

Coupling a Fluctuating Fluid with Suspended Particles

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Fluid-Structure Coupling

- We want to construct a **bidirectional coupling** between a fluctuating fluid and a small spherical **Brownian particle (blob)**.
- Macroscopically, the coupling between flow and a rigid sphere relies on:
 - **No-slip** boundary condition at the surface of the Brownian particle.
 - Force on the bead is the integral of the (fluctuating) stress tensor over the surface.
- The above two conditions are **questionable at nanoscales**, but even worse, they are very hard to implement numerically in an efficient and stable manner.
- It is important to point out that **fluctuations should be taken into account at the continuum level**.

Levels of Coarse-Graining

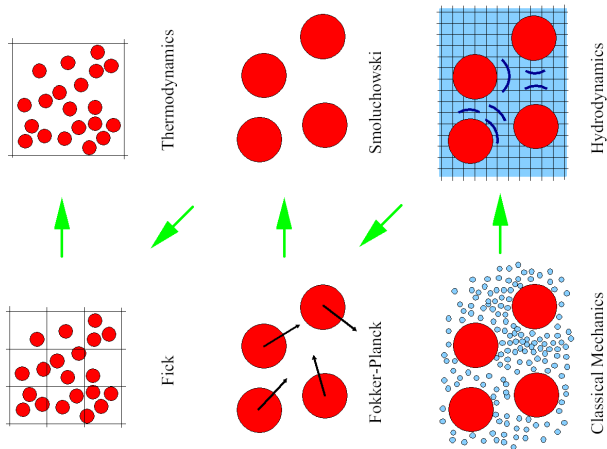


Figure: From Pep Español, “Statistical Mechanics of Coarse-Graining”

Particle/Continuum Hybrid

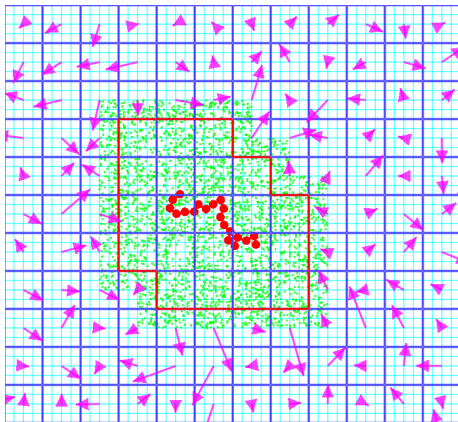


Figure: Hybrid method for a polymer chain.

Particle: Stochastic Collision Dynamics

- The most direct and accurate way to simulate the interaction between the fluid and blob is to use a particle scheme for both, e.g., **Molecular Dynamics** (MD).
- Over longer times it is **hydrodynamics** (local momentum and energy *conservation*) and **fluctuations** (*Brownian motion*) that matter.
- Coarse grain fluid: **Markov Chain Monte Carlo** instead of MD.
- *Replace deterministic interactions with conservative stochastic pairwise collisions between nearby fluid particles* [1] (based on DSMC, also related to MPCD/SRD and DPD).
- Fluid particles interact with blobs either via deterministic (hard-sphere) or stochastic (MCMC) collisions.

Continuum: Fluctuating Hydrodynamics

$$D_t \rho = -\rho \nabla \cdot \mathbf{v}$$

$$\rho (D_t \mathbf{v}) = -\nabla P + \nabla \cdot (\eta \overline{\nabla \mathbf{v}} + \boldsymbol{\Sigma})$$

$$\rho c_p (D_t T) = D_t P + \nabla \cdot (\mu \nabla T + \boldsymbol{\Xi}) + (\eta \overline{\nabla \mathbf{v}} + \boldsymbol{\Sigma}) : \nabla \mathbf{v},$$

where the variables are the **density** ρ , **velocity** \mathbf{v} , and **temperature** T fields,

$$D_t \square = \partial_t \square + \mathbf{v} \cdot \nabla (\square)$$

$$\overline{\nabla \mathbf{v}} = (\nabla \mathbf{v} + \nabla \mathbf{v}^T) - 2(\nabla \cdot \mathbf{v}) \mathbf{I}/3$$

and capital Greek letters denote stochastic fluxes:

$$\boldsymbol{\Sigma} = \sqrt{2\eta k_B T} \mathcal{W}.$$

$$\langle \mathcal{W}_{ij}(\mathbf{r}, t) \mathcal{W}_{kl}^*(\mathbf{r}', t') \rangle = (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk} - 2\delta_{ij} \delta_{kl}/3) \delta(t - t') \delta(\mathbf{r} - \mathbf{r}').$$

Incompressible Fluctuating Navier-Stokes

- Ignoring density and temperature fluctuations, we obtain the **incompressible approximation**:

$$\begin{aligned}\rho D_t \mathbf{v} &= \eta \nabla^2 \mathbf{v} - \nabla \pi + \sqrt{2\eta k_B T} (\nabla \cdot \mathcal{W}), \\ \nabla \cdot \mathbf{v} &= 0\end{aligned}$$

where the stochastic stress tensor \mathcal{W} is a white-noise random Gaussian tensor field with covariance

$$\langle \mathcal{W}_{ij}(\mathbf{r}, t) \mathcal{W}_{kl}^*(\mathbf{r}', t') \rangle = (\delta_{ik} \delta_{jl}) \delta(t - t') \delta(\mathbf{r} - \mathbf{r}').$$

- We have developed **numerical schemes** to solve the compressible and incompressible fluctuating equations for simple fluids and miscible binary mixtures on **collocated** [2] and **staggered grids** [3].
- Solving them numerically requires paying attention to **discrete fluctuation-dissipation balance**, in addition to the usual deterministic difficulties.

Fluid-Structure Coupling using Particles

- Split the domain into a **particle** and a **continuum (hydro) subdomains**, with timesteps $\Delta t_H = K \Delta t_P$.
- Hydro solver is a simple explicit **(fluctuating) compressible** code and is *not aware* of particle patch.
- The method is based on Adaptive Mesh and Algorithm Refinement (AMAR) methodology for conservation laws and ensures **strict conservation** of mass, momentum, *and* energy.

MNG

Continuum-Particle Coupling

- Each macro (hydro) cell is either **particle or continuum**. There is also a **reservoir region** surrounding the particle subdomain.
- The coupling is roughly of the **state-flux** form:
 - The continuum solver provides *state boundary conditions* for the particle subdomain via reservoir particles.
 - The particle subdomain provides *flux boundary conditions* for the continuum subdomain.
- The fluctuating hydro solver is **oblivious** to the particle region: Any conservative explicit finite-volume scheme can trivially be substituted.
- The coupling is greatly simplified because the ideal **particle fluid has no internal structure**.

"A hybrid particle-continuum method for hydrodynamics of complex fluids", A. Donev and J. B. Bell and A. L. Garcia and B. J. Alder, **SIAM J. Multiscale Modeling and Simulation** 8(3):871-911, 2010

Our Hybrid Algorithm

- 1 The hydro solution \mathbf{u}_H is computed everywhere, including the **particle patch**, giving an estimated total flux Φ_H .
- 2 **Reservoir particles** are *inserted* at the boundary of the particle patch based on *Chapman-Enskog distribution* from kinetic theory, accounting for *both* collisional and kinetic viscosities.
- 3 Reservoir particles are *propagated* by Δt and *collisions* are processed, giving the total particle flux Φ_p .
- 4 The hydro solution is overwritten in the particle patch based on the particle state \mathbf{u}_p .
- 5 The hydro solution is corrected based on the more accurate flux,
$$\mathbf{u}_H \leftarrow \mathbf{u}_H - \Phi_H + \Phi_p.$$

Velocity Autocorrelation Function

- We investigate the **velocity autocorrelation function** (VACF) for a Brownian bead

$$C(t) = \langle \mathbf{v}(t_0) \cdot \mathbf{v}(t_0 + t) \rangle$$

- From equipartition theorem $C(0) = kT/m$.
- For a Brownian particle with density ρ' incompressible hydrodynamic theory gives

$$C(0^+) = \left(1 + \frac{\rho}{2\rho'}\right)^{-1} \frac{kT}{m}$$

because the momentum correlations decay instantly due to sound waves.

- Hydrodynamic persistence (conservation) gives a **long-time power-law tail** $C(t) \sim (kT/m)(t/t_{\text{visc}})^{-3/2}$ *not* reproduced in Brownian dynamics.

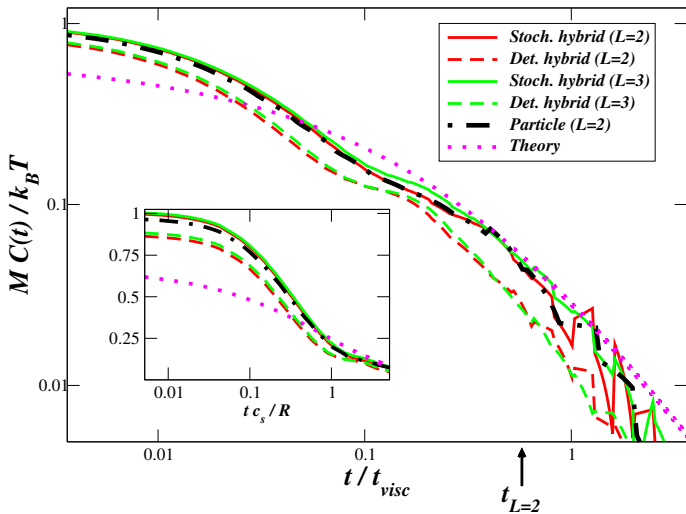
Large Bead (~ 1000 particles)

Figure: VACF for a neutrally-buoyant spherical Brownian particle.

Fluid-Structure Coupling

- Consider a blob (Brownian particle) of size a with position $\mathbf{q}(t)$ and velocity $\mathbf{u} = \dot{\mathbf{q}}$, and the velocity field for the fluid is $\mathbf{v}(\mathbf{r}, t)$.
- We do not care about the fine details of the flow around a particle, which is nothing like a hard sphere with stick boundaries in reality anyway.
- Take an **Immersed Boundary Method** (IBM) approach and describe the fluid-blob interaction using a localized smooth **kernel** $\delta_a(\Delta\mathbf{r})$ with compact support of size a (integrates to unity).
- Often presented as an interpolation function for point Lagrangian particles but here a is a **physical size** of the blob.
- See Florencio Balboa's talk and paper [4].

Local Averaging and Spreading Operators

- Postulate a **no-slip condition** between the particle and local fluid velocities,

$$\dot{\mathbf{q}} = \mathbf{u} = [\mathbf{J}(\mathbf{q})] \mathbf{v} = \int \delta_a(\mathbf{q} - \mathbf{r}) \mathbf{v}(\mathbf{r}, t) d\mathbf{r},$$

enforced by a Lagrange multiplier fluid-blob force λ .

- The **induced force density** in the fluid because of the particle is:

$$\mathbf{f} = -\lambda \delta_a(\mathbf{q} - \mathbf{r}) = -[\mathbf{S}(\mathbf{q})] \lambda,$$

which ensures **momentum conservation**.

- Crucial for **energy conservation** is that the *local averaging operator* $\mathbf{J}(\mathbf{q})$ and the *local spreading operator* $\mathbf{S}(\mathbf{q})$ are **adjoint**, $\mathbf{S} = \mathbf{J}^*$.
- I will **ignore the nonlinear advective terms** and simply denote them with ellipses ...

Fluid-Structure Direct Coupling

- The equations of motion in our coupling approach are *postulated*

$$\begin{aligned}\rho (\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v}) &= -\nabla \cdot \boldsymbol{\sigma} - \mathbf{S} \boldsymbol{\lambda} \\ m_e \dot{\mathbf{u}} &= \mathbf{F} + \boldsymbol{\lambda} \\ \text{s.t. } \mathbf{u} &= \mathbf{J} \mathbf{v},\end{aligned}$$

where $\boldsymbol{\lambda}$ is a Lagrange multiplier that enforces the **no-slip condition** and m_e is the **excess mass** of the particle.

- The **fluid fluctuations** drive the Brownian motion: no stochastic forcing of the particle motion.
- In the existing (stochastic) IBM approaches **inertial effects** are ignored, $m_e = 0$ and thus $\boldsymbol{\lambda} = -\mathbf{F}$.
- In Lattice-Boltzmann approaches [5] a frictional (dissipative) force $\boldsymbol{\lambda} = -\zeta (\mathbf{u} - \mathbf{J} \mathbf{v})$ is used instead of a constraint.

Effective Inertia

- Eliminating λ we get the particle equation of motion

$$m\dot{\mathbf{u}} = -\Delta V (\mathbf{J}\nabla \cdot \boldsymbol{\sigma}) + \mathbf{F} + \dots ,$$

where the **effective mass** $m = m_e + m_f$ includes the mass of the “excluded” fluid

$$m_f = \rho (\mathbf{J}\mathbf{S})^{-1} = \rho \Delta V = \rho \left[\int \delta_a^2(\mathbf{r}) d\mathbf{r} \right]^{-1} .$$

- For the fluid we get the effective equation

$$\rho_{\text{eff}} \partial_t \mathbf{v} = -\nabla \cdot \boldsymbol{\sigma} + \mathbf{S}\mathbf{F} + \dots$$

where the effective **mass density matrix** (operator) is

$$\rho_{\text{eff}} = \rho \mathbf{l} + m_e \mathbf{S}\mathbf{J} .$$

Fluctuation-Dissipation Balance

- One must ensure fluctuation-dissipation balance in the coupled fluid-particle system. This is work in progress...
- This really means that the **stationary** (equilibrium) distribution must be the **Gibbs distribution**

$$P(\mathbf{x}) = Z^{-1} \exp[-\beta H]$$

where the **Hamiltonian** is postulated to be

$$H = U(\mathbf{q}) + m_e \frac{u^2}{2} + \int \left[\rho \frac{v^2}{2} + \epsilon(\rho) \right] dr.$$

- We can eliminate the particle velocity using the no-slip constraint, to obtain the **effective Hamiltonian**

$$H = U(\mathbf{q}) + \int \frac{\mathbf{v}^T \rho_{\text{eff}} \mathbf{v}}{2} dr + \int \epsilon(\rho) dr.$$

- The equations as written do not formally satisfy fluctuation-dissipation balance as the dynamics is **not incompressible in phase space**.

Brownian Dynamics Limit

- For the case of a neutrally-bouyant particle, $m_e = 0$, fluctuation-dissipation balance is restored if one adds an extra drift term to the fluid dynamics:

$$\rho \partial_t \mathbf{v} = -\nabla \cdot \boldsymbol{\sigma} + \mathbf{S}\mathbf{F} + (k_B T) \frac{\partial}{\partial \mathbf{q}} \cdot \mathbf{S}.$$

- Paul Atzberger [6] has obtained these equations by carefully taking the limit $m_e \rightarrow 0$ and *then* **infinite friction** of the Stokes dissipative fluid-particle coupling [5].
- In the overdamped or Brownian dynamics limit

$$\dot{\mathbf{q}} = \mathbf{M}\mathbf{F} + \sqrt{2k_B T} \mathbf{M}^{1/2} \widetilde{\mathcal{W}} + \left(\frac{\partial}{\partial \mathbf{q}} \cdot \mathbf{M} \right) k_B T,$$

where the **mobility tensor** is related to the Stokes solution operator \mathcal{L}^{-1} :

$$\mathbf{M}(\mathbf{q}) = -\mathbf{J}\mathcal{L}^{-1}\mathbf{S}.$$

Incompressible Approximation

- For an incompressible fluid the fluid forcing must be projected using the **projection operator** \mathcal{P} , in Fourier space $\hat{\mathcal{P}} = \mathbf{I} - k^{-2} (\mathbf{k}\mathbf{k}^T)$.
- Now the effective density matrix for the fluid is

$$\rho_{\text{eff}} = \rho + m_e \mathcal{P} \mathbf{S} \mathbf{J} \mathcal{P}.$$

- The modified Gibbs distribution gives a kinetic energy of the particle that is **less than equipartition** suggests,

$$\langle u^2 \rangle = \left[1 + \frac{m_f}{(d-1)m} \right]^{-1} \left(d \frac{k_B T}{m} \right),$$

as predicted also for a rigid sphere a long time ago, $m_f/m = \rho'/\rho$.

- Incompressible hydro is much harder for non-periodic systems due to additional splitting of pressure terms.

Numerical Scheme

- Spatial discretization is based on previously-developed **staggered schemes** for fluctuating hydro [3] and the **IBM kernel functions** of Charles Peskin [7].
- Temporal discretization follows a first-order **splitting algorithm** (move particle + update momenta) based on the **Direct Forcing Method** of Uhlmann [8].
- The scheme ensures **strict conservation** of momentum and strictly enforces the no-slip condition using a projection step at the end of the time step.
- Continuing work on **second-order** temporal integrators that reproduce the correct **equilibrium distribution** and **diffusive dynamics**.
- Both compressible (explicit) and incompressible (semi-implicit) methods are work in progress...

Numerical VACF

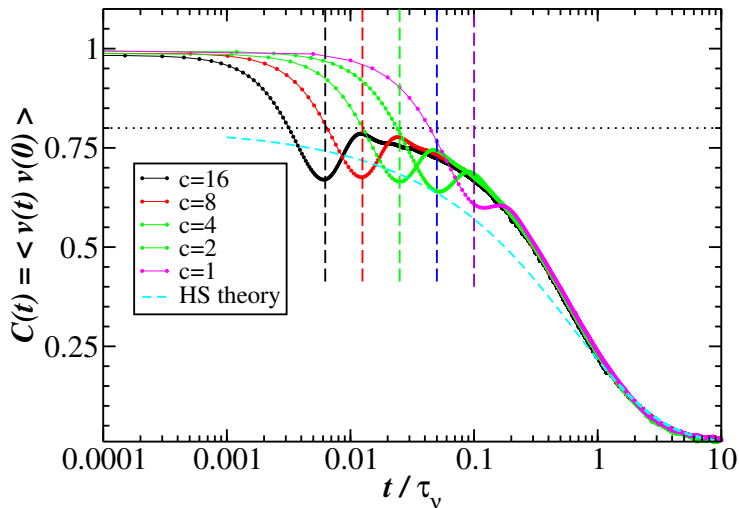


Figure: (F. Balboa) VACF for a blob with $m_e = m_f = \rho\Delta V$.

Conclusions / Discussion

- **Coarse-grained particle methods** can be used to accelerate hydrodynamic calculations at small scales.
- **Hybrid particle continuum methods** closely reproduce purely particle simulations at a fraction of the cost.
- It is **necessary to include fluctuations** in the continuum solver in hybrid methods.
- **Direct fluid-structure coupling** between fluctuating hydrodynamics and microstructure can replace expensive particle methods and complicated hybrid algorithms.
- Ensuring **fluctuation-dissipation balance** is crucial and nontrivial:
How to do it when $m_e \neq 0$?
- Can one derive the proper set of fluid-blob equations, or at least their structure, via **coarse graining** (work with Pep Espanol)?

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