsiding air; it merely warms adiabatically as it sinks.

248 To incorporate skewness into the vertical velocity distribution, we draw w from a skew-normal
249 distribution generated following Azzalini and Capitanio (1999), instead of from a normal distri-
250 bution as before. A skew-normal distribution has three degrees of freedom which determine its
251 mean, variance, and asymmetry. When the asymmetry is zero, the skew-normal distribution be-
252 comes normal. We adjust the skew-normal distribution so that the mean is always zero to maintain
253 mass conservation, and we maintain a constant variance of the w distribution to eliminate the ef-
254 fects of changing circulation strength. The resulting distribution of w and the response in rain
255 frequency and amount distributions to a 0.2 increase in skewness are shown in Fig. 4g-i.

256 The responses of the rain frequency and amount distributions to increasing skewness of the
257 vertical velocity have some intriguing features. There is a notable decrease in the frequency of
258 rain for moderate rain rates (Fig. 4h), but the total amount of rain remains essentially constant due
259 to a slight increase in the frequency of higher rain rates (Fig. 4i). This strongly resembles the shift
260 mode. The magnitude of the strongest updrafts also changes little. Increasing skewness without
261 conserving the mean of w would increase the strength of the strongest updrafts, but the shift of the
262 distribution to maintain mass continuity compensates for this.

263 To move toward the response of precipitation to global warming in climate models, we simul-
264 taneously warm and increase the skewness of the vertical velocity distribution, shown in Fig. 4j-l.
265 The response of the rain frequency and amount distributions to warming and skewing has all the
266 features seen in climate models: a decrease in the total rain frequency and in the frequency of
267 rain falling at moderate rain rates, along with an increase in rain amount focused at the heaviest

268 rain rates. Increasing the skewness of the vertical velocity distribution effects crucial components
269 of the change. It decreases the total frequency of rain events, breaks the symmetry between the
270 changes in mean and extreme rainfall, and allows us to change the magnitude of the shift mode
271 without changing the increase mode.

272 To fully capture the changes we see in climate model simulations, we weaken the distribution
273 of vertical velocity (decrease σ_w) while simultaneously increasing its skewness and increasing \bar{T} ,
274 shown in Fig. 4m-o. Here we see many of the same features as before, but now we also have the
275 decrease in mean rainfall that arises from the weakening circulation, giving us shift and increase
276 modes of roughly the same magnitude as we see in climate models.

277 To recap, we have shown that warming (increasing \bar{T}) results in shift and increase modes of equal
278 magnitude, while increasing the skewness of the vertical velocity distribution produces the shift
279 mode alone, allowing us to reproduce some salient features of the response of the rain distribution
280 to warming projected by climate models. This motivates us to construct a model that predicts ver-
281 tical velocity to understand how atmospheric energetic constraints lead to the increasing skewness
282 of the vertical velocity distribution with warming.

283 **3. The second model: Predicted vertical velocity**

284 We know that precipitation is energetically constrained by total column heating and cooling.
285 Thus, in this model we start with energetics. We prescribe a distribution of non-latent heating
286 Q_n , which is the sum of radiative and sensible heating and the convergence of dry static energy
287 flux in the atmospheric column (see Muller and O’Gorman 2011). In the time mean, \bar{Q}_n balances
288 the latent heating, and so relates to the total precipitation. In daily fields from the MPI-ESM-LR
289 climate model, the width of the atmospheric radiative cooling distribution is small compared with
290 that of the atmospheric column dry static energy flux convergence, so the standard deviation of

291 the non-latent heating distribution, σ_{Q_n} , comes primarily from the convergence of the dry static
292 energy flux. The distribution of \overline{Q}_n thus captures both the impact of radiation and the transport of
293 energy by the circulation.

294 *a. Model description*

295 Our goal is to predict the distribution of w , which will in turn give us the rainfall from Eqn. 2,
296 as in our first model. We begin with the temperature and moisture distributions (again connected
297 by the assumption of saturation, Fig. 5a), except that the tail of the temperature distribution is
298 truncated at a maximum temperature, T_{max} , which in turn implies a maximum allowable moisture
299 content. We then assume that the non-latent atmospheric column heating, Q_n (Fig. 5b), can be de-
300 scribed by another independent Gaussian distribution. The sum of non-latent atmospheric column
301 heating and latent heating from precipitation must be zero in the time mean to maintain energy
302 conservation.

303 We calculate the distributions of vertical velocity and rain according to a form of the thermody-
304 namic equation (inspired by Sobel and Bretherton 2000),

$$wS = Q_n + Q_l, \quad (5)$$

305 where the parameter S is a constant that converts energy to vertical motion. In Sobel and Brether-
306 ton (2000), S is a stability that varies in time and space, but here we assume it is a constant to
307 maintain the mathematical simplicity of the model. Physically, this equation implies that the total
308 atmospheric column heating (both latent, Q_l , and non-latent Q_n) exactly balances the energy re-
309 quired to move air (w) against stability S . This balance holds in the time mean in the real world,
310 but here we enforce it at all times.

311 We calculate the latent heating Q_l from the moisture and vertical velocity when it is raining (as
312 in the first model),

$$Q_l = L\rho_a wq, \quad (6)$$

313 where L is the latent heat of vaporization of water (which we hold constant at $2.5 \times 10^{-6} \text{ J kg}^{-1}$, its
314 value at 0°C) and ρ_a is the air density as in the first model. With substitution, we have an equation
315 for vertical velocity,

$$w = \begin{cases} \frac{Q_n}{S}, & Q_n \leq 0 \\ \frac{Q_n}{S-L\rho_a q}, & Q_n > 0. \end{cases} \quad (7)$$

316 To conserve mass, the average vertical velocity must equal zero, as in the first model, and to con-
317 serve energy, the mean latent heating Q_l must be equal and opposite to the mean non-latent heating
318 Q_n . These balances are effected by integral constraints based on Eqn. 5, derived in Appendix B.

319 The parameters we use are listed in Table 3. The mean of the non-latent atmospheric column
320 heating is equal but opposite to the CMIP5 multi-model mean precipitation (88 W m^{-2}), and its
321 standard deviation is dominated by variability in the dry static energy flux convergence on short
322 time scales (following Muller and O’Gorman 2011); we choose a value similar to those we found
323 in climate model integrations.

324 Truncating the temperature distribution is necessary to ensure that the denominator in Eqn. 7
325 never drops to or below zero, which would result in infinite w . T_{max} can be interpreted as an upper
326 bound on SST, which is enforced by convection in the real world (Sud et al. 1999; Williams et al.
327 2009).

328 In addition to our choice of \overline{Q}_n , we also choose \overline{T} , σ_T , T_{max} , and σ_{Q_n} values that are plausibly
329 realistic or comparable to calculations using daily data from the MPI-ESM-LR climate model. The
330 other requirement to maintain a positive-definite denominator in Eqn. 7 is that S must be greater
331 than $L\rho_a q(T_{max})$. In this way, the minimum possible choice of the parameter S is tied to T_{max} . With
332 a realistic temperature and moisture distribution and a constant S , the minimum allowable value
333 of S is much larger than observed values of static stability (see e.g., Jukes 2000).

334 The distributions of vertical velocity and rain produced by our model with the parameters listed
335 in Table 3 are shown in Fig. 5c-e. As with the first model, the distributions of rain frequency and
336 amount are qualitatively similar to observations and climate model simulations in terms of both
337 the peak magnitudes and overall structure.

338 Most importantly, the model predicts a skewed distribution of w . To ensure that the skewness
339 was not an artifact of the non-zero mean of the non-latent heating distribution, we specified $\overline{Q}_n =$
340 0 (thereby neglecting energy and mass balance) in an alternative calculation (not shown), and
341 the positive skewness remained. Rather, the skewness arises from the asymmetry introduced by
342 latent heating, as can be seen in Eqn. 7. Atmospheric column cooling ($Q_n < 0$) causes downward
343 velocity, with a magnitude linearly related to Q_n , since S is constant. But atmospheric heating
344 ($Q_n > 0$) induces upward motion and also condensation. The resulting latent heating effectively
345 weakens the stability, and w is thus no longer simply proportional to Q_n , but grows super-linearly
346 with Q_n .

347 *b. Perturbations about the control climate*

348 Here we explore the responses to the three parameters other than warming: mean non-latent
349 heating \overline{Q}_n , the width of non-latent heating σ_{Q_n} , and stability S . To maintain mass and energy
350 conservation, when one parameter changes, it must be compensated by a change in at least one

351 other parameter. The amplitude of the parameter changes described in this section were chosen so
352 they can be compared with the next set of experiments, where we warm by 3 K. This is a fairly
353 linear regime where the results are not highly sensitive to the amplitude of the perturbations.

354 In the first experiment, we increase the magnitude of mean non-latent heating \bar{Q}_n by 24 W m^{-2}
355 to 113 W m^{-2} and balance it by widening the non-latent heating distribution (allowing σ_{Q_n} to
356 increase by 27.5%, equivalent to increasing the strength of heat transport convergence). Details
357 of how we carry out the variation of the parameters are discussed in Appendix A. The resulting
358 distribution of vertical velocity and the changes in rain amount and rain frequency are shown in
359 Fig. 6a-c. The vertical velocity distribution has widened, with no change in skewness. The rain
360 frequency distribution shifts to heavier rain rates, with no change in the dry frequency, and thus
361 no change in total rain frequency. The total amount of rainfall increases (to balance the increase
362 in magnitude of non-latent heating), reflected in the response of the rain amount distribution.

363 Also included in Fig. 6c is the combined shift-plus-increase mode fitted to the rain amount
364 response. The fitted shift-plus-increase response is colored orange (following the color scheme
365 shown in Fig. 2), which corresponds to equal magnitudes of shift and increase modes. The magni-
366 tudes and error of the fit are listed in Table 2 (and are normalized by 3 K warming to compare with
367 warming experiments, discussed next); the error is the magnitude of the response that the fitted
368 shift-plus-increase fails to capture. The fitted shift mode is slightly bigger than the fitted increase
369 mode, 11 versus 9 \%K^{-1} .

370 The response of the vertical velocity and rainfall distributions is essentially the same response
371 we would get from strengthening w in the first model (the opposite of the weakening w experiment
372 in Fig. 4d-f), only here it is achieved in a way that is consistent with energy as well as mass
373 balance. In this experiment, the magnitudes of vertical velocity and rain change, but the shape of
374 their distributions, including of the fraction of events that are rain-producing updrafts, does not.

375 In the second experiment, we again increase the magnitude of mean non-latent heating, but now
376 hold the width of the non-latent heating distribution constant and instead decrease stability S . We
377 determine the decrease in S required to balance the increase in \overline{Q}_n by linearizing the energy/mass
378 balance equation about a perturbation in S , shown in Appendix C. A decrease of S by 19% is
379 needed to maintain balance; the result is shown in Fig. 6d-f. Again we see strengthening of the
380 vertical velocity distribution, but here we also see an increase in skewness of 38%. The change
381 in rain frequency distribution has a shape that is similar to but not the same as in the previous ex-
382 periment, because the symmetry is broken: there is an increase in the dry-day frequency by 0.4%,
383 and thus a decrease in the total rain frequency. This change in symmetry arises from changing the
384 mean of Q_n without changing its width, so that the fraction of non-latent heating events that are
385 positive decreases (the positive w events and rainfall follow). The fitted shift-plus-increase mode
386 to the rain amount response is colored magenta to correspond to a broken symmetry between the
387 shift and increase modes.

388 In the third experiment, we narrow the distribution of non-latent heating by decreasing σ_{Q_n} by
389 23% and compensate it by decreasing S by 20%, holding \overline{Q}_n constant (Fig. 6g-i). Here, there
390 is negligible change in the width, or strength, of the vertical velocity distribution, but there is an
391 increase in skewness which arises from strong (though still relatively infrequent) updrafts. The dry
392 frequency increases, so there is an overall decrease in rain frequency, occurring mainly at moderate
393 rain rates. At the same time, there is a slight increase in frequency at the heaviest rain rates and
394 a larger (but still small) increase at light rain rates. The response of the rain amount distribution
395 is dominated by the decrease at moderate rain rates and increase at heavy rain rates, which are in
396 balance because the total rainfall does not change (\overline{Q}_n is fixed). The shift-plus-increase mode is
397 not a good fit for this response (light gray represents a poor fit of the shift-plus-increase mode).

398 The response of the vertical velocity distribution is a negligible change in width but an increase
399 in skewness, which we can understand as follows. The narrowing Q_n distribution would weaken
400 the vertical velocity distribution, but this is countered by the decrease in S , which strengthens
401 it (see Eqn. 7). Meanwhile, decreasing σ_{Q_n} with no corresponding change in \bar{Q}_n decreases the
402 fraction of events that are updrafts. The w distribution must adjust so that the same total latent
403 heating is achieved through fewer updrafts, which is accomplished by strengthening the strongest
404 updrafts, increasing the skewness of vertical velocity.

405 The response of the rain frequency and amount distributions to changing σ_{Q_n} and S in Fig. 6g-i
406 has some similarities to but also differences from the response to increasing skewness of w in the
407 first model (Fig. 4g-i). The close fit by the shift mode of the rain amount response to increasing
408 skewness in the first model indicates that the response is mostly just a movement of the rain amount
409 distribution to higher rain rates. In contrast, in this model and experiment, the shift mode poorly
410 captures the response. Despite that it is not captured by the shift and increase modes, the rain
411 frequency and amount responses have interesting resemblances to the global warming response in
412 climate models. One feature present here and in climate models that is not captured by the shift-
413 plus-increase is the light rain mode identified in Pendergrass and Hartmann (2014b). The light
414 rain mode is the small increase at light rain rates (around 1 mm d^{-1}) visible in Fig. 1c.

415 To summarize the effect of perturbing parameters other than temperature in this model: increas-
416 ing \bar{Q}_n increases the total amount of rainfall, while increasing σ_{Q_n} and decreasing S increase the
417 magnitude of vertical velocity events and the intensity of rainfall. When the combination of pa-
418 rameters changes in such a way that the fraction of events that are updrafts changes, the skewness
419 of the vertical velocity distribution also changes.

420 *c. Response to warming*

421 Next, we explore the response of the vertical velocity and rainfall distributions to warming. We
422 increase \bar{T} by 3 K (while allowing T_{max} to increase by the same amount). To maintain energy and
423 mass balance while warming, we will begin by adjusting one other parameter at a time, consid-
424 ering three experiments in turn, shown in Fig. 7. These first experiments are designed to help us
425 understand the model, and we will consider more realistic scenarios below.

426 In the first experiment, we balance warming by increasing S . Stability also changes in climate
427 model simulations of global warming; specifically, dry static stability increases with warming in
428 the tropics (e.g. Knutson and Manabe 1995) and subtropics and midlatitudes (e.g., Frierson 2006;
429 Lu et al. 2007). We determine effects of changing T on energy and mass balance and the increase
430 in S needed to balance it by linearizing Eqn. B4 for energy and mass balance about perturbations
431 in S and T , shown in Appendix C. This linearization shows that one degree of warming is balanced
432 by a 7% increase in stability, where the factor of 7% arises from the moistening associated with
433 the warming. The distributions of vertical velocity and moisture that result from warming by 3
434 K and increasing stability by 21% are shown in Fig. 7a-c. The increased stability decreases the
435 magnitude of vertical velocity for a given atmospheric column heating, so that the vertical velocity
436 is weakened (its standard deviation decreases, as in Held and Soden 2006; Vecchi and Soden 2007)
437 and the distribution of rainfall is exactly unchanged. The skewness of vertical velocity is also
438 unchanged. In this model, the dry frequency is just the fraction of the time that the atmospheric
439 column heating is negative; since atmospheric column heating does not change in this experiment,
440 neither does the dry frequency. The tradeoff between warming and stability here is similar to the
441 tradeoff between warming and the width of the vertical velocity distribution in our first model.

442 In the second experiment, we warm while increasing the magnitude of mean non-latent heating
443 \overline{Q}_n and holding all other parameters constant. Recall that \overline{Q}_n controls the total precipitation. The
444 resulting distributions of vertical velocity and rainfall are shown in Fig. 7d-f. The resulting vertical
445 velocity distribution has no substantial change in width, but it does have increase in skewness.
446 Similarly to the “narrow Q_n and decrease S ” experiment in Fig. 6g-i, the increase in moisture and
447 increase in mean Q_n have largely compensating effects on the vertical velocity distribution, except
448 for a decrease in the total fraction of updrafts compared to downdrafts, resulting in an increase
449 in skewness with little change in width of the w distribution. The response of the rain frequency
450 distribution, on the other hand, is more similar to the increasing \overline{Q}_n and decreasing S experiment.
451 There is an increase in the dry frequency, and the rain amount response is captured by a shift mode
452 that is slightly larger than the increase mode. Examination of Eqns. 2 and 7 reveals that this is
453 possible because both experiments have the same change in Q_n , and decreasing S has the same
454 effect on the denominator of Eqn. 7 as increasing q .

455 In the third experiment, warming is balanced by narrowing of the non-latent heating distribution
456 (decreasing σ_{Q_n} or weakening the dry static energy flux convergence, Fig. 7g-i). In this exper-
457 iment, the vertical velocity distribution weakens while the skewness increases. The skewness
458 arises because of the decrease in upward frequency and adjustments to maintain mass as well
459 as energy balance, while the weakening results from the weakening of the Q_n distribution. The
460 rain frequency and amount distributions are very similar to the “narrowing Q_n and decreasing S ”
461 experiment with no warming.

462 In two final experiments, we emulate the changes seen in climate models: we warm and also
463 increase the magnitude of non-latent atmospheric column heating \overline{Q}_n by $1.1 \text{ W m}^{-2} \text{ K}^{-1}$, which
464 is the rate at which global-mean precipitation and clear-sky atmospheric radiative cooling increase
465 in climate model projections of the response to transient carbon dioxide increase (Pendergrass and

466 Hartmann 2014a). This change in atmospheric radiative cooling includes both the temperature-
467 mediated and direct effects of carbon dioxide. To maintain mass and energy balance, we allow
468 a third parameter to change, and keep the fourth constant (first increasing S , and then decreasing
469 σ_{Q_n}); these experiments are shown in Fig. 8. We examine each parameter change separately, but
470 in at least one climate model simulation forced by a transient increase in carbon dioxide (with
471 the MPI-ESM-LR model) both changes occur: S increases (by 1.7 \%K^{-1} in the tropics) and σ_{Q_n}
472 decreases (by 0.7 \%K^{-1}).

473 First, we warm, increase mean Q_n , and allow S to increase. According to the linearizations about
474 S and T in Appendix C, a change in stability of 6.0 \%K^{-1} is needed to maintain energy and mass
475 balance. This change in stability is slightly smaller than what was needed to balance warming
476 alone (7 \%K^{-1} , discussed in the first experiment above), due to the accompanying change in \bar{Q}_n .
477 The result (shown in Fig. 8a-c) is a combination of the experiments where we warmed and varied
478 mean Q_n and S separately. The vertical velocity distribution weakens and has a small increase in
479 skewness. There is a modest increase in dry frequency, and a modest break in symmetry between
480 the shift and increase modes (2.0 versus 1.6 \%K^{-1}). This is not as large as the break in symmetry
481 we see in climate models.

482 Finally, we warm, increase mean Q_n , and allow σ_{Q_n} to decrease by 6.2 \%K^{-1} . This value of
483 σ_{Q_n} change is need to restore energy and mass balance given the warming of 1 K and the increase
484 in \bar{Q}_n of $1.1 \text{ Wm}^2\text{K}^{-1}$, chosen following Appendix Ac. In Fig. 8d we see a weakening of the
485 vertical velocity distribution and a larger increase in skewness than in Fig. 8a. Analogously to the
486 warming and skewing experiment with the first model, the rain frequency and amount distribution
487 responses (Fig. 8e,f) resemble the superposition of responses in previous experiments. The dry
488 frequency increases, and the response of the rain frequency distribution has a decrease at moderate
489 rain rates that is partially compensated by an increase at heavy rain rates. The rain frequency

490 response strongly resembles the response we see in climate models (Fig. 1c), except that the light
491 rain mode is absent. The rain amount distribution response is partially but not completely captured
492 by the shift and increase modes, which reflects that it is the sum of a response that the shift-plus-
493 increase captures (the response to warming while and increasing $|\overline{Q}_n|$) and one that it does not (the
494 response to changing σ_{Q_n}). The fitted shift-plus-increase overestimates the decrease at moderate
495 rain rates and underestimates the increase at heavy rain rates, reminiscent of the extreme mode
496 identified in Pendergrass and Hartmann (2014b).

497 To summarize, in our second model, the atmosphere can respond in three ways to warming: (1)
498 increasing the stability (S), which weakens the circulation (w) but has no effect on rain, (2) in-
499 creasing the total precipitation (\overline{Q}_n), which drives an increase in skewness of w and of the intensity
500 of the heaviest rainfall events, and (3) decreasing the width of the non-latent heating distribution
501 (σ_{Q_n}), which leads to both a weakening of the circulation and increase in its skewness, and the
502 accompanying increase in intensity of the heaviest rainfall events. In climate model projections of
503 warming, energetic constraints require an increase in the total precipitation \overline{Q}_n .

504 In this simple model, if we warm and increase mean latent heating \overline{Q}_n , the stability S and/or
505 width of the non-latent heating distribution σ_{Q_n} – which is intimately related to the circulation
506 – must also change to maintain energy and mass balance. Any combination of these parameter
507 changes results in: (1) a weakening of the circulations (i.e. of w), the essential conclusion of
508 Vecchi and Soden (2007), (2) an increase in the skewness of w , and (3) an increase in intensity of
509 the heaviest rain events (e.g., Trenberth 1999).

510 **4. Comparison with the response to warming in climate models**

511 The two heuristic models above show that increasing skewness of the vertical velocity distri-
512 bution coincides with key characteristics of the changing distribution of rainfall that we see in

513 climate models. Does skewness of the vertical velocity distribution increase with warming in
514 climate models?

515 To address this question, we calculate statistics of daily-average 500 hPa pressure vertical veloc-
516 ity and their change in three warming experiments in the CMIP5 archive (Table 4). We calculate
517 the area-weighted global-average moments from years 2006-2015 and 2090-2099 in the RCP8.5
518 scenario, and years 1-10 and 61-70 in the transient carbon dioxide increase 1pctCO2 scenario;
519 these results can be compared with the fitted shift-plus-increase modes of the distribution of rain
520 in Pendergrass and Hartmann (2014b). Trends in data can contaminate statistical measures of a dis-
521 tribution, so we also analyze the last 10 years of the CO₂ quadrupling experiment (abrupt4xco2),
522 when the climate is as close to equilibrating as is available in the CMIP5 archive, and trends are
523 as small as possible.

524 All climate model simulations have increasing skewness of vertical velocity, consistent with
525 our expectations from the heuristic models along with the changing distribution of rain in climate
526 models. The magnitude of increase in skewness varies widely across models, from less than 1
527 to 27 %K⁻¹. Note that the models with the biggest increases in skewness (the GFDL-ESM and
528 IPSL-CM5A models) also have a large extreme mode (Pendergrass and Hartmann 2014b). While
529 we have touched on the extreme mode in our second heuristic model, much about it remains to be
530 investigated.

531 The variance of vertical velocity decreases in all but one of the climate model simulations.
532 Decreasing variance of vertical velocity at 500 hPa is consistent with Held and Soden (2006) and
533 Vecchi and Soden (2007), though their metrics were slightly different from ours and the magnitude
534 of changes shown here is smaller. Additionally, the change in vertical velocity strength at 500 hPa
535 is expected to underestimate the weakening of the total vertical overturning circulation because the
536 strongest motion is above 500 hPa and shifts upward with warming (Singh and O’Gorman 2012).

537 We include the changes in kurtosis in Table 4, the fourth moment of the distribution. Larger
538 kurtosis corresponds to a fatter tail and a narrower peak of the distribution; a normal distribution
539 has a kurtosis of 3 (e.g., DeCarlo 1997). In all climate models, kurtosis of vertical velocity is
540 initially greater than Gaussian, and it increases with warming. Our second model predicts an
541 increase in kurtosis along with the increases in skewness. Interestingly, the GFDL models have by
542 far the largest increases in kurtosis with warming (they also have large extreme modes).

543 We are now in a position to reconcile the differing magnitudes of the shift and increase modes
544 with warming that we see in climate model simulations. For the multi-model mean, moistening
545 occurs at about 6-7 %K⁻¹ and global mean precipitation increases at 1.5 %K⁻¹. The multi-model
546 mean rain amount response has an increase mode of 1 %K⁻¹ and a shift mode of 3.3 %K⁻¹. The
547 MPI-ESM-LR model, whose response is best captured by the shift and increase modes, has an
548 increase mode of 1.3 %K⁻¹ and a shift mode of 5.7 %K⁻¹.

549 We relate the shift and increase modes to changes in moisture and circulation as follows (and
550 shown in Fig. 4 as well as listed in Table 2): moistening at 7 %K⁻¹ results in equal magnitudes
551 of shift and increase modes. This is countered by a narrowing of the vertical velocity distribution
552 that is not quite as large, bringing the net magnitudes of both the shift and increase modes down.
553 Finally, an increase in skewness of the vertical velocity distribution results in a shift mode with no
554 corresponding increase mode. The combination of these three changes results in a shift mode that
555 is larger than the increase mode seen in the climate model response to warming.

556 While the heuristic models developed here capture some important aspects of the response of
557 rainfall and vertical velocity to warming seen in climate models, the cost of its simplicity is the
558 number of assumptions that must be made. Assumptions for our idealized relationship between
559 moisture, vertical velocity and rain rate include: that all moisture is removed whenever there is
560 upward motion, that the vertical structure of the atmosphere is fixed, and that relative humidity

561 does not change. Our models do not accommodate any unresolved processes, parameterized in
562 climate models, which can alter the relationship between rainfall and vertical velocity. This ide-
563 alized framework also does not address the differing direct and temperature-mediated responses
564 of precipitation and circulation to greenhouse gas forcing. Finally, aggregating over all locations
565 and seasons convolves many different processes, and the relationships we explore here may not
566 hold for all of them. Nonetheless, while we anticipate that our heuristic models do not capture the
567 behavior of every relevant process that contributes to the responses of rainfall and vertical velocity
568 to global warming, we think these models are useful for understanding a substantial portion of the
569 response in many regions of most climate models.

570 **5. Convective area**

571 The spatial manifestation of the distribution of rain and vertical velocity is convective area, by
572 which we mean the area with upward motion and the cloudiness and rainfall that accompany it.
573 The fraction of time that vertical motion is upward and the fraction of time that it is raining in
574 the heuristic models presented here is analogous to the fraction of the area in a domain where
575 rain is occurring. The literature is currently unsettled about how the change in convective area
576 and frequency of upward motion are expected to change with warming. Johnson and Xie (2010)
577 argues that the convectively active fractional area of the tropics changes little relative to the area
578 above an absolute SST threshold, which increases by 45% over the 21st century in the experiments
579 they analyze, though this study focused on monthly mean precipitation, rather than daily data. In
580 contrast, Vecchi and Soden (2007) report a decrease in the number of grid points with upward mo-
581 tion in GFDL-CM2.1 simulations of global warming in the tropics. Other recent studies focusing
582 on monthly to seasonal mean precipitation find a decrease in the area of the ITCZ with warming
583 (Neelin et al. 2003; Huang et al. 2013; Wodzicki and Rapp 2016). Byrne and Schneider (2016)

584 examine the width of the ITCZ over a wide range of climates in a gray-radiation climate model and
585 find different responses in different climate states. In CMIP5 model simulations, the frequency of
586 dry days has a small but significant increase (see Fig. 1a or Pendergrass and Hartmann 2014b).

587 The heuristic models shown here reproduce the increase in dry frequency seen in the CMIP5
588 models and thus also the decrease in convective area. Figure 9 shows a schematic of the tropical
589 overturning circulation to aid in interpreting its response to changes in the distribution of vertical
590 velocity. The initial distribution has a region of ascent that is narrower than the region of descent,
591 analogous to the circulation in the tropical atmosphere (Fig. 9a). Because the region of ascent is
592 narrower and mass is conserved, the ascending motions are stronger than corresponding descend-
593 ing ones. Decreasing the standard deviation of the vertical velocity distribution decreases the
594 magnitude of both upward and downward motion (weakening the circulation), with no change in
595 area of either region (Fig. 9b). Increasing the skewness of vertical velocity increases the magnitude
596 of upward motion while decreasing its area, and decreases the speed of descent while increasing
597 its area (Fig. 9c). When the decrease in standard deviation and increasing skewness occur to-
598 gether, both contribute to weakening the descending motion, but they have competing effects on
599 the magnitude of ascent, resulting in little change in updraft strength (Fig. 9d).

600 **6. Conclusion**

601 We have introduced two idealized models relating the distributions of rain and vertical veloc-
602 ity. In both models, temperature (and thus moisture, assuming constant relative humidity) is pre-
603 scribed, and the distribution of rainfall is predicted. In the first model, the distribution of vertical
604 velocity is also prescribed and can be varied; mass conservation is respected. In the second model,
605 the distribution of non-latent atmospheric column heating is prescribed, the distribution of vertical
606 velocity is predicted, and both mass and energy are conserved. Some key assumptions made by

607 both models are that relative humidity is fixed within and between climate states and that stability
608 is constant within each climate state.

609 Both of these models show that increasing skewness, or asymmetry, of the vertical velocity dis-
610 tribution is necessary to recover important characteristics of the changing distribution of rain with
611 warming predicted by climate models: dry-day frequency increases, and extreme precipitation in-
612 creases at a rate faster than the increase in mean precipitation. In the context of shift and increase
613 modes of change of the distribution of rain, an increase in skewness is necessary to achieve the
614 larger shift mode than increase mode seen in climate model projections. The second model, where
615 the distribution of vertical velocity is predicted, shows how the asymmetric influence of latent
616 heating creates skewness in the vertical velocity distribution. Experiments with this model show
617 that this skewness increases in response to warming, along with the adjustments needed to main-
618 tain mass and energy balance. In addition to an increase in skewness, the standard deviation of
619 the vertical velocity distribution also decreases, consistent with the weakening circulation found
620 in climate model simulations of global warming.

621 The models developed here capture salient aspects of the changing distributions of rain and
622 vertical velocity with simple thermodynamic relationships, implying that we do not need to resort
623 to complex dynamical explanations for these aspects of the changing distribution of rain. The
624 idealized relationships between the distributions of vertical velocity and precipitation explored
625 here hopefully form a basis for understanding the richer and more complex interactions in climate
626 models and in the real world.

627 *Acknowledgments.* We thank Clara Deser, Ben Sanderson, Brian Rose, Flavio Lehner, and two
628 anonymous reviewers for their feedback. NCAR's Advanced Studies Program postdoctoral re-

629 search fellowship provided funding for AGP. EPG acknowledges support from the National Sci-
630 ence Foundation through grant AGS-1264195.

631 APPENDIX A

632 Numerical solutions

633 *a. Normal and skew-normal distributions*

634 We calculate the value of the normal distribution at points that are evenly spaced in percentile
635 space, 5000 points for Model 1 and 10 000 for Model 2. For the temperature distribution, any
636 values of $T > T_{max}$ are truncated. For making calculations over joint distributions (r over T/q and
637 w in Model 1, r and w over Q_n and T/q in Model 2), we form a matrix over both distributions (of
638 size 5000 x 5000 or 10 000 x 10 000¹) and calculate the value at each point in the joint space.

639 Calculating the skew normal distribution is similar to a joint distribution because the algorithm
640 of Azzalini and Capitanio (1999) calls for operating on two normal distributions. We start with
641 normal distributions u_0 and v (5000 samples for each). To get a distribution with a shape parameter
642 a (which is related to the skewness; when a is zero the distribution is normal, and we use $a > 0$
643 here), we calculate $u_1 = du_0 + \sqrt{(1-d^2)}v$, where $d = a/\sqrt{(1+a^2)}$ is a correlation related to the
644 shape parameter. Then, the skewed distribution z is u_1 when $u_0 > 0$ and $-u_1$ otherwise. Finally,
645 this 5000 x 5000 array is subsampled back to 5000 values by sorting them and keeping every
646 5000th one.

647 *b. Frequency and amount distributions*

648 We use logarithmically-spaced bins for the rain frequency and amount distributions, and choose
649 250 of them to obtain stable fits of the shift-plus-increase modes. Details of the calculation and

¹With the introduction of T_{max} , we truncate a few values at the high end of the T/q distribution.

650 further examples of rain amount and rain frequency distributions can be found in Pendergrass and
651 Hartmann (2014c). We use 50 linearly-spaced bins for $p(T)$, $p(Q_n)$, and $p(w)$, which are for
652 display only.

653 *c. Model 2 parameters*

654 To calculate the parameters in the second model, there are two steps: the initial set up to find a
655 balanced state and variation of parameters about this state.

656 To set up the model initially, the challenge is meeting energy and mass balance. We accomplish
657 this numerically by specifying all parameters other than \bar{Q}_n , and then systematically solving for the
658 value of \bar{Q}_n that achieves energy and mass balance (Eqn. B4). First, we calculate the distribution
659 of T from \bar{T} and σ_T , truncating anything over T_{max} , and we calculate the associated q . Then
660 with a choice of S , we calculate the LHS of the energy/mass balance equation (B in Appendix C).
661 Finally, we use a specified value of σ_{Q_n} , and solve systematically for the value of \bar{Q}_n that most
662 closely results in mass/energy balance. We take a vector of 10 000 Gaussian values evenly spaced
663 percentile-wise (call them y), and using the σ_{Q_n} value, calculate the RHS of the energy/mass
664 balance equation that would result for each choice of $\bar{Q}_n = y\sigma_{Q_n}$. To vary parameters, new \bar{T} , σ_T ,
665 S , and σ_{Q_n} values can be manually chosen and a new \bar{Q}_n found.

666 To find a new balanced state due to small variations in T and S around the initial balanced state,
667 we use the linearizations in Appendix C. This is done in three different ways. Whenever possible,
668 we use the linearization alone to find new values of T and S , or of the new LHS of the energy/mass
669 balance equation. When necessary, we re-solve for a new \bar{Q}_n that best meets energy/mass balance
670 as we did to find the initial balanced \bar{Q}_n value. Otherwise (e.g., when changing σ_{Q_n}), we iteratively
671 choose parameter values (manually) until the energy/mass balance equation is satisfied again (to

672 4 decimal places). Once we have a new set of parameters, r , w , and their frequency and amount
673 distributions $p(r)$, $P(r)$, and $p(w)$ are calculated once again.

674

APPENDIX B

675

Conservation of mass and energy

676 In this appendix, we derive the equation for mass and energy conservation of the model described
677 in Section 3. In order to conserve mass, we must maintain an integral of vertical velocity over the
678 entire distribution equal to zero,

$$\int_{-\infty}^{\infty} \int_0^{q_{max}} w p(q, Q_n) dq dQ_n = 0, \quad (\text{B1})$$

679 where $p(q, Q_n)$ is the joint probability distribution function (pdf) of q and Q_n , and q_{max} is the
680 maximum realized specific humidity, occurring at temperature T_{max} . In order to conserve energy,
681 we enforce that the total latent heating must be balanced by the total non-latent heating,

$$\int_{-\infty}^{\infty} Q_n p(Q_n) dQ_n + \int_{-\infty}^{\infty} \int_0^{q_{max}} L r p(q, Q_n) dq dQ_n = 0, \quad (\text{B2})$$

682 where $p(Q_n)$ is the pdf of non-latent heating Q_n .

683 Substituting Eqns. 2 and 5 into B2, separating regions of positive and negative Q_n , exploiting
684 the independence of q and Q_n , and rearranging, we have,

$$\int_0^{q_{max}} \left[\frac{1}{1 - L \rho_a q / S} \right] p(q) dq = \frac{- \int_{-\infty}^0 Q_n p(Q_n) dQ_n}{\int_0^{\infty} Q_n p(Q_n) dQ_n}. \quad (\text{B3})$$

685 It is also possible to arrive at Eqn. B3 by starting from the mass conservation constraint
 686 (Eqn. B1), substituting Eqn. 5, exploiting the independence of q and Q_n , recognizing that
 687 $\int p(q)dq = 1$, and rearranging.

688 Following either path, we find that both the mass and energy constraints are met when,

$$E_q \left[\frac{1}{1 - L\rho_a q/S} \right] = \frac{-\int_{-\infty}^0 Q_n p(Q_n) dQ_n}{\int_0^{\infty} Q_n p(Q_n) dQ_n}, \quad (\text{B4})$$

689 where the expectation operator is defined as $E_x[f(x)] = \int_{-\infty}^{\infty} f(x)p(x)dx$.

690 APPENDIX C

691 **Linearization of energy and mass balance about T and S**

692 Here, we linearize the mass and energy conservation equation about its base state (the left hand
 693 side of Eqn. B4) to obtain its response to small changes in stability S and mean temperature \bar{T} .
 694 Along with new values of \bar{Q}_n and σ_{Q_n} chosen by trial and error, we use this linearization to find new
 695 sets of parameters that satisfy energy and mass balance in the experiments described in Section 3b
 696 and c. To be concise, in this appendix we refer to the LHS of Eqn. B4 as B ,

$$B = E_T \left[\frac{1}{1 - L\rho_a q(T)/S} \right]. \quad (\text{C1})$$

697 *a. Linearization in T*

698 First, we linearize the LHS of Eqn. B4 to find its response to small changes in \bar{T} and the asso-
 699 ciated moistening. We expand $T = \bar{T} + \Delta T = \bar{T}(1 + x)$, where $x = \Delta T/\bar{T} \ll 1$. Incorporating our

700 moisture equation (1), we have,

$$B = \int_{-\infty}^{T_{max}} \frac{1}{1 - L\rho_a q_0 e^{0.07\bar{T}(1+x)}/S} p(T) dT. \quad (C2)$$

701 A first order Taylor expansion around B gives us,

$$B \approx B_0 + 0.07 \Delta T B_1, \quad (C3)$$

702 where B_0 is the value of B evaluated at $T = \bar{T}$ and,

$$B_1 \equiv \int_0^{q_{max}} \frac{L\rho_a q/\bar{S}}{(1 - L\rho_a q/\bar{S})^2} p(q) dq. \quad (C4)$$

703 This integral is readily evaluated numerically from a base q distribution.

704 *b. Linearization in S*

705 Next, we linearize Eqn. B4 to find the response to small changes in stability S . Expanding

706 $S = \bar{S} + \Delta S = \bar{S}(1+x)$, where $x = \Delta S/\bar{S} \ll 1$, we have,

$$B = \int_0^{q_{max}} \frac{1}{1 - L\rho_a q/\bar{S}(1+x)} p(q) dq. \quad (C5)$$

707 Another Taylor expansion gives us,

$$B \approx B_0 - \frac{\Delta S}{\bar{S}} B_1. \quad (C6)$$

708 We can combine Eqns. C3 and C6 and solve for ΔS ,

$$\Delta S = S \left(0.07 \Delta T - \frac{B - B_0}{B_1} \right). \quad (C7)$$

709 Given a ΔT and possibly a new value of \bar{Q}_n or σ_{Q_n} (which requires calculating a new value of B),
710 we can solve for the ΔS that satisfies mass and energy balance.

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788 **LIST OF TABLES**

789 **Table 1.** Initial parameter choices for the first model. 40

790 **Table 2.** The magnitude of fitted shift and increase modes along with their error (the
791 magnitude of the response that the fitted shift-plus-increase fails to capture) for
792 each of the experiments shown and discussed here. The precipitation response
793 to a transient CO₂ increase in climate models is shown for the CMIP5 multi-
794 model mean as well as for one GCM, MPI-ESM-LR, which is fit the best of
795 all the CMIP5 models (see Pendergrass and Hartmann 2014b for details). The
796 Model 1 experiments are shown in Fig. 4 and discussed in Section 2b-d. Model
797 Model 2 experiments are shown in Figs. 6-8 and discussed in Section 3c. 41

798 **Table 3.** Initial parameter choices for the second model. 42

799 **Table 4.** Standard deviation, skewness, and kurtosis of 500 hPa pressure vertical veloc-
800 ity from CMIP5 models and their response to warming (normalized by global
801 mean surface temperature change). 43

TABLE 1. Initial parameter choices for the first model.

Variable	Value	Description
\bar{T}	287 K	Mean temperature
σ_T	16 K	Width of temperature dist.
\bar{w}	0	Mean vertical velocity, w
σ_w	1 mm s ⁻¹	Width of w dist.

802 TABLE 2. The magnitude of fitted shift and increase modes along with their error (the magnitude of the
803 response that the fitted shift-plus-increase fails to capture) for each of the experiments shown and discussed here.
804 The precipitation response to a transient CO₂ increase in climate models is shown for the CMIP5 multi-model
805 mean as well as for one GCM, MPI-ESM-LR, which is fit the best of all the CMIP5 models (see Pendergrass
806 and Hartmann 2014b for details). The Model 1 experiments are shown in Fig. 4 and discussed in Section 2b-d.
807 Model 2 experiments are shown in Figs. 6-8 and discussed in Section 3c.

Model	Experiment	Shift (%K ⁻¹)	Increase (%K ⁻¹)	Error (%)
CMIP5 MMM	2xCO ₂	3.3	0.9	33
MPI-ESM-LR	2xCO ₂	5.7	1.3	14
Model 1	Warm	7	7	2
	Weaken w	-4	-4	1
	Skew w	5	-1	27
	Warm, skew w	13	6	15
	Warm, weaken w , skew w	8	2	21
Model 2	Increase \bar{Q}_n , widen Q_n	11	9	11
	Increase \bar{Q}_n , decrease S	11	8	23
	Narrow Q_n , decrease S	0	-1	81
	Warm, increase S	0	0	22
	Warm, increase \bar{Q}_n	11	8	23
	Warm, narrow Q_n	0	-1	81
	Warm, GCM \bar{Q}_n , increase S	2.0	1.6	12
	Warm, GCM \bar{Q}_n , narrow Q_n	1.7	0.5	68

TABLE 3. Initial parameter choices for the second model.

Variable	Value	Description
\bar{T}	287 K	Mean temperature
σ_T	10 K	Width of temperature dist.
T_{max}	317 K	Cap on the temperature dist.
\bar{Q}_n	-88 W m^{-2}	Mean non-latent heating
σ_{Q_n}	$2,500 \text{ W m}^{-2}$	Width of non-latent heating dist.
S	$4.75 \times 10^5 \text{ kg m}^{-1} \text{ s}^{-2}$	Stability

808 TABLE 4. Standard deviation, skewness, and kurtosis of 500 hPa pressure vertical velocity from CMIP5
 809 models and their response to warming (normalized by global mean surface temperature change).

Scenario	Model (Pa s ⁻¹)	std (%K ⁻¹)	Δstd	skew (%K ⁻¹)	Δskew	kurtosis (%K ⁻¹)	Δkurtosis
RCP8.5	MIROC-ESM-CHEM	9.0	-2.5 %	-0.66	0.57%	5.8	0.85%
	FGOALS-g2	12	-2.7 %	-1.9	1.4 %	15	1.8 %
	NorESM1-M	8.1	-2.0 %	-1.2	1.4 %	8.6	3.5 %
	BNU-ESM	8.2	-2.1 %	-0.80	2.7 %	5.9	3.6 %
	CMCC-CESM	8.9	-1.9 %	-0.56	3.1 %	5.2	2.0 %
	BCC-CSM1.1	11	-0.97%	-1.8	4.0 %	15	6.3 %
	IPSL-CM5B-LR	11	-2.1 %	-3.3	4.4 %	48	5.8 %
	MPI-ESM-LR	11	-1.8 %	-1.00	4.6 %	7.4	4.8 %
	CNRM-CM5	11	-1.1 %	-1.9	5.4 %	20	8.3 %
	GFDL-CM3	8.5	-1.7 %	-1.4	6.2 %	13	10 %
	CCSM4	9.0	-1.4 %	-1.8	6.2 %	17	10 %
	GFDL-ESM2M	8.9	-1.4 %	-1.6	16 %	18	28 %
	IPSL-CM5A-LR	8.8	-1.2 %	-1.1	21 %	14	23 %
GFDL-ESM2G	8.7	-1.1 %	-1.3	22 %	12	49 %	
Transient CO ₂ increase	IPSL-CM5B-LR	12	-2.1%	-3.2	2.3%	46	4.0%
	MIROC5	10	-2.0%	-1.4	4.4%	10	6.5%
	GFDL-ESM2G	8.8	-1.0%	-1.2	11 %	10	22 %
	IPSL-CM5A-MR	9.5	-2.1%	-1.4	14 %	18	19 %
	GFDL-ESM2M	8.9	-1.8%	-1.3	19 %	12	38 %
IPSL-CM5A-LR	9.1	-2.7%	-0.86	27 %	11	26 %	
Abrupt CO ₂ increase	MIROC-ESM	9.3	-2.6 %	-0.65	0.29%	5.6	0.75%
	IPSL-CM5B-LR	12	-2.3 %	-3.3	3.0 %	48	5.1 %
	MIROC5	10	-1.9 %	-1.4	4.2 %	10	5.8 %
	CanESM2	9.3	-0.64%	-1.0	5.2 %	9.6	6.2 %
	MPI-ESM-LR	11	-1.4 %	-0.91	5.8 %	7.0	4.7 %
	MRI-CGCM3	11	0.84 %	-2.0	17 %	20	35 %
	IPSL-CM5A-MR	9.5	-1.0 %	-1.4	20 %	18	31 %
	IPSL-CM5A-LR	9.1	-1.4 %	-0.87	25 %	11	27 %

810 **LIST OF FIGURES**

811 **Fig. 1.** The CMIP5 multi-model mean distributions of daily (a) rain frequency (with dry-day fre-
 812 quency at top left) and (b) rain amount, during the first ten years of the transient carbon
 813 dioxide increase emissions scenario, 1pctco2. The response of (c) rain frequency and (d)
 814 rain amount to increasing carbon dioxide, calculated as the difference between the ten years
 815 at the time of carbon dioxide doubling and the first ten years and normalized by the change
 816 in global-mean surface temperature. Change in dry-day frequency ($\%K^{-1}$) is noted in the
 817 top left corner of panel c. Error intervals are the 95% confidence limits according to a Stu-
 818 dent's t -test. As the distributions are plotted on a logarithmic scale, they are weighted by
 819 the rain rate r so that the area under the curve accurately represents the contribution of each
 820 rain rate to the total integral. Following Pendergrass and Hartmann (2014b and c), though
 821 the r -weighting is implicit to the procedure described there. 46

822 **Fig. 2.** The rain frequency (left) and amount (right) responses to (a-b, purple) an increase mode
 823 of 0.9%, (c-d, turquoise) a shift mode of 3.3%, (e-f, magenta) a shift mode of 3.3% and
 824 increase mode of 0.9%, and (g-h, orange) equal magnitude shift and increase of 3.3%. The
 825 color scheme corresponds to these modes throughout the paper. The initial distribution is
 826 shown in Fig 3. 47

827 **Fig. 3.** The distributions driving the first model, where vertical velocity is prescribed: (a) tempera-
 828 ture and moisture, and (b) vertical velocity (skewness is noted in the top right corner). The
 829 resulting distributions of (c) rain frequency (dry frequency, when rain rate is equal to zero,
 830 is noted in the bottom left corner) and (d) rain amount. 48

831 **Fig. 4.** Experiments with the first model. (left) Prescribed vertical velocity distribution, with the
 832 initial distribution in the gray-dashed line and each experiment's distribution in solid black
 833 (skewness noted at top right of each panel). (center) Predicted rain frequency response
 834 (change in dry frequency noted at center-left). (right) Predicted rain amount response
 835 in black, with the fitted shift-plus-increase response in color. Colors correspond to Fig. 2; the
 836 magnitude of the fitted shift and increase modes and their errors are listed in Table 2. Each
 837 row is one experiment: (a-c) warm, (d-f) weaken the vertical velocity distribution, (g-i) skew
 838 the vertical velocity distribution, (j-l) warm and skew, and (m-o) warm while weakening and
 839 skewing the vertical velocity distribution. 49

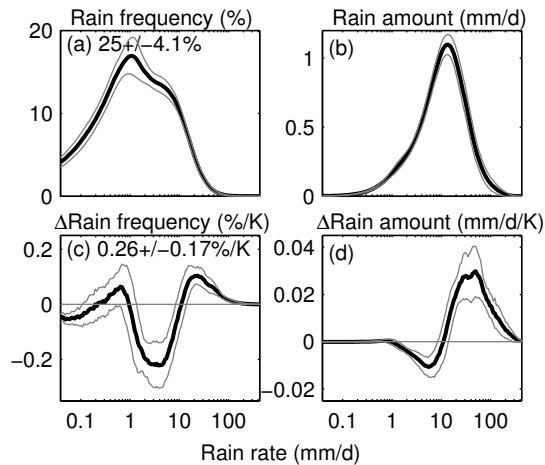
840 **Fig. 5.** The prescribed (top) distributions driving the second model, where vertical velocity is pre-
 841 dicted: (a) temperature and moisture, and (b) non-latent heating (mean is noted in the top-
 842 right corner). The resulting predicted (bottom) distributions of (c) vertical velocity, (d) rain
 843 frequency (dry frequency noted in the bottom left corner) and (e) rain amount. 50

844 **Fig. 6.** Experiments varying parameters other than the mean temperature with the second model,
 845 following Fig. 4 but here the vertical velocity distribution (left) is predicted. (a-c) Increasing
 846 the magnitude of mean non-latent heating and increasing the width of the non-latent heating
 847 distributions, while holding all other parameters constant. (d-f) Increasing the magnitude
 848 of mean non-latent heating and decreasing stability. (g-i) Narrowing the non-latent heating
 849 distribution (decreasing σ_{Q_n}) and decreasing stability. Note the smaller y axis magnitudes in
 850 panels h and i. Changes are normalized by a 3 K warming for comparison with Figs. 7 and 8. 51

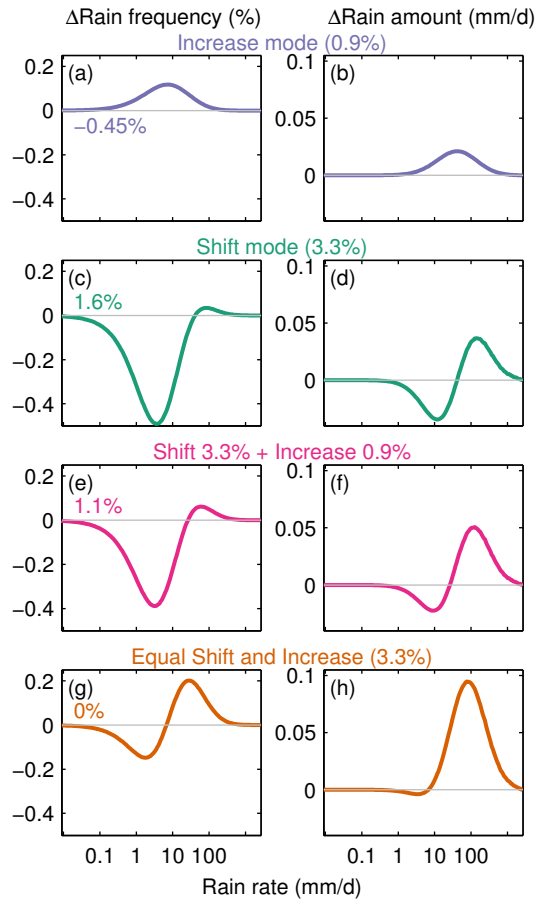
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 852 Fig. 6: (a-c) increasing stability, (d-f) increasing the magnitude of mean non-latent heating,
 853 and (g-i) narrowing the non-latent heating distribution (decreasing σ_{Q_n} , note the smaller y
 854 axis magnitudes in panels h and i). 52

855 **Fig. 8.** Experiments warming, increasing the magnitude of the non-latent heating distribution by
856 the value from climate models, $1.1 \text{ W m}^{-2} \text{ K}^{-1}$, while varying one other parameter with the
857 second model, following Fig. 6: (a-c) increasing stability, and (d-f) narrowing the non-latent
858 heating distribution (decreasing σ_{Q_n}). 53

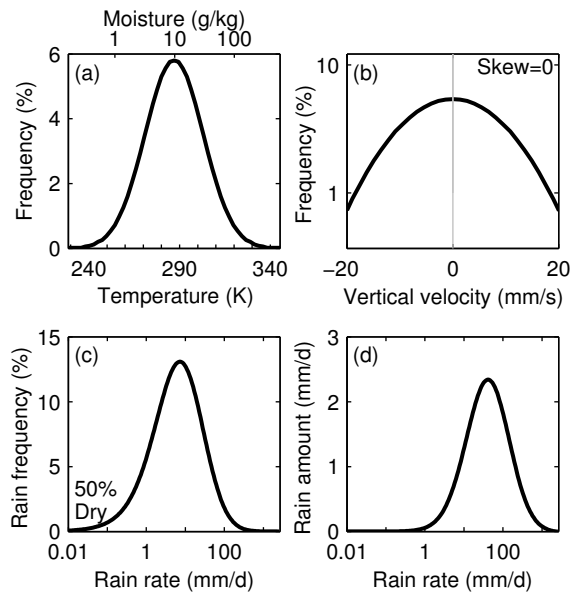
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861 dard deviation, (c) increasing its skewness, and (d) both decreasing standard deviation and
862 increasing skewness together. 54



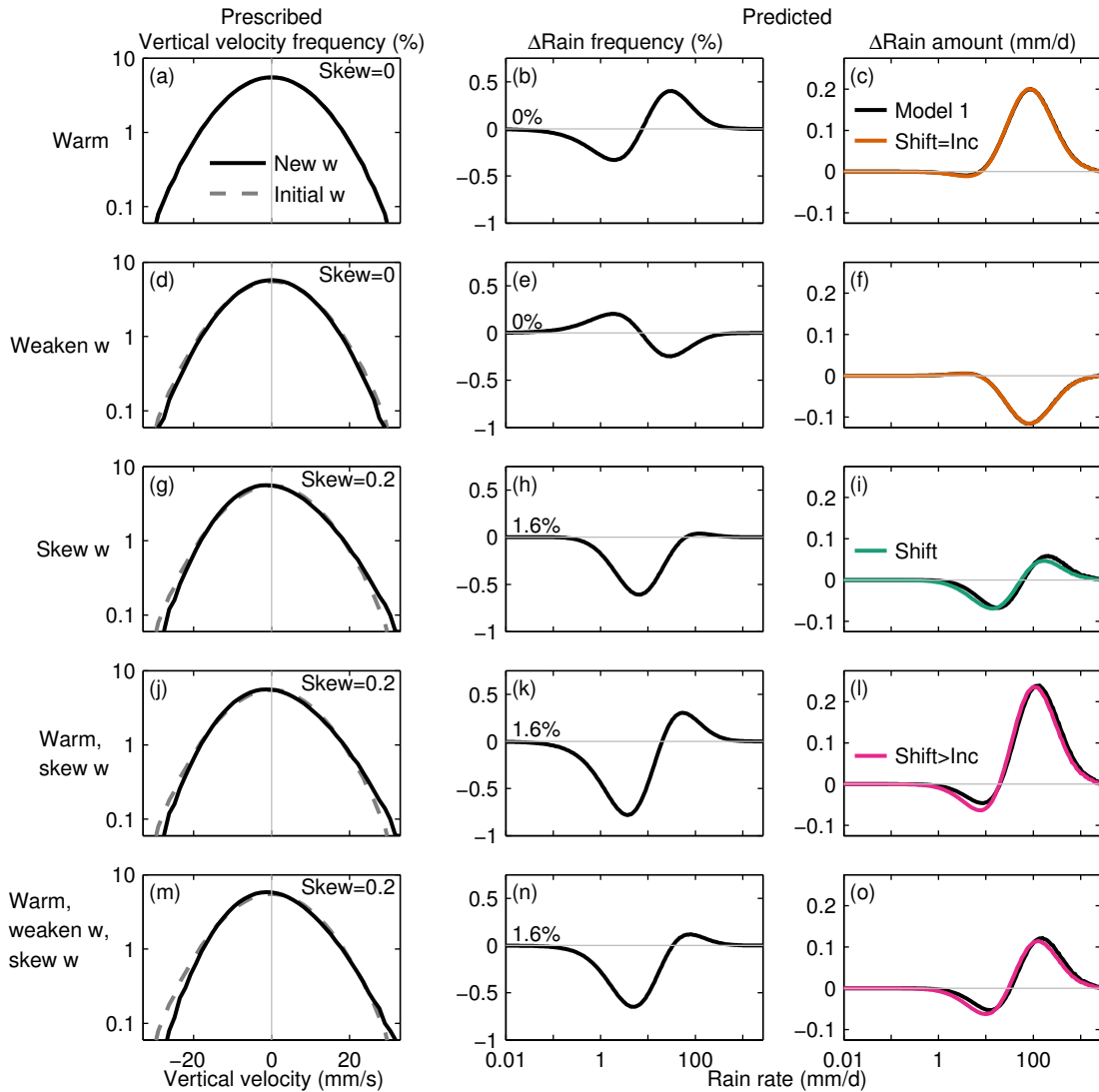
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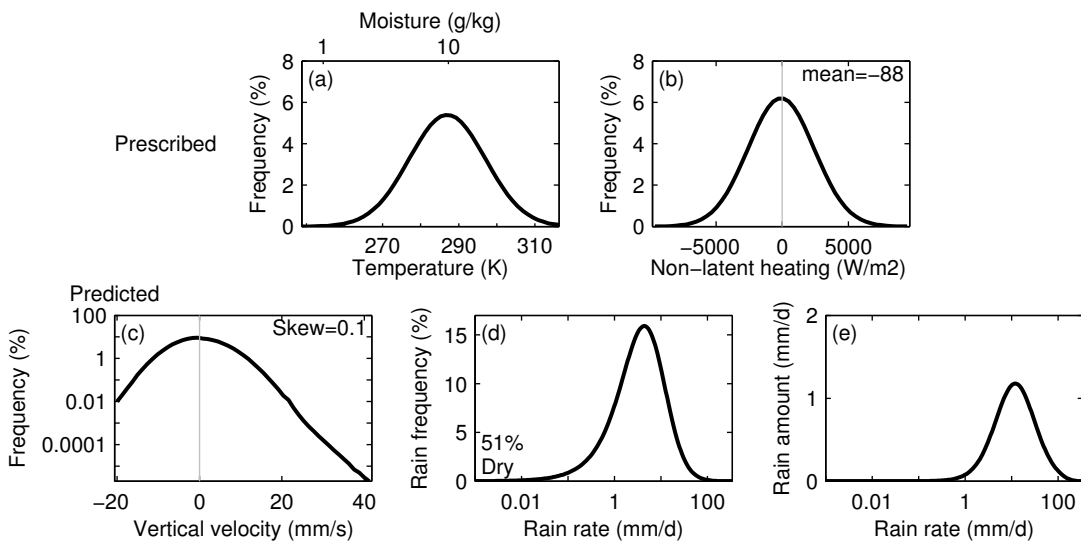
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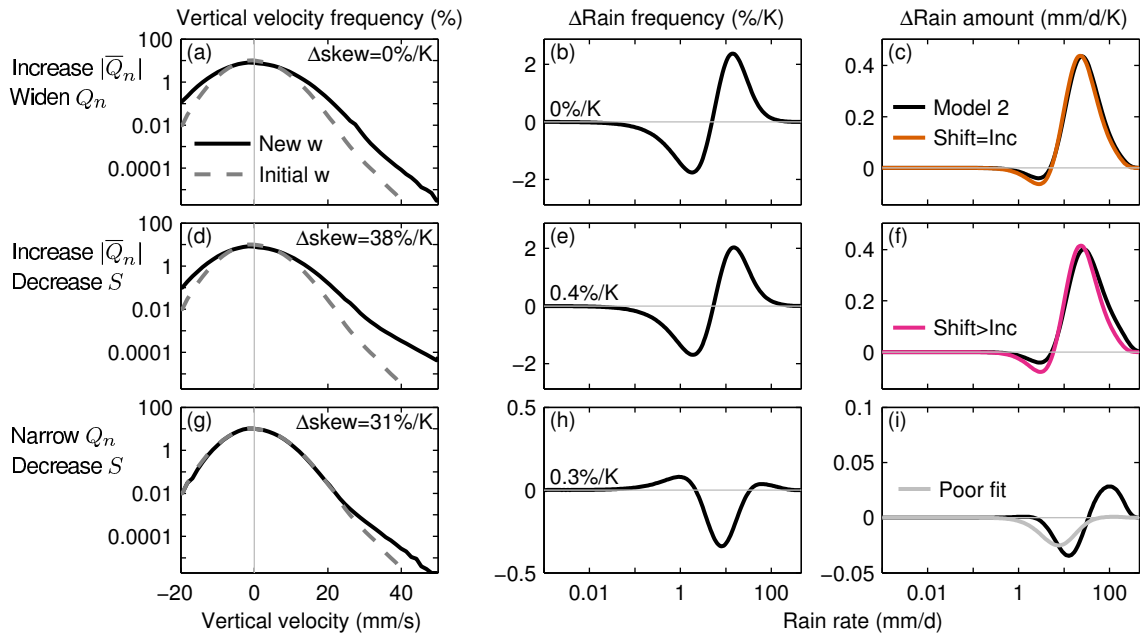
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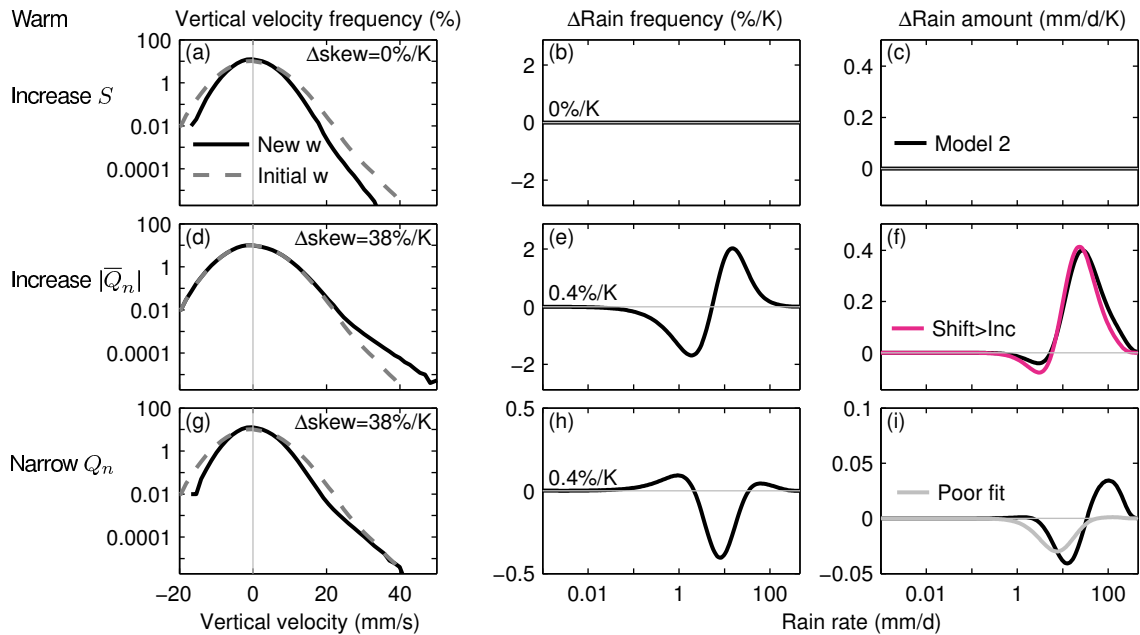
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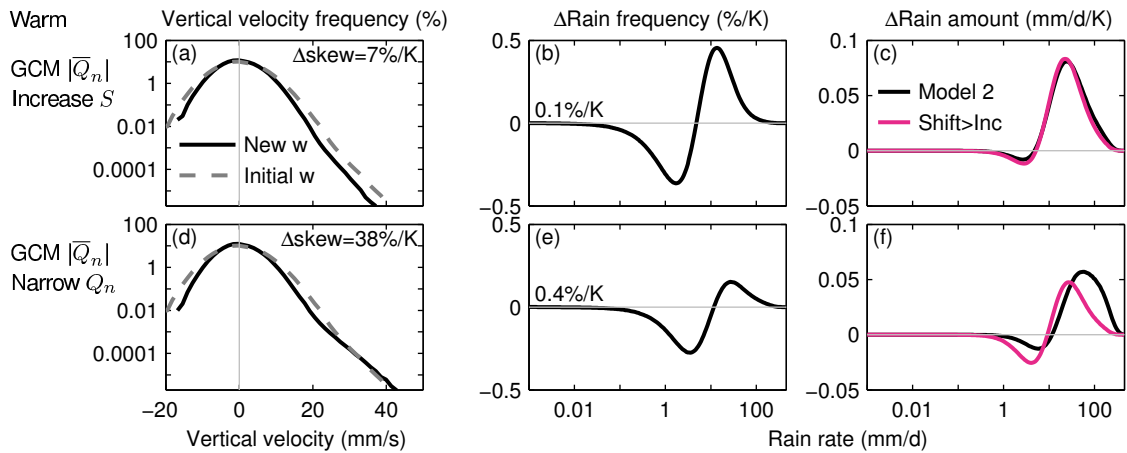
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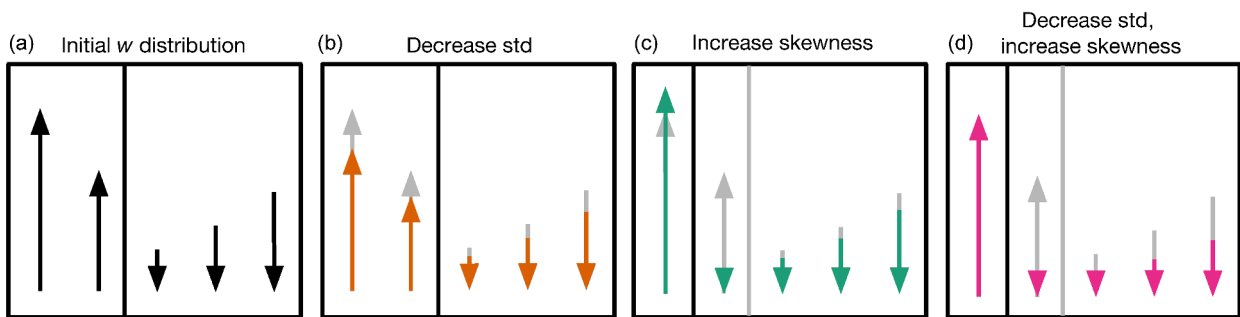
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898 FIG. 7. Experiments warming while varying one other parameter with the second model, following Fig. 6:
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