

PDE Spring 2016

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Review notes for midterm

Important PDEs

① Heat or diffusion eq.

$$u_t = k u_{xx} \quad \text{in } 1D, \quad k > 0$$

$$u_t = k \nabla^2 u \quad \text{in any dimension}$$

② Advection equation

$$u_t + c u_x = 0 \quad \text{in } 1D$$

$$u_t + \vec{c} \cdot \vec{\nabla} u = 0 \quad \text{in any dimension}$$

③ Laplace and Poisson equation:

$$\nabla^2 u = f \quad (\text{Poisson})$$

$$\nabla^2 u = 0 \quad (\text{Laplace})$$

④ Inviscid or Viscous Burgers

$$u_t + u u_x = k u_{xx}$$

IVP = initial value problem
BVP = Boundary value problem

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① Advection equation:

Needs initial conditions and boundary condition on boundaries (in space-time domain) where characteristics go into the domain

② Heat eq:

Needs initial conditions and on all boundaries one of:

Dirichlet BC : $u(0, t) = g(t)$

Neumann BC $u_x(0, t) = h(t)$

Mixed / Robin BC $\alpha(t)u + \beta(t)u_x = f(t)$

In higher dimensions Neumann is

$$\frac{\partial u}{\partial n} = \vec{n} \cdot \vec{\nabla} u = \text{given on boundary}$$

↑
normal vector

③ For Laplace / Poisson same as heat but no initial conditions

A BVP is linear if it has 3
the form:

$$\left. \begin{array}{l} \mathcal{L}u = f(x, t) \leftarrow \text{PDE} \\ \mathcal{B}u = h(x, t) \leftarrow \text{BCs} \end{array} \right\}$$

Linear operator

If $f = h = 0$ — homogeneous eq.

Superposition principle:
Sums and integrals of solutions are solutions, specifically.

① If $\mathcal{L}u = f$ solves the BVP
then if $\mathcal{L}v = 0$ then $u + \alpha v$ also solves the BVP
so does $u + \alpha v$ where α is an arbitrary coefficient

② $\mathcal{L}u = f$ has a unique solution iff
 $\mathcal{L}v = 0 \iff v = 0$

③ If $u(x, t; \eta)$ is a solution, so is
 $\int c(\eta) u(x, t; \eta) d\eta$

A BVP is well-posed if: (4)

- existence
- uniqueness
- stability

Stability means that

$$\begin{cases} \mathcal{L}u = f \\ \mathcal{L}(u + \delta u) = f + \delta f \end{cases} \Rightarrow \|\delta u\| \leq C \|\delta f\|$$

\uparrow
 any norm suitable to the problem

Conservation laws

In 1D:

$$u_t + \psi_x = f \quad \leftarrow \begin{array}{l} \text{strong form} \\ \text{of PDE} \end{array}$$

\uparrow flux \uparrow source

e.g. $\left. \begin{array}{l} \psi = uc \text{ for advection} \\ \psi = -ku_x \text{ for diffusion} \end{array} \right\}$

In higher dimensions

$$u_t + \vec{\nabla} \cdot \vec{\psi} = f$$

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PDE classification for second-order PDEs

$$\mathcal{L}u = a u_{xx} + 2b u_{xy} + c u_{yy} = 0$$

$$d = b^2 - ac$$

The discriminant determines

① $\left\{ \begin{array}{l} d > 0 \text{ hyperbolic} \Rightarrow \\ \mathcal{L} = (\alpha \partial_x + \beta \partial_y)(\gamma \partial_x + \delta \partial_y) \\ \Rightarrow \text{Change (coordinates) so that} \\ \mathcal{L} = \partial_s \partial_t = \partial_{st} \end{array} \right.$

② $\left\{ \begin{array}{l} d = 0 \text{ parabolic} \\ \mathcal{L} = (\alpha \partial_x + \beta \partial_y)^2 \\ \mathcal{L} = \partial_{ss} \end{array} \right.$

③ $\left\{ \begin{array}{l} d < 0 \\ \mathcal{L} \text{ cannot be factored in real factors} \\ \mathcal{L} = \partial_{ss} + \partial_{tt} \end{array} \right.$

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Advection / One-Way Wave Eq.

$$u_t + c u_x = 0 \Rightarrow$$

$$u = f(x - ct)$$

Method of characteristics:

$$p u_x + q u_y = f$$

Track solution along characteristic

$$w = u(x(t), y(t))$$

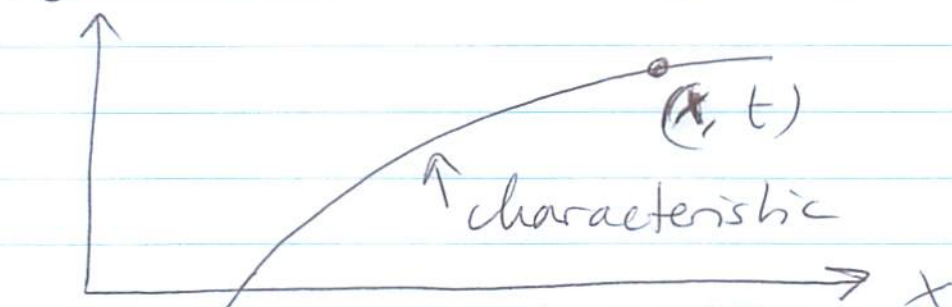
$$\frac{dw}{dt} = \underbrace{\frac{dx}{dt}}_p u_x + \underbrace{\frac{dy}{dt}}_q u_y = f$$

or

$$\frac{dx}{p} = \frac{dy}{q} = \frac{dw}{f}$$

versus

$$\frac{dx}{dt} = p, \quad \frac{dy}{dt} = q, \quad \frac{dw}{dt} = f$$



Solve ODE along characteristic

The Wave Equation
or general hyperbolic eqs

$$\begin{aligned} \mathcal{L} &= a u_{xx} + 2b u_{xy} + c u_{yy} \\ &= (\alpha \partial_x + \beta \partial_y) (\gamma \partial_x + \delta \partial_y) \\ &= \underbrace{\hspace{10em}}_{\partial_s} \underbrace{\hspace{10em}}_{\partial_t} \end{aligned}$$

Find linear transformation

$$\begin{cases} x = d s + \beta t \\ y = \gamma s + \delta t \end{cases}$$

and choose

$$\begin{cases} \partial_s = d \partial_x + \beta \partial_y \\ \partial_t = \gamma \partial_x + \delta \partial_y \end{cases}$$

then solve

$$\partial_{st} u = f(s, t)$$

$$\partial_s (\partial_t u) = f \quad \text{first}$$

$$\partial_t u = \int^s f ds' + A(t)$$

$$u = \int \int^s f ds' dt' + B(t) + C(s)$$

Then use initial and/or boundary conditions to try to figure out $B(t)$ and $C(t)$ (8)

For wave equation $x \in \mathbb{R}$

$$\begin{cases} u_{tt} = c^2 u_{xx} + f(x, t) \\ u(x, 0) = \varphi(x) \\ u_t(x, 0) = \psi(x) \end{cases}$$

D'Alembert's formula
(know how it is derived!)

$$u = \frac{1}{2} [\varphi(x+ct) + \varphi(x-ct)] + \frac{1}{2c} \int_{x-ct}^{x+ct} \psi(s) ds$$

$$\int f \neq 0 \left\{ \begin{aligned} &+ \frac{1}{2c} \int_0^t \int_{x-d(t-\bar{t})}^{x+c(t-\bar{t})} f(s, \bar{t}) ds d\bar{t} \end{aligned} \right.$$

We derived this using d'Alembert but you can also derive it directly from change of variables
→ Try it!

Diffusion Equation

(9)

$$\begin{cases} u_t = k u_{xx} & x \in \mathbb{R} \\ u(x, 0) = \varphi(x) \end{cases}$$

$$\Rightarrow u(x, t) = \int_{-\infty}^{\infty} G(x-y, t) \varphi(y) dy$$

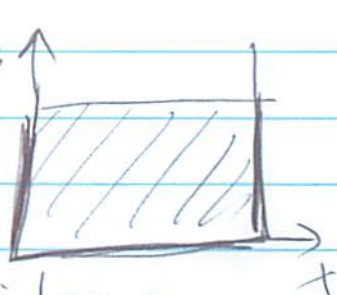
where G is the Green's function, i.e., the solution of

$$\begin{cases} u_t = k u_{xx} \\ u(x, 0) = \delta(x) \end{cases} \quad \text{or} \quad \begin{cases} u_t = \delta(x) \delta(t) \\ u(x, -\infty) = 0 \end{cases}$$

$$G = \frac{1}{\sqrt{4\pi kt}} e^{-x^2/(4kt)}$$

Maximum principle

Extremum is achieved on one of the three sides: initial conditions or boundary



"Energy" $E = \frac{1}{2} \int_{-\ell}^{\ell} u^2 dx$

$$\frac{dE}{dt} < 0 \quad \text{if} \quad u_x \neq 0$$

$$-k \int_{-\ell}^{\ell} (u_x)^2 dx$$

Duhamel's Principle

(10)

$$u(x, t) = \overline{F}_t(\psi(\cdot))(x)$$

$$u(x, t) = \overline{F}_t \psi(x)$$

(linear) solution operator or
forward map

for homogeneous equation

$$\begin{cases} \mathcal{L}u = 0 \\ u(x, 0) = \psi(x) \end{cases}$$

Then the solution of

$$\begin{cases} \mathcal{L}u = f \\ u(x, 0) = \psi(x) \end{cases}$$

is

$$u(x, t) = \overline{F}_t(\psi) + \int_0^t \overline{F}_{t-s} f(x, s) ds$$

Note! This assumes that the equation is time invariant: looks the same at all times.

If PDE depends on time explicitly then $\overline{F}_{t,s}$ and not $t-s$